## CXE/AVC MODBUS

## Universal control module

## Operating Instructions



Keep for reference!

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## 1 General notes

### 1.1 Structure of the operating instructions

## Before installation and start-up, read this manual carefully to ensure correct use! We emphasize that these operating instructions apply to specific units only, and are in no way valid for the complete system!

Use these operating instructions to work safely with and on the device. They contain safety instructions that must be complied with as well as information that is required for failure-free operation of the device.
Keep these operating instructions together with the device. It must be ensured that all persons that are to work on the device can refer to the operating instructions at any time.
Keep the operating instructions for continued use. They must be passed-on to all successive owners, users and final customers.

### 1.2 Target group

The operating instructions address persons entrusted with planning, installation, commissioning and maintenance and servicing and who have the corresponding qualifications and skills for their job.

### 1.3 Exclusion of liability

Concurrence between the contents of these operating instructions and the described hardware and software in the device has been examined. It is still possible that non-compliances exist; no guarantee is assumed for complete conformity. To allow for future developments, construction methods and technical data given are subject to alteration. We do not accept any liability for possible errors or omissions in the information contained in data, illustrations or drawings provided.
We accept no liability for damage caused by misuse, incorrect use, improper use or as a consequence of unauthorized repairs or modifications.

### 1.4 Copyright

These operating instructions contain copyright protected information. The operating instructions may be neither completely nor partially photocopied, reproduced, translated or put on data medium without previous explicit consent. Infringements are liable for damages. All rights reserved, including those that arise through patent issue or registration on a utility model.

## 2 Safety instructions

This chapter contains instructions to prevent personal injury and property damage. These instructions do not lay claim to completeness. In case of questions and problems, please consult our company technicians.

### 2.1 Intended use

The equipment is to be used solely for the purposes specified and confirmed in the order.
Any other use above and beyond this is considered not for the intended purpose unless agreed otherwise by contract. The manufacturer will not be liable for any damage resulting from this. The individual or company using it bears the sole risk.
Reading these operating instructions and complying with all contained instructions - especially the safety notifications contained therein - are considered part of intended use. To consider is also the manual of attached components. Not the manufacturer, rather the operator of the device is liable for any personal harm or material damage arising from non-intended use!

### 2.2 Explanations of symbols

Safety instructions are highlighted with warning triangles and are depicted according to the degree of hazard as follows.

|  | Attention! <br> General hazardous area. Death or severe injury or significant property damage can occur if the <br> corresponding precautions are not taken! |
| :--- | :--- |

### 2.3 Product safety

The device conforms to the state of the art at the time of delivery and is fundamentally considered to be reliable. The device and its accessories must only be used in a flawless condition and installed and operated in compliance with the assembly instructions and/or operating instructions. Operating outside the device's technical specifications ( name plate and attachment / technical data) can lead to a defect in the device and additional damage!
In the case of a malfunction or a failure of the equipment check all functions with alarms in order to prevent injury to persons or property. Note possibility of back-up operation. If used in intensive animal environments, any malfunctions in the air supply must be detected as soon as possible to prevent the development of a life-threatening situation for the animals. The design and installation of the system must comply with local regulations and directives. In Germany these include DIN VDE 0100, the animal protection and the keeping of working animals ordinance and the pig-keeping ordinance etc. Also note the instructions of AEL, DLG, VdS.

### 2.4 Requirements placed on the personnel / due diligence

Persons entrusted with the planning, installation, commissioning and maintenance and servicing in connection with the frequency inverter must have the corresponding qualifications and skills for these jobs.
In addition, they must be knowledgeable about the safety regulations, EU directives, rules for the prevention of accidents and the corresponding national as well as regional and in-house regulations. Personnel to be trained or instructed and apprentices are only permitted to work on the device under the supervision of an experienced person. This also applies to personnel undergoing general training. Comply with the legal minimum age.

### 2.5 Start-up and during operation



## Attention!

- During commissioning, unexpected and hazardous conditions can arise in the entire installation due to defective adjustments, defective components or incorrect electrical connections. Remove all persons and objects from the hazardous area.
- During operation, the device must be closed or installed in a control cabinet. Fuses may only be replaced by new ones and must not be repaired or bypassed. The data for the maximum line fuse are to be considered absolutely ( Technical data). Use only fuses specified in schematic diagrams.
- Any faults detected in the electric system/modules/operating equipment must be corrected immediately. If these faults are not corrected, the device/system is potentially very dangerous. The device/system must therefore not be operated when it is faulty.
- Pay attention to smooth, low vibration running of the motor/fan, the appropriate instructions in the drive documentation must be observed!


### 2.6 Work on the device

## Information

Mounting, electrical connection, and start-up operation may only be carried out by an electrical specialist in accordance with electrotechnical regulations (e.g. EN 50110 or EN 60204)!

## Danger due to electric current

It is generally forbidden to carry out work on electrical live parts. Protection class of the device when open is IP00! It is possible to touch hazardous voltages directly.
The safe isolation from the supply must be checked using a two-pole voltage detector.


## Attention!

Automatically restart after a power failure or mains disconnection!

### 2.7 Modifications / interventions in the device

## Attention!

For reasons of safety, no unauthorized interventions or modifications may be made on the device. All planned modifications must be authorized by the manufacturer in writing.

Only use the manufacturer's original spare parts / wearing parts / accessories. These parts are specially designed for this device. If parts from other sources are used, there is no guarantee that they are designed and produced for the proper loads and with the required level of safety.
Parts and special equipment not supplied by the manufacturer are not approved for use.

### 2.8 Operator's obligation of diligence

- The contractor or owner must also ensure that the electric systems and equipment are operated and maintained in accordance with electro-technical regulations.
- The owner is obliged to ensure that the device is operated in perfect working order only.
- The device may only be used as intended (area of application").
- You must periodically examine the safety equipment for their properly functioning condition.
- The assembly instructions and/or operating instructions are always readily available at the location where the device is being used, are complete and are in legible condition.
- These persons are regularly instructed in all applicable questions regarding occupational safety and environmental protection and are knowledgeable regarding the assembly instructions and/or operating instructions and, especially, are familiar with the safety instructions contained therein.
- All safety and warning notices attached to the device are never removed and remain legible.


### 2.9 Employment of external personnel

Maintenance and service work are frequently carried out by external employees who often do not recognize the specific situations and the thus resulting dangers. These persons must be comprehensively informed about the hazards in their area of activity.
You must monitor their working methods in order to intervene in good time if necessary.

## 3 Product overview

### 3.1 Operational area

The purpose of the device is to reach and maintain the target values set. To accomplish this, the measured actual value (sensor value) is compared with the adjusted target value, and the controlled value is deduced from this.
The device has two separate control circuits and two sensor inputs (0-10 V, 4-20 mA, KTY 81-210, PT 1000).
Speed controllers for fans or fans with an integrated controller can be activated via the $0-10 \mathrm{~V}$ signal or the parallel option of the MODBUS Master interface.

### 3.2 Maintenance

The device must be checked for soiling and, if necessary, cleaned in periodic intervals.

### 3.3 Transport

- The device is packed ex factory to suit the transport method previously agreed.
- Always use the original packaging materials when transporting the device.
- Avoid shocks and impacts to the device during the transport.
- During manual handling the human lifting and carrying restrictions must be observed and adhered to.


### 3.4 Storage

- The device must be stored in its original packaging in a dry and weather-proof room.
- Avoid exposure to extreme heat and cold.
- Avoid over-long storage periods (we recommend a maximum of one year).


### 3.5 Disposal / recycling

Disposal must be carried out professionally and in an environmentally friendly way in accordance with the respective national legal stipulations.
$\triangleright$ Separate the materials by type and in an environmentally friendly way.
$\Delta$ If necessary, commission a specialist company with the waste disposal.

## 4 Mounting

### 4.1 General notes

## Attention!

The following points must be complied with during the mechanical installation to avoid causing a defect in the device due to assembly errors or environmental influences:

- Before installation remove the device from the packing and check for any possible shipping damage!
- Assemble the device on a clean and stable base. Do not distort during assembly! Use the appropriate mounting devices for proper installation of the unit!
- Do not mount equipment on vibrating base!
- When mounted onto lightweight walls, there must be no impermissibly high vibrations or shock loads. Any banging shut of doors that are integrated into these lightweight walls, can result in extremely high shock loads. Therefore, we advise you to decouple the devices from the wall.
- Do not allow drilling chips, screws and other foreign bodies to reach the device interior!
- The device should be installed in a location where it will not be disturbed, but at the same time can be easily accessed!
- Depending on the housing model use supplied stoppers for cable inlets, cut off necessary cable inlets respectively to the cable diameter. Or alternative use cable inlet for cable glands. Any cable ducts openings not used must be sealed!
- Care must be taken to avoid direct radiation from the sun!
- The device is designed for vertical installation (cable inlet down). A horizontal or reclined installation is only permissible after technical release of the manufacturer!
- Be sure to observe proper heat dissipation ( Technical data, heat dissipation).


### 4.2 Outdoor installation

Outdoor installation is possible up to $-20^{\circ} \mathrm{C}$ when the controller supply is not switched off. Installation must be protected from the effects of weather as much as possible, including protection from direct sunlight!

### 4.3 Installation location for agriculture

When using for animal keeping, do not install the device directly in the stable but in a separate room with a lower pollutant load. This helps to avoid damages caused by pollutant gases (e.g. ammonia fumes, hydrogen sulphide fumes).

### 4.4 Temperature influences during commissioning

Avoid condensation in the controller and functional faults attributable to condensation by storing the controller at room temperature!

## 5 Electrical installation

### 5.1 Safety precautions

## Danger due to electric current

- Work on electric components may only be carried out by trained electricians or by persons instructed in electricity under the supervision of an electrician in accordance with electrical engineering regulations.
- The 5 electrical safety rules must be observed!
- It is forbidden to carry out work on electrically live parts.
- Other measures may be necessary to achieve safe electrical isolation.
- A second person must always be present when working on energized parts or lines who disconnects in case of emergency.
- Inspect electrical equipment periodically: retighten loose connections - immediately replace damaged lines and cables.
- Always keep switch cabinets and all electrical supply facilities locked. Access is only allowed for authorized persons using a key or special tool.
- Operating the device with the housing cover removed is prohibited because energized, exposed parts are present inside the device. Disregarding this regulation can lead to severe personal injury.
- The required protective earth connection is established using screws between the housing parts in metal terminal space covers and housing casings. Commissioning is only permissible after these screws have been properly attached!
- The device owner is responsible for the EMC of the entire plant according to the locally applicable standards.
- Metal screwed-connections are not permitted in plastic housing parts because there is no potential equalization.
- Never clean electrical equipment with water or similar liquids.


## Information

The respective connections are represented in the enclosure of this manual (Connection diagram)!

### 5.2 EMC-compatible installation of control lines

Pay attention to sufficient distance from powerlines and motor wires to prevent interferences. The control cable may not be longer than 30 m . Screened control cables must be used when the cable length is longer than 20 m . When using a shielded cable connect the shielding to one side only, i.e. only to the control unit with the protective ground (keep cable short and with as little inductance as possible!).

### 5.3 Mains connection

Power from the mains is connected to terminals: PE, L1 and N. Here, it must be strictly observed that the mains voltage lies within the allowable tolerance specifications ( Technical data and nameplate affixed to the side).

## Danger due to electric current

The mains voltage must comply with the DIN EN 50160 quality characteristics and the defined standard voltages in IEC 60038!

### 5.4 Signal input or sensor connection (E1, E2)

The unit has two analog inputs: Analog In $1=$ "E1" and Analog $\ln 2=$ "E2"
The connection is independent of the programmed operating mode and from the sensor signal employed.

- When connecting passive temperature sensorsTF.. (KTY81-210) or PT1000 at terminals "E1" and "T" or "E2" und "T" must be paid attention to no polarity.
For a high interference immunity a capacitor must be connected directly to the sensor ( 1 nF parallel). With temperature sensors type TF.. (KTY81-210) a capacitor is integrated.
- When connecting aktive sensors at the terminals "E1" and "GND" or "E2" and "GND" attention must be paid to correct polarity, a 24 V DC power supply is integrated.
- For sensors in two-wire-technology ( $4-20 \mathrm{~mA}$ signal), the connection is made on the "E1" and " 24 V " or "E2" and " 24 V ", "GND" terminal is omitted.


## Danger due to electric current

Never apply line voltage to analog inputs!

### 5.5 Control outputs 0-10 V (A1, A2)

The analogue outputs can be used to activate a speed controller with 0-10 V input for example. Fans with integrated controller and $0-10 \mathrm{~V}$ input can be activated directly.

- Analog output 1 (terminals A1-GND)
- Controlled 0-10 V output for control circuit 1 (factory setting function 2A).
- Analog output 2 (terminals A2-GND)
- For operation with one control circuit: constant voltage +10 V e.g. for supply of an external potentiometer (function factory setting 1 A ).
- For operation with a second control circuit: controlled 0-10 V output for control circuit 2 (function initial setting 8A).

Other functions can be assigned if necessary (Operating Instructions / IO Setup).


Danger due to electric current
It is not permissible to connect outputs of several devices to each other!

### 5.6 Voltage supply for external devices (+24V, GND)

A voltage supply is integrated for external devices e.g. a sensor (max. current load technical data). In case of overload or short circuit ( $24 \mathrm{~V}-\mathrm{GND}$ ), the external power supply is shut down (multi-fuse). The device performs a "Reset" and continues operation.

- It is not permissible to connect voltage outputs of several devices to each other!
- It is not permissible to connect voltage outputs in the device to each other!


### 5.7 Digital inputs (D1, D2)

Various functions can be allocated to the digital inputs "D1" and "D2" ( 10 Setup: Functions summary of the digital inputs). Activation via floating contacts (a low voltage of ca. $24 \mathrm{~V} D C$ is connected).

## Danger due to electric current

Never apply line voltage to the digital input!
Observe input resistance and voltage range (Technical data).

### 5.8 Relay outputs (K1, K2)

Various functions can be allocated to the relay outputs "K1" and "K2" ( 10 Setup: function and inverting relais outputs). Max. contact rating technical data and connection diagram.

## Relays K1

- Connection of the floating contacts of relay "K1" to the terminals $11,14,12$.
- "K1 Function" factory setting: 1 K = Operating indication. I.e. energized for operation without fault, for enable "OFF" de-energized.


## Relays K2

- Connection of the floating contacts of relay "K2" to the terminals $21,24,22$.
- "K2 Function" factory setting: 2 K = Fault indication. l.e. energized for operation without fault and for enable "OFF".


### 5.9 RS-485 interfaces for MODBUS RTU

The device has two RS-485 interfaces for networking via MODBUS RTU:

1. Interface "1A (1D+)", "1B (1D-)" for MODBUS Master applications

- Pre-programmed function is output from control circuit 1: 1. Control signal (2A) e.g. for activating speed controllers for fans or fans with integrated controller and MODBUS interface ( member MODBUS Master).
The programmable functions correspond to the functions for the analogue outputs described in the IO Setup.
- Automatic addressing of members via a patented procedure.

It is no longer necessary to address each individual member manually in the network. The "ID" connection is also assigned (for more information the following chapter). .

- Integrated failsafe wiring and $150 \Omega$ termination.

2. Interface "2A (2D+)", "2B (2D-)" for MODBUS Slave applications

- Connection of the device to a superordinate building control system.
- Setting of address and communication parameters Programming: Menu group MODBUS Slave.


Connection MODBUS Slave and MODBUS Master interface
When using telephone flex with four cable cores, we recommend the following allocation:

- $A(D+)=$ red
- $B(D-)=$ black
- ID - ID1/2 = yellow (for automatic addressing for MODBUS Master)
- GND = white


## Information

- You must ensure correct connection; i.e. "A (D+)" must also be connected on the following devices to "A (D+)". The same applies to "A (D+)".
- Inaddition,a "GND" connection must be established, as dissimilar potential (over 10 V !) will lead to the destruction of the RS-485 interface (e.g. lightning).
- Except for the data link "A (D+)", "B (D-)", the "ID1 - ID2" (automatic addressing for MODBUS Master) and the "GND" connection, no further cable cores of the data line may be used.
- Do not use wire shield!
- Pay attention to sufficient distance from powerlines and motor wires (min. 20 cm ).

The data line must be connected from one device to the next. No other type of wiring is allowed! Always use only two wires of one lead (twisted pair) for the connection.
MODBUS connection

## Recommended wire types



1. CAT5 / CAT7 cables
2. J-Y (St) $2 \times 2 \times 0.6$ (telephone wire)
3. AWG22 ( $2 \times 2$ twisted pair)

Max. allowed wire length 1000 m (CAT5/7 500 m)

## Information

If any matters are unclear, please contact our V-STE support department for control systems ventilation technology. The information sheet "Network structure of MODBUS" R-TIL08_01 contains detailed information about "MODBUS".

### 5.9.1 Addressing member MODBUS Master Interface

Up to 32 members can be connected at the MODBUS Master interface.
No other components are required for the patented automatic addressing (activation menu group MODBUS Master: AutoAddressing). Only the connections "ID1" and "ID2" of the Slave members are connected additionally next to the bus connection and at the "ID" connection of the MODBUS Master for this.
The "ID" connection of the MODBUS Master must be connected to the "ID1" or "ID2" connection of the first Slave member. This is recognised as a result and occupied by address 1.
For the following users the connection "ID1" or "ID2" of a Slave user respectively is connected with connection "ID1" or "ID2" of the next Slave user.
The automatic addressing of other users is initiated by the previous user via this connection.
The individual members can be addressed in advance without this device by an external terminal or a PC.

Alternatively, the addressing can be done manually by a separate hand held terminal or PC software, the appropriate number of members must then be entered on the MODBUS Master (cs menu group MODBUS Master: BUS Slavecount).

## Information

- When using the automatic addressing, no repeaters can be used because these do not pass the signal through to the addressing.
- Depending on the version, the connections for MODBUS "A (D+)", "B (D-)" are available single or double at the Slave members. These are connected with each other internally electrically.
- The connections for the automatic addressing "ID1" and "ID2" are not directly connected with each other internally. These may not be bridged; any order of connection is possible.
- Do not connect the cable screen! When using the connection box, the cable screen of the CAT5 cable is connected internally by an RC element to "PE".
- The communication parameters are fixed Programming: Menu group MODBUS Master.

Networking with telephone wire


The connection at the terminal is made at the terminals: 1A (1D+), 1B (1D-) and GND
Connection of the users via the terminals: A ( $\mathrm{D}+$ ), $\mathrm{B}(\mathrm{D}-), \mathrm{GND}$ and ID1/ID2

Networking with RJ45 patch cable by usage connection box for ECblue (part. no. 380085).


Connection to the MODBUS Master at the terminals: 1A (1D+), 1B (1D-), ID and GND
Connection of the Slave members via the two RJ45 connections "BUS1" and "BUS2"

### 5.10 USB-interface

Over the USB interface if necessary a software update can be made. For this a consultation with the manufacturer is necessary.

## Danger due to electric current

Plug the jumper J1 to both PINs only for a software update via USB interface. The device will not switch on if this jumper is plugged to both PINs!
Do not replug the jumper under voltage, observe the safety instructions!

### 5.11 Potential at control voltage connections

The control voltage connections (<50 V) relate to the joint GND potential (Exception: Relay contacts are potential free). There is a potential separation between the control voltage connections and the protective earth. It must be ensured that the maximum external voltage at the control voltage connections cannot exceed 50 V (between "GND" terminals and "PE" protective earth). If necessary, a connection to the protective earth potential can be established, install bridge between "GND" terminal and the "PE" connection (terminal for screening).

## 6 Select operation mode

### 6.1 Mode and signal input

## Information

Simple installation is possible through the selection of the preprogrammed mode of operation ( Start-up)
This determines the basic function of the device; factory setting 1.01 = speed controller (activation via $0-10 \mathrm{~V}$ signal). The controller configuration is automatically carried out during selection of the application related mode of operation. The factory presets in accordance with the mode of operation are based on many years of experience, which is suitable for many applications. Under special circumstances, these can be individually adapted ( Operating Instructions / Controller Setup: "Controller Configuration").
The purpose of the device is to reach and maintain the target values set. To accomplish this, the measured actual value (sensor value) is compared with the adjusted target value, and the controlled value (modulation) is deduced from this.

By selection of the mode the function for control circuit 1 is determined, this influences the following outputs (factory setting):

1. Analog output "A1" 0-10 V with function 2A (Electrical installation).
2. MODBUS Master interface " 1 A " + "1B" with function 2A ( Electrical installation).

| Mode |  | Signal or Sensor (input) | Function |
| :---: | :---: | :---: | :---: |
| 1.01 |  | Signal: 0-10 V, 0-20 mA, 4-20mA | Speed controller with input for Setting signal, two step operation (Factory setting) |
| 1.02 |  | - | Manual speed controller with direct setting by the keys V © (0-100 \% or in 1-5 steps) |
| 2.01 |  | Sensor KTY81-210 / PT1000 (E1) | Temperature control airconditioning and refrigeration (preset set-point $20.0^{\circ} \mathrm{C}$, P-band 5.0 K ) |
| 2.02 |  | Sensor KTY81-210 / PT1000 (E1) | Temperature control depending on outdoor temperature (preset set-point $5.0^{\circ} \mathrm{C}$, - P-band 20.0 K ) |
| 2.03 |  | Sensor KTY81-210 / PT1000 (E1) | Temperature control with additional functions (shutter and heating) |
| 2.04 |  | 1x Sensor KTY81-210 / PT1000 (E1) <br> 1x Sensor KTY81-210 / PT1000 (E2) | Temperature control with two sensors, comparison or average |
| 2.05 |  | 1x Sensor KTY81-210 / PT1000 (E1) <br> 1x Sensor KTY81-210 / PT1000 (E2) | Temperature control with two sensors differential temperature |
| 3.01 |  | Sensor MBG.. (E1) | Pressure control condensers (refrigeration) |
| 3.02 | * | Sensor MBG.. (E1) | Pressure control for condensers with input for refrigerant |
| 3.03 |  | 1x sensor MBG.. (E1) <br> 1x sensor MBG.. (E2) | Pressure control for two circuit condensers |
| 3.04 |  | 1x sensor MBG.. (E1) <br> 1x sensor MBG.. (E2) | Pressure control for two circuit condensers with input for refrigerant |
| 4.01 |  | Sensor DSG.. / MPG.. (E1) | Pressure control for ventilation systems |
| 4.02 |  | 1x Sensor DSG.. / MPG.. (E1) 1x Sensor KTY81-210 / PT1000 (E2) | Pressure control depending on outdoor temperature |
| 4.03 |  | 1x Sensor DSG.. / MPG.. (E1) <br> 1x BUS RS 485 | Pressure control with outdoor temperature-dependent setpoint adaptation and activation by MODBUS |
| 5.01 |  | Sensor DSG.. / MPG.. (E1) | Volume control (constant) for ventilation systems |
| 5.02 |  | 1x Sensor DSG.. / MPG.. (E1) <br> 1x Sensor KTY81-210 / PT1000 (E2) | Volume control with setpoint depending on outdoor temperature |
| 6.01 |  | Sensor MAL.. (E1) | Air velocity control e.g. clean room |

[^0]Mode and Signal to E1, E2


### 6.2 Operation with a second control circuit

The function for control circuit 1 is determined by selection of the mode. This influences the output with function 2 A .

A second control circuit with separate actual value measuring and separate output can be activated additionally if required.
Control circuit 2 influences the output with function 8 A

- Analog output "A2" (factory setting) IO Setup
- MODBUS Master interface member menu

Operation with a second control circuit is not possible in the following modes:

### 1.01, 1.02, 2.03, 4.02, 4.03, 5.02

The following modes which are pre-programmed to operation with a second sensor can be reprogrammed to operation with a second control circuit.

### 2.04, 2.05, 3.03, 3.04

The second control circuit is activated by the "E2 function" for the second analogue input "E2" ( menu group "Base Setup").

E2 functions for activating control circuit 2:

| E2 Function | Description second control circuit | Factory setting |  |
| :---: | :---: | :---: | :---: |
|  |  | E2 Analog In | 2.Setpoint 1 |
| Temperature (8E) | Temperature control Presettings and sensor selection Mode 2.01 | TF | $20.0{ }^{\circ} \mathrm{C}$ |
| Cold-Pressure (9E) | Pressure control condensers Presettings and sensor selection Mode 3.01 | MBG0-30 | 15.00 bar |
| Cold-Temperature (10E) | Pressure control for condensers with input for refrigerant Presettings, sensor selection and input for refrigerant Mode 3.02 | MBG0-30 | $35.0^{\circ} \mathrm{C}$ |
| Air Pressure (11E) | Pressure control Airconditioning <br> Presettings and sensor selection Mode 4.01 | DSG200 | 100.0 Pa |
| Air flow (12E) | Air volume control <br> Pressettings, sensor selection and K-Factor for inlet ring Mode 5.01 | DSG200 | $44720 \mathrm{~m}^{3} \mathrm{~h}$ |
| Air speed (13E) | Air velocity control Presettings and sensor selection Mode 6.01 | MAL1 | 0.50 m/s |

When activating control circuit 2, the "Setting" menu group is extended.

- The additional parameters for control circuit 2 are identified by a prefixed "2." e. g. "2.Setpoint 1 ".
- A prefixed "1." e. g. "1.Setpoint 1 " is added to the parameters for control circuit 1.


## Example:Second control circuit Pressure control condensers

| E2 function = 9E, | 2.01 for temperature control via control circuit 1 |
| :---: | :---: |
| Setting | 1.Setpoint 1 |
| $\begin{gathered} 20.0^{\circ} \mathrm{C} \\ \text { 1.Setpoint } 1 \end{gathered}$ | Setpoint 1 for control circuit 1 <br> Setting range with passive sensor type "TF", "PT1000" : -50.0...150.0 ${ }^{\circ} \mathrm{C}$ Factory setting: $20.0^{\circ} \mathrm{C}$ |
| Setting | 1.Setpoint 2 |
| 1.Setpoint 2 | Setpoint 2 for control circuit 1 <br> Setting "Setpoint 2" e.g. reduced value for night operation. <br> Switch over Setpoint 1/2 by external contact (as long as no allocation is carried out Display: $\square$ IOSetup). |
| Setting | 1. Pband 1 |
| 5.0 K <br> 1. Pband 1 | Pband 1 for control circuit 1 <br> Setting range with passive sensor type "TF", "PT1000" : 0.0...200.0 ${ }^{\circ} \mathrm{C}$ Factory setting: 5.0 K |
| Setting | 1. Min. Speed |
| $\begin{gathered} 0 \% \\ \text { 1. Min. Speed } \end{gathered}$ | Minimal Speed for control circuit 1 <br> Setting range: 0 rpm... "1. Max. Speed" Factory setting: 0 \% |
| Setting | 1. Max. Speed |
| $\begin{aligned} & 100 \% \\ & \text { 1. Max. Speed } \end{aligned}$ | Maximal Speed for control circuit 1 Setting range: 100 \%... "1. Min. Speed" Factory setting: 100 \% |
| Setting | 2.Setpoint 1 |
|  | Setpoint 2 for control circuit 2 |
| 12.0 bar 2.Setpoint 1 | Setting range: in measuring range of sensor Factory setting: 12,0 bar |


| Setting | 2.Setpoint 2 |
| :---: | :---: |
| 2.Setpoint 2 | Setpoint 2 for control circuit 2 <br> Setting "Setpoint 2" e.g. reduced value for night operation. <br> Switch over Setpoint $1 / 2$ by external contact (as long as no allocation is carried out: <br> Display: $\square$ IOSetup). |
| Setting | 2. Pband 1 |
| 5.0 bar <br> 2. Pband 1 | Pband 1 for control circuit 2 <br> Setting range: in measuring range of sensor Factory setting: 5,0 bar |
| Setting | 2. Min. Speed |
| $\begin{gathered} 0 \% \\ \text { 2. Min. Speed } \end{gathered}$ | Minimal Speed for control circuit 2 Setting range: 0. rpm... "2. Max. Speed" Factory setting: 0 \% |
| Setting | 2. Max. Speed |
| $100 \text { \% }$ <br> 2. Max. Speed | Maximal Speed for control circuit 2 Setting range: 100 \%... "2. Min. Speed" Factory setting: 100 \% |
| Setting | Manual mode |
| OFF <br> 1. Manual mode | Manual mode for control circuit 1 <br> "OFF" = automatic control as function of the set parameters (Factory setting) <br> "ON" = automatic control without function, speed setting in menu "Speed manual" |
| Setting | Speed manual |
| $100 \text { \% }$ <br> 1. Speed man. | Speed Manual mode for control circuit 1 Setting range: 0 rpm... "1. Max. Speed" Factory setting: 100 \% |

Function extension for digital inputs "D1" and "D2" in operation with second control circuit

| D1 / D2 Function | Description * |
| :---: | :--- |
| E1 / E2 <br> (4D) | The output for control circuit 2 is set additionally to "A2" to "A1" (regardless of the <br> programmed function for A1 ). Control circuit 1 has no output for the duration of the <br> switching. |
| 2. Setpoint 1/2 <br> (9D) | for control circuit 2: Switch over "Setpoint 1" / "Setpoint 2" |
| 2.Setp+Pband1/2 <br> (16D) | for control circuit 2: Switch over Setpoint 1/2 and Pband 1/2 <br> When programming this function, "Setting" additionally lists the parameter: "2.Pband 2 for <br> control circuit 2." |

[^1]
## Following restrictions apply for the control circuit 2:

- The "Manual Mode" function in the "Setting" menu group only influences control circuit 1!
- The Limit (IO Setup 3D and Controller Setup) function influences both control circuits simultaneously.
- The "Max. Speed" setting by a digital input ( IO Setup 11D) simultaneously influences both control circuits. I.e. at "1.Max. Speed" and at "2.Max. Speed".
- The controller configurations (KP, KI, KD, TI Controller Setup) are identical for both control circuits. Fine adjustment is possible for each control circuit by the separate "Pband" setting.


### 6.3 External Setpoint / External speed setting in manual operation

External setpoint setting or external manual operation are possible using a $0-10 \mathrm{~V}(0-20 \mathrm{~mA}, 4-20 \mathrm{~mA})$ signal at the "E2" and "GND" terminals. Configure "E2" in Base setup. For potentiometers, program Analog Out 1 (terminal "A1") to the function 1A = "+10 V" (as factory setting IO Setup).
E2 Analog In = factory setting 0-10 V

$$
0-10 \mathrm{~V}
$$



External Setpoint via external signal instead of "Setpoint 1". The "external Setpoint" function must be activated in base setup 1 E for " $E 3$ function". The active external Setpoint value is displayed in the "info" menu group. External speed setting in manual operation. The "external manual operation" function must be activated in the basic settings 2E for "E3 function". Switchover between settings on the device and external manual operation via the digital input (

Not possible in modes with 2 sensors and operation with a second control circuit because the second analogue input is already occupied by it.

## 7 Start-up

### 7.1 Prerequisites for commissioning

## Attention!

1. You must mount and connect the device in accordance with the operating instructions.
2. Double check that all connections are correct.
3. The mains voltage must match the information on the rating plate.
4. Make sure that no persons or objects are in the fan's hazardous area.

### 7.2 Procedure for commissioning

1. Turn on mains voltage

- Display:

(Function of display controls and menu)

2. Switch over between "Info" and "Main menu" with the "Esc" key combination
3. Menu group: Start

- Set the menu language if necessary (factory setting English = Language GB).
- The display can be switched between SI units (US units = OFF) and imperial (US) units (US units = ON).

4. Menu group: Base setup

- Set the desired mode (factory setting 1.01 = speed controller).
- Further settings depend on the selected mode and the sensor / setting signal used.

5. Menu group: Setting

- Set the parameters for the control mode.


## Excerpt from the menu table

| Start |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Language | GB | GB | GB | GB | GB | GB | GB | GB | GB |
| US units | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |
| Base setup |  |  |  |  |  |  |  |  |  |
| Mode | $\begin{aligned} & 1.01 \\ & 1.02 \end{aligned}$ | $\begin{array}{\|l\|} \hline 2.01 \\ \hline 2.03 \\ \hline 2.04 \\ \hline \end{array}$ | 2.02 | 2.05 | $\begin{array}{\|l\|} \hline 3.01 \\ \hline 3.02 \\ \hline \end{array}$ | $\begin{array}{\|l\|} \hline 3.03 \\ \hline 3.04 \\ \hline \end{array}$ | 4.01 <br> 4.02 <br> 4.03 | $\begin{array}{\|l\|} \hline 5.01 \\ 5.02 \\ \hline \end{array}$ | 6.01 |
| E1 Analog In | $\begin{gathered} 1.01=0 \\ -10 \mathrm{~V} \end{gathered}$ | TF | TF | TF | $\begin{aligned} & \text { 0-30 } \\ & \text { MBG } \end{aligned}$ | $\begin{aligned} & \text { 0-30 } \\ & \text { MBG } \end{aligned}$ | DSG200 | $\begin{array}{\|c\|} \hline 4.01= \\ \text { DSG200 } \\ 4.02+ \\ 4.03= \\ \text { DSG50 } \\ \hline \end{array}$ | 0-1 MAL |
| Number steps | $1.02=0$ |  |  |  |  |  |  |  |  |
| Step 1 value | $\begin{array}{\|l\|} \hline 1.02=-- \\ --(20 \%) \\ \hline \end{array}$ |  |  |  |  |  |  |  |  |
| E1 Refrigerant |  |  |  |  | $\begin{aligned} & 3.02= \\ & \text { R503 } \end{aligned}$ | $\begin{aligned} & 3.04= \\ & \text { R503 } \end{aligned}$ |  |  |  |
| E1 K-Factor |  |  |  |  |  |  |  | 75 |  |
| E2 Refrigerant |  |  |  |  |  | $\begin{gathered} 3.04= \\ \text { R503 } \end{gathered}$ |  |  |  |
| Setting |  |  |  |  |  |  |  |  |  |
| Set Intern1 | $\begin{gathered} 1.01= \\ 80 \% \end{gathered}$ |  |  |  |  |  |  |  |  |
| Setting direct | $\begin{gathered} 1.02= \\ 80 \% \end{gathered}$ |  |  |  |  |  |  |  |  |
| Setting Step | $1.02=0$ |  |  |  |  |  |  |  |  |
| Setpoint1 |  | $20.0{ }^{\circ} \mathrm{C}$ | $5.0{ }^{\circ} \mathrm{C}$ | $0.0{ }^{\circ} \mathrm{C}$ | $\begin{aligned} & 12.0 \mathrm{bar} \\ & 35.0^{\circ} \mathrm{C} \end{aligned}$ | $\begin{aligned} & 12.0 \mathrm{bar} \\ & 35.0^{\circ} \mathrm{C} \end{aligned}$ | 100 Pa | $530 \mathrm{~m}^{3} \mathrm{~h}$ | 0.50 m/s |
| Pband 1 |  | 5.0 K | 20.0 K | 5.0 K | $\begin{gathered} 5.0 \mathrm{bar} \\ 7.0 \mathrm{~K} \end{gathered}$ | $\begin{gathered} 5.0 \mathrm{bar} \\ 7.0 \mathrm{~K} \end{gathered}$ | 100 Pa | $530 \mathrm{~m}^{3} \mathrm{~h}$ | 0.50 m/s |
| Set external1 | $\begin{gathered} 1.01= \\ \text { ON } \end{gathered}$ |  |  |  |  |  |  |  |  |

## Information

Adjust further settings according to the desired function ( Operating Instructions / Programming)

## 8 Controls and Menu

### 8.1 Multipurpose LC display and keyboard



|  | Actual value display <br> Display after line voltage is switched on or after <br> the Esc key combination is used to exit the <br> settings menu (display depends on selected <br> mode and sensor value). |
| :---: | :--- |
| $\mathbf{B}$ | Main menu <br> Display after the Esc key combination is used <br> to exit the actual value display. <br> Select the desired menu group with the $\mathbf{\nabla} \mathbf{~}$ <br> buttons and use the P-key to open it. |
| $\mathbf{P}$ | Program key and open menu. |
| $\mathbf{\nabla}$ | Menu selection, reduce value. |
| $\mathbf{A}$ | Menu selection, increase value. |
| $\mathbf{\nabla + \Delta}$ | Esc-key combination, Escape $=$ leave menu. <br> Esc |

1. Status bar
2. Display of the menu group in which the displayed menu is
located
3. Display window
4. Log entry which still was not seen
5. Timer function active
6. Fire-Symbol (heating operation)
7. Moon-Symbol for set point 2
8. Alarm symbol (fault message alternating with actual value
display)
9. Modulation control circuit 1
10. Modulation control circuit 2 (if activated)
11. STOP-Symbol (enable)
12. Position of the menu in the menu group
13. List of the menu groups

### 8.2 Menu operation

| Info |  | Display after turning on the mains voltage description for menu language English = "GB" (delivery status). <br> Switch over between "Info" * and "Main menu" with the Esc key combination. <br> Example for mode 1.01 (speed controller). | Main men |  |
| :---: | :---: | :---: | :---: | :---: |
| $0 \%$ <br> Modulation |  |  | Start <br> Setting <br> Protocol <br> Base setup <br> Controller Setup |  |
|  |  |  |  |  |
|  |  |  |  |  |
|  |  |  |  |  |
|  |  |  |  |  |
| [ESC] Menu |  |  | [P] Enter | [ESC] Info |
|  |  | *Info depending on device type: <br> - "Speed" / rpm,- "Frequency" / Hz, - "Modulation" <br> / \% |  |  |


| Main menu |  |
| :--- | :--- |
| Start |  |
| Setting <br> Protocol <br> Base setup <br> Controller Setup | Select the desired menu group with the $\boldsymbol{\nabla} \boldsymbol{\Delta}$ keys (text highlighted) and open with the $\mathbf{P}$ - <br> key. |
| [P] Enter $\quad[E S C]$ Info |  |

$\Delta \nabla$

| Start |  |  |
| :--- | ---: | :--- |
|  | ---- <br> PIN input | PIN input, e.g. for resetting to basic factory setting |
| [P] Edit | [ESC] Menu |  |

$\Delta \nabla$

| Start |  |
| :--- | :--- |
|  | GB <br> Language |
| [P] Edit | In the menu point "Language" display language can be selected. <br> One returns to the menu group "Start" using the Esc $(\boldsymbol{\nabla}+\boldsymbol{\Delta})$ shortcut keys. |

### 8.3 Example for programming mode 2.01 in "Base setup "

## Sequence



### 8.4 Menu structure



Menu dependent on mode

Selection of the menu group (e.g. Base setup) to the right through the $\boldsymbol{\nabla}$-key, to the left through the $\boldsymbol{\nabla}$-key.
You can go to the menu items in the menu groups (e.g. mode of operation) by using the $\mathbf{P}$ key. Use the arrow keys to move up and down within the menu group.
The menu groups consist of one area for the user (user menu) and one area for installation (service). The service area can be protected against unauthorized access by using a PIN.
In order to simplify the initial start-up operation, the service level is enabled at first (i.e., not protected by the PIN 0010 (な
Operating Instructions / Controller Setup, PIN protection = OFF). If PIN protection is activated (ON), the service menu remains enabled after input of PIN 0010 as long as one is pressing keys. If no keys are pressed for ca. 15 minutes, the PIN is automatically erased, i.e. the service level is blocked.
To make adjustments, press the $\mathbf{P}$ key after selecting the menu item. If the previously set value starts to ash, it can be adjusted with the $\boldsymbol{\nabla}+\boldsymbol{\Delta}$ keys and then saved with the $\mathbf{P}$ key. To exit the menu without making any changes, use the "Esc" short-key, i.e., the originally set values remain.

Information
After installation of the device has been carried out, PIN protection should be activated ( Operating Instructions / Controller Setup)!

### 8.5 Overview menu groups

| Main menu | Possible settings |
| :---: | :--- |
| Info | Display measured actual values, selected setpoints, modulation, etc. <br> Settings cannot be made in this menu group. |
| Start | PIN input for reset to initial settings and to protect settings. <br> Setting the menu language. <br> Display in SI units or Imperial units (US) <br> Complete re-start of the device. <br> Display of the set mode, software version, etc. |
| Setting | Settings for Operation, Setpoint, Pband, Min. Speed, Max. Speed, etc. |
| Protocol | Display and query of events / malfunctions. |
| Base setup | Setting of the desired mode, configuration of signal and sensor inputs. <br> Activation control circuit 2. |
| Controller Setup | Activate set protection, save user settings. <br> Activate alarm message in the event of a sensor fault. <br> Activate limitation of modulation via digital input or timer of time switch. <br> Configuration of control parameters, group control. |
| IO Setup | Configuration and function assignment for: analogue outputs, digital inputs, relay out- <br> puts. <br> Function MODBUS interface: COM2 for MODBUS Slave or MODEM SMS. |
| Limits | Limit messages depending on modulation, setting signal or sensor signal, offset to <br> setpoint. |
| Timer | Integrated time switch with programmable timer functions. <br> Clock fine adjustment |
| Diagnostic | Current operating states of the device. |
| MODBUS Slave | Addressing and configuration of the MODBUS Slave interface. <br> alternatively <br> Input of SIM PIN for MODBUS SMS interface (currently no function). |
| MODBUS SMS | Start automatic addressing of members. <br> alternatively <br> Manual input of number of members. |
| MODBUS Master |  |

## 9 Programming

Display in SI units or Imperial units (US)
The following description is for display in SI units (factory setting). The appropriate conversion factors must be observed when switching over to Imperial units (US) ( menu group Start / US Units).

### 9.1 Speed controller 1.01, 1.02

### 9.1.1 Speed controller with setting by external signal 1.01

Settings for controller output with function 2A (by analogue signal IO Setup, by MODBUS members menu).

Base setup 1.01

| Main menu | Base setup |
| :---: | :---: |
| Setting <br> Protocol <br> Base setup <br> Controller Setup <br> IO Setup |  |
| Base setup ${ }^{\text {P }}$ (1.01 | Mode <br> Factory setting Mode: 1.01 |
| Base setup $\begin{gathered} 0-10 \mathrm{~V} \\ \text { E1 Analog In } \end{gathered}$ | E1 Analog In <br> Selection: 0-10V, 0-20 mA, 4-20 mA (Inverting, E1 BUS Modus IO Setup) Factory setting: 0-10 V |
| Base setup <br> OFF <br> E2 Function | E2 Function (only for special applications) <br> Analog input 2 "E2" factory set at "OFF". <br> For operation with a second setting signal and switch over by potential-free contact: E2 <br> Function = Ext. Setpoint (1E) <br> Necessary function for digital input: E1/E2 (4D) IO Setup <br> For operation with a second signal and automatic control at the higher level: E2 Function = comparison E1 (4E). |
| Base setup $\qquad$ <br> E2 Analog In | E2 Analog In <br> Display as long as no function allocated: $\square$ <br> Selection: 0-10 V, 0-20 mA, 4-20 mA (Inverting, E2 BUS Modus IO Setup) Factory setting: 0-10 V |

## Setting for operation 1.01

| Main menu | Setting |
| :---: | :---: |
| Setting <br> Protocol <br> Base setup <br> Controller Setup <br> IO Setup |  |
| Setting $80 \text { \% }$ <br> Set Intern1 | Set Intern1 <br> Setting range manual speed setting: 0... 100 \% 气 "Min. Speed"... "Max. Speed" Factory setting: 80 \% |
| Setting <br> Set Intern2 | Set Intern2 <br> Setting "Set Intern2" e.g. reduced value for night operation. <br> Switch over Interni 1/2 over external contact (display where no allocation: $\square$ ${ }^{\circ}$ IO Setup). |
| Setting $\begin{gathered} 0 \% \\ \text { Min. Speed } \end{gathered}$ | Min. Speed <br> Setting range: 0... "Max. Speed" <br> Factory setting: 0 \% |
| Setting $100 \text { \% }$ <br> Max. Speed | Max. Speed <br> Setting range: 100 \%... "Min. Speed" Factory setting: 100 \% |
| Setting <br> ON <br> Set external1 | Set external1 <br> "ON" (factory setting) = speed setting by external Signal "OFF" = Setting "Set Intern1" |

Diagram setting signal and output voltage (Idealized principle diagram)


MODBUS Out: speed setting over MODBUS
Analog Out: speed setting over analog output 0-10 V
Si Signal

### 9.1.2 Speed controller with direct setting by keyboard 1.02

## Base setup 1.02

| Main menu | Base setup |
| :---: | :---: |
| Setting <br> Protocol <br> Base setup <br> Controller Setup <br> IO Setup |  |
|  | Mode <br> Mode selection: 1.02 |
| Base setup <br> 0 <br> Number steps | Number steps <br> Selection: 0, 1, 2, 3, 4, 5 <br> Factory setting: 0 <br> Number steps: 0 <br> In the factory setting " 0 " (without steps) the modulation can be set directly with the <br> $\Delta$ keys ( setting in operation). <br> Number steps: 1, 2, 3, 4, 5 <br> The modulation value can be assigned to each step. The desired step is set with the © keys ( setting in operation). <br> The following menus become active depending on the selected step count. (Step not active = $\square$ |
|  |  |
| Base setup <br> ---- <br> Step 1 value | Step 1 value - 5 <br> Setting range: 0... 100 \%. <br> Factory setting: ---- (Number steps 0) <br> Factory setting: $20 \%, 40 \%, 50 \%, 60 \%, 100 \%$ (Number steps 1 - 5 ) |

## Menu group "Setting" (only when needed)

| Main menu | Setting |
| :---: | :---: |
| Setting |  |
| Protocol <br> Base setup <br> Controller Setup <br> IO Setup |  |
| Setting | Setting direct (at Number steps: 0 "Base setup") |
| $80 \text { \% }$ <br> Setting direct | If the setting is to be made during operation directly with the $\boldsymbol{\nabla} \boldsymbol{\Delta}$ keys, no setting is necessary here ( setting in operation 1.02). |
|  | Setting range: Min. Speed - Max. Speed Factory setting: 80 \% |
| Setting | Setting step (at Number steps: 1-5 "Base setup") |
| 0 | If the setting is to be made during operation directly with the $\boldsymbol{\nabla} \boldsymbol{\Delta}$ keys, no setting is necessary here ( setting in operation 1.02). |
|  | Setting range: 0 - setting nummber steps Factory setting: 0 |


| Setting | Min. Speed <br> Setting range: 0... "Max. Speed" Factory setting: 0 \% |
| :---: | :---: |
| $\begin{gathered} 0 \text { \% } \\ \text { Min. Speed } \end{gathered}$ |  |
| Setting | Max. Speed <br> Setting range: 100 \% - "Min. Speed" Factory setting: $100 \%$ |
| $\begin{gathered} 100 \text { \% } \\ \text { Max. Speed } \end{gathered}$ |  |

## Setting in operation 1.02

After installation is completed, only the "Setting direct" or "Setting Step" setting is visible in the "Info" menu group. All other menus are protected by a PIN.

| Info | ```Setting direct (at Number steps: 0 "Base setup") Setting range: Min. Speed - Max. Speed Factory setting: 80 %``` |
| :---: | :---: |
| $76 \text { \% }$ <br> Setting direct |  |
|  | The value set by the $\boldsymbol{\nabla}$ keys is accepted and executed directly ( $\mathbf{P}$ key without function). |
| Info | Setting step (at Number steps: 1-5 "Base setup") |
| 5 <br> Setting Step | Setting range: 0 - programmed number steps Factory setting: 0 |

Switching over to the protected "Info" menu group takes place automatically after approximately minutes if no key is pressed.

## Possibilities for early activation of PIN protection:

- Select the "Info" menu group and confirm with the P key.
- Press the Esc key combination several times until the "Setting direct" or "Setting Step" menu is displayed.
- Execute the "Reset" function in the "Start" menu group.
- By switching the mains voltage off and then on again.

Input PIN 0010 to exit the protected area

|  |  | $\rightarrow$ | $\rightarrow$ | $\rightarrow$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $76 \text { \% }$ <br> Setting direct | $\boldsymbol{\nabla}+\boldsymbol{\Delta}=$ Esc | PIN input | P | 0010 <br> PIN input | P | Start <br> Setting <br> Protocol <br> Base setup <br> Controller Setup <br> IO Setup |
| $\begin{gathered} 5 \\ \text { Setting Step } \end{gathered}$ |  |  |  |  |  |  |

### 9.2 Temperature control 2.01...2.05

### 9.2.1 Basic setting 2.01... 2.05

| Main menu | Base setup |
| :---: | :---: |
| Setting <br> Protocol <br> Base setup <br> Controller Setup <br> IO Setup |  |
| \| ${ }^{\text {Base setup }}$ ( ${ }^{\text {2.01 }}$ Mode | Mode <br> Mode selection e.g. 2.01 |
| $\begin{array}{\|} \text { Base setup } \\ \hline \text { TF } \\ \text { E1 Analog In } \end{array}$ | E1 Analog In <br> The sensor input is factory set in modes of group $\mathbf{2}$ to sensors of the "TF" type series (sensor type KTY81-210). <br> Measuring range: $-50.0 \ldots+150^{\circ} \mathrm{C}$ <br> Connection terminals: "GW E1 Viive" and "T" <br> Other settable sensors: <br> - PT1000 at terminals "E1" and "T", (measuring range $-50.0 \ldots+150^{\circ} \mathrm{C}$ ) <br> - MTG-120V (type designation for active sensor with 0-10 V output, connection to terminals "E1", "GND" and " 24 V ", measuring range: $-10 \ldots+120^{\circ} \mathrm{C}$ ) <br> - 0-10 V, 0-20 mA, 4-20 mA (for sensors with free measuring range and linear characteristic) <br> The sensor measuring range must be entered for sensors with free measuring range in order to display the actual value correctly. <br> Example with a $0-10 \mathrm{~V}$ sensor and $0-100^{\circ} \mathrm{C}$ measurement range: <br> E1 Analog In = 0-10 V, E1 Unit $={ }^{\circ} \mathrm{C}$, E1 Decimals $=1$, E1 Min. $=0,0^{\circ} \mathrm{C}$, E1 Max. $=$ $100,0^{\circ} \mathrm{C}$, <br> When selecting sensors with active signal, the setpoint and the Pband are automatically set to the $1 / 2$ measuring range. |
|  |  |
| Base setup | E1 Offset <br> Sensor calibration with calibrated comparison device. <br> The current "E1 Actual" is displayed including the offset set here. |
| $\begin{gathered} 20.0^{\circ} \mathrm{C} \\ \text { E1 Offset } \end{gathered}$ |  |


| Base setup | E2 Function |
| :---: | :---: |
|  | The second signal input is not activated at the factory for modes with one sensor. <br> The function is automatically jointly programmed in operating modes using two sensors. The second analog input is thus allocated and additional function allocations are not possible. <br> - 2.04 E2 Function at 4E preprogrammed = comparison value with control to higher temperature. Alternative: average of 2 measuring points for this must be reprogrammed on function 3E preprogrammed sensor type "TF". <br> - 2.05 E2 Function at 5E preprogrammed = regulation on difference temperature between sensor 1 and sensor 2. Preprogrammed sensor type "TF". <br> Adjustable "E2 Function" <br> - $1 \mathrm{E}=$ External Setpoint e.g. via external signal ( $0-10 \mathrm{~V}$ ) instead of "Setpoint 1 " <br>  <br> - For sensors with active signal: $0-10 \mathrm{~V} \triangleq 0-100 \%$ sensor measuring range. <br> - 2E = External manual operation via external signal (0-10 V). Switch over between settings on the device and external manual operation via digital input ( IO Setup: function 7D). <br> - 6E = sensor for outdoor temperature-dependent setpoint adaptation (at 2.03 not possible), pre-programmed sensor type "TF..". <br> - additional parameters menu group "Setting": T-Band, T-Start SA, Min. Setpoint. <br> - additional parameters menu group"Info": Setpoint Control <br> - Example Setting for operation 4.01... 4.03 / additional menu items. <br> - 7E = Measurement value = Measurement value e.g. for limit indication, display in Info menu "E2 Actual". <br> - $8 \mathrm{E} . .1$ 13E = sensor input for control circuit 2 (at 2.03 not possible) base setup / operation with second control circuit. |
|  |  |
|  |  |

### 9.2.2 Settings for operation modes 2.01... 2.05

2.01 Temperature control airconditioning and refrigeration
(preset set-point $20.0^{\circ} \mathrm{C}$, P-band 5.0 K )
2.02 Temperature control depending on outdoor temperature (preset set-point $5.0^{\circ} \mathrm{C}$, - P-band 20.0 K )
2.03 Temperature control with pre-programmed additional functions (heating, shutter, temperature monitoring).
2.04 Temperature control with 2 sensors

Comparison with control to higher value "E2 Function" set to comparison 4E. Display during operation: "Control value "
Alternative: Average calculation of 2 measuring places "E2 Function" set to 3E. Display during operation: "Average E1 / E2"
2.05 Temperature control with 2 sensors, regulation on difference temperature.

Display during operation: "Value of E1 - E2" in K, "E1" = reference temperatur, "E2" causes positiv (E2 <E1) or negative (E2 >E 1) difference.

Settings for controller output with function 2A (by analogue signal IO Setup, by MODBUS members menu).

| Main menu | Setting |
| :--- | :--- |
| Setting |  |
| Protocol |  |
| Base setup |  |
| Controller Setup |  |
| IO Setup |  |
|  |  |



### 9.2.3 Functional diagrams temperature control

Example 1: Temperature control in factory setting "Cooling function" (Idealized principle diagram)

(Controller Setup: "Actual>Nominal=n+" at "ON")
MODBUS Out: speed setting over MODBUS
Analog Out: speed setting over analog output 0-10 V
$S$ Setpoint
$R$ Pband
I Actual value
Example 2: Temperature control in "Heating function" (Idealized principle diagram)

(Controller Setup: "Val>Set=n+" to "OFF")
MODBUS Out: speed setting over MODBUS
Analog Out: speed setting over analog output 0-10 V
S Setpoint
$R$ Pband
I Actual value

### 9.2.4 Additionally for 2.03 (controller output 2 with function 6 A )

The 0-10 V output signal A2 can, e.g., be used for triggering a shutter or heating.


Example for signal out 0-10 V (IO Setup: "A2 function" = 6A)


Example: Setpoint ventilation $25.0^{\circ} \mathrm{C}$, Offset -5.0 K , Pband 10.0 K
$S$ Setpoint Ventilation +/- Offset
$R$ Pband
1 Actual value

### 9.2.5 For mode 2.03: Relay output for Heating or Cooling

| Setting | OffsetDigitalOut <br> Offset Digital Out = Offset for relay output ("K2" is pre-programmed by the factory). <br> The relay operating point deviates by the adjusted offset of the Setpoint of the ventilation (if relay "K2" not inverted, terminal " 21 "-" 24 " bridged). <br> Setting range: -10.0...+10.0 K <br> Factory setting: -1.0 K <br> - "0.0 K" set, i.e. heating "ON" when: actual value = Setpoint <br> - During negative offset value heating "ON" when: actual value = Setpoint - offset <br> - During positive offset value heating "ON" when: actual value $=$ Setpoint + offset |
| :---: | :---: |
| $\begin{gathered} -1.0 \mathrm{~K} \\ \text { OffsetDigitalOut } \end{gathered}$ |  |
|  |  |
| Setting | Hyst.DigitalOut |
| $\begin{gathered} 1.0 \mathrm{~K} \\ \text { Hyst.DigitalOut } \end{gathered}$ | Setting range: $0 \ldots . .10,0 \mathrm{~K}$, Factory setting: 1.0 K (Kelvin) |

Temperature variation with factory setting 9 K ] in IO Setup e. g. for controlling a Heating. If the ambient temperature is lower than the set operating point, the heating remains switched on. If the ambient temperature exceeds the set operating point of the heating by 2 K (Kelvin), the heating is switched off. I.e., the release point is situated at the hysteresis value over the operating point.

## Example:

Setpoint $15.0^{\circ} \mathrm{C}$, Offset +5.0 K , Hysteresis 2.0 K


## Example:

Setpoint $20.0^{\circ} \mathrm{C}$, Offset -5.0 K , Hysteresis 2.0 K



Temperature variation with reprogramming to 10 K for "K2" in IO Setup, e.g., for activation of the Cooling

Example:
Setpoint $15.0^{\circ} \mathrm{C}$, Offset +5.0 K , Hysteresis 2.0 K


If the ambient temperature is higher than the set operating point, the cooling remains switched on. If the ambient temperature falls below the set operating point of the cooling by 2 K (Kelvin), it is switched off. I.e., the OFF point is situated at the hysteresis value under the ON point.

### 9.2.6 For mode 2.03 Relay output for temperature monitoring

If the set value for the "minimum alarm" is not reached or the set value for the "maximum alarm" is exceeded, a message is generated via the alarm symbol in the display. In addition, „Lmt E1 min" is displayed alternately with the actual value for the minimum alarm and Lmt E1 max for the „Maximum alarm". An external message follows via the factory-assigned"K1" relay. (IO Setup: K1 function = 2K).

| Setting | Alarm Minimum <br> Setting range: OFF / -49.9... $150.0^{\circ} \mathrm{C}$ Factory setting: $0.0^{\circ} \mathrm{C}$ |
| :---: | :---: |
| $\begin{gathered} 0.0^{\circ} \mathrm{C} \\ \text { Alarm Minimum } \end{gathered}$ |  |
| Setting | Alarm Maximum |
| $40.0^{\circ} \mathrm{C}$ <br> Alarm Maximum | Factory setting: $40.0{ }^{\circ} \mathrm{C}$ |


| Info | Example for display if falling below setting "Alarm Minimum" alternating to the actual value display. <br> Relay "K1" disengages (if not inverted). |
| :---: | :---: |
| Lmt E1 min |  |
| Info | Example for display if exceeding setting "Alarm Maximum" alternating to the actual value display <br> Relay "K1" disengages (if not inverted). |
| Lmt E1 max. |  |

### 9.3 Pressure control for condensers refrigeration 3.01...3.04

### 9.3.1 Base setup 3.01... 3.04

| Main menu | Base setup |
| :---: | :---: |
| Start <br> Setting <br> Protocol <br> Base setup <br> Controller Setup |  |
| Base setup <br> 3.01 <br> Mode | Mode <br> Mode selection e.g. 3.01 |
| Base setup <br> MBG0-30 E1 Analog In | E1 Analog In <br> The sensor input is factory set for modes of group $\mathbf{3}$ to sensor type "MBG-30I". <br> Measuring range: $0 \ldots 30$ bar <br> Output signal: 4-20 mA <br> Connection terminals: "E1", " 24 V " <br> Other settable sensors: <br> - MBG-50I (measuring range 0...50 bar, output signal 4-20 mA) <br> - DSF2-25 (measuring range 2...25 bar, output signal 4-20 mA) <br> - 0-10 V, 0-20 mA, 4-20 mA (for sensors with free measuring range and linear characteristic) <br> The sensor measuring range must be entered for sensors with free measuring range in order to display the actual value correctly. <br> Example 0-10 V sensor and measuring range 0-20 bar: <br> E1 Analog In = 0-10 V, E1 Unit = bar, E1 Decimals = 1, E1 Min. = 0,0 bar, E1 Max. = 20,0 bar |
|  |  |
| Base setup | E1 Offset <br> Sensor calibration with calibrated comparison device. <br> The current " $E 1$ Actual" is displayed including the offset set here. |
| $\begin{aligned} & 0.00 \text { bar } \\ & \text { E1 Offset } \end{aligned}$ |  |
| Base setup | E1 Refrigerant <br> With $\mathbf{3 . 0 2}$ and $\mathbf{3 . 0 4}$ operating modes with input of the refrigerant, the device automatically calculates the corresponding temperature for the measured pressure. The settings for offset, target value and the controlling range are then carried out in ${ }^{\circ} \mathrm{C}$ or K . Calculation for relative pressure (differential measurement of pressure relative to ambient pressure). No further settings are necessary for pressure sensors model e.g. "MBG-301" or "MBG-501" (measurement range 0-30 bar or 0-50 bar). In the case of sensors with other measurement ranges, the "E1 Min. value" and the "E1 Max. Value". Setting in "bar" although unit display is in " C "! |
| $\begin{gathered} \text { R503 } \\ \text { E1 Refrigerant } \end{gathered}$ |  |
|  |  |


| Base setup | E2 Function |
| :---: | :---: |
| OFF <br> E2 Function | The second signal input is not activated at the factory for modes with one sensor. The function is automatically jointly programmed in operating modes using 2 sensors. The second analog input is thus allocated and additional function allocations are not possible. |
|  | Modes with two sensors <br> - 3.03 and 3.04 E2 Function at 4 E preprogrammed = comparison value with control to higher value (two circuit condensers). <br> Adjustable "E2 Function" <br> - $1 \mathrm{E}=$ external setpoint e.g. by external signal $(0-10 \mathrm{~V})$ instead of setting "Setpoint 1 ". $0-10 V \triangleq 0-100 \%$ sensor measuring range. <br> - 2E = External manual operation via external signal (0-10 V). Switch over between settings on the device and external manual operation via digital input (\$) IO Setup: function 7D). <br> - 3E = Sensor average to E1 <br> - 5E = Sensor difference to E1 <br> - 6E = sensor for outdoor temperature-dependent setpoint adaptation, preprogrammed sensor type "TF..". <br> - Menu group "Setting" additional parameter: T-Band, T-Start SA, Min. Setpoint. <br> - Menu group "Info" additional parameter: Setpoint control <br> - Example Setting for operation 4.01... 4.03 / additional menu items. <br> - 7E = Measurement value $=$ Measurement value e.g. for limit indication, display in Info menu "E2 Actual". <br> - $8 \mathrm{E} . . .13 \mathrm{E}$ = sensor input for control circuit 2 base setup / operation with second control circuit. |

## Selection of the refrigerants:

| R12 | R13 | R13b1 | R22 | R23 | R32 | R114 | R134a | R142B |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| R227 | R401 | R401A | R401B | R402 | R402A | R402B | R404A | R407A |
| R407B | R407C | R410A | R500 | R502 | R503 | R507 | R717 |  |

### 9.3.2 Setting for operation modes 3.01... 3.04

3.01 Pressure control condensers, setting Setpoint in bar
3.02 Pressure control for condensers with input for refrigerant, Setpoint in ${ }^{\circ} \mathrm{C}$
3.03 Two sensors for dual circuit condenser. Automatic regulation to the highest pressure (selection amplifier integrated) operation display: "Control value", Setpoint in bar
3.04 Two sensors for dual circuit condenser with input for refrigerant automatic regulation to the highest pressure (selection amplifier). Setpoint in ${ }^{\circ} \mathrm{C}$, also for different refrigerants suitably there comparison of the temperatures. Display during operation: "Control value "

Settings for controller output with function 2A (by analogue signal IO Setup, by MODBUS members menu).

| Main menu | Setting |  |  |  |
| :--- | :--- | :---: | :---: | :---: |
| Start <br> Setting <br> Protocol <br> Base setup <br> Controller Setup |  |  |  |  |
| Setting |  |  |  |  |
| Setpoint1 | Setpoint1 <br> Setting range: in measuring range of sensor <br> Factory setting: 12.0 bar |  |  |  |
|  | $\mathbf{3 . 0 2}$ and $\mathbf{3 . 0 4}$ <br> Setting range: dependent on the selected refrigerant <br> Factory setting: $35.0^{\circ} \mathrm{C}$ |  |  |  |


| Setting | Setpoint2 <br> Setting "Setpoint 2" e.g. reduced value for night operation. <br> Switch over Setpoint $1 / 2$ by external contact (display as long as no allocation is carried out: $\square$ IO Setup). |
| :---: | :---: |
| Setpoint2 |  |
| Setting <br> 5.00 bar Pband | Pband <br> Narrow control range = Short control times <br> Wide control range $=$ Longer control times and more stable control <br> 3.01 and 3.03 |
|  |  |
|  | Setting range: in measuring range of sensor Factory setting: 5.0 bar |
|  | 3.02 and 3.04 |
|  | Setting range: dependent on the selected refrigerant Factory setting: 7.0 K |
| Setting | Min. Speed <br> Setting range: 0... "Max. Speed" <br> Factory setting: 0 \% |
| $\begin{gathered} 0 \% \\ \text { Min. Speed } \end{gathered}$ |  |
| Setting | Max. Speed <br> Setting range: 100 \%... "Min. Speed" Factory setting: 100 \% |
| $\begin{gathered} 100 \text { \% } \\ \text { Max. Speed } \end{gathered}$ |  |
| Setting | Manual mode <br> "OFF" = automatic control as function of the set parameters (Factory setting) <br> "ON" = automatic control without function, speed setting in menu "Speed manual" |
| OFF <br> Manual mode |  |
| Setting | Speed manual <br> Manual speed setting without influence by the external signal. <br> Activation by menu "Manual mode" or external contact at digital input (IO Setup). <br> Setting range: $0 . . .100 \%$ 气 "Min. Speed"... "Max. Speed" <br> Factory setting: 100 \% |
| $100 \text { \% }$ <br> Speed manual |  |
|  |  |
|  | For information about deactivated regulation the adjusted value for manual speed is indicated alternating with the actual value. |

### 9.3.3 Functional diagrams pressure control condensers

Functional diagram for Mode 3.01 and 3.03 (Idealized principle diagram)


MODBUS Out: speed setting over MODBUS
Analog Out: speed setting over analog output 0-10 V
S Setpoint
$R$ Pband
I Actual value
Functional diagram for Mode 3.02 and 3.04 (Idealized principle diagram)


MODBUS Out: speed setting over MODBUS
Analog Out: speed setting over analog output 0-10 V
$S$ Setpoint
$R$ Pband
I Actual value
Information
The factory default presets must be adapted to match the system conditions by a competent person.

### 9.4 Pressure control airconditioning 4.01... 4.03

### 9.4.1 Base setup 4.01... 4.03

| Main menu | Base setup |
| :---: | :---: |
| Start <br> Setting <br> Protocol <br> Base setup <br> Controller Setup |  |
| Base setup <br>  <br> $\mathbf{4 . 0 1}$ <br> Mode | Mode <br> Mode selection e.g. 4.01 |
| Base setup <br> DSG200 <br> E1 Analog In | E1 Analog In <br> The sensor input is factory set for modes of group 4 to sensor type "DSG200". <br> Measuring range: $0 . . .200 \mathrm{~Pa}$ <br> Output signal: 0-10 V <br> Connection terminals: "E1", "GND", " 24 V " <br> Other settable sensors / measuring ranges: <br> - "DSG 50", "DSG100", "DSG200", "DSG300", "DSG500", "DSG1000", "DSG2000", "DSG4000", "DSG6000", INT300, INT500 (numerical data $\hat{=}$ measuring range $[\mathrm{Pa}]$, output signal $0-10 \mathrm{~V}$ ). Type designation DSG... $\hat{=}$ pressure sensor with new type designation MPG.. <br> - 0-10 V, 0-20 mA, 4-20 mA (for sensors with free measuring range and linear characteristic) <br> The sensor measuring range must be entered for sensors with free measuring range in order to display the actual value correctly. <br> Example with a 0-10 V sensor and 0-400 Pa measurement range: <br> E1 Analog In = 0-10 V, E1 Unit = Pa, E1 Decimals = 1, E1 Min. = 0,0 Pa, E1 Max. = 400 Pa |
| Base setup <br>  <br> 0.0 Pa <br> E1 Offset | E1 Offset <br> Sensor calibration with calibrated comparison device. <br> The current "E1 Actual" is displayed including the offset set here. |


| Base setup | E2 Function |
| :---: | :---: |
| OFF <br> E2 Function | The second signal input is not activated at the factory for modes with one sensor. The function is automatically jointly programmed in operating modes using two sensors. The second analog input is thus allocated and additional function allocations are not possible. |
|  | Modes with two sensors <br> - For 4.02 E2 Function at 6E preprogrammed = sensor for setpoint lowering. Preprogrammed sensor type "TF.." <br> - For 4.03 E2 Function at 6E preprogrammed = sensor for setpoint lowering. <br> - Preprogrammed sensor: type "0-10 V" (measuring range $-35.0 \ldots+65.0^{\circ} \mathrm{C}$ Pre-programmed in the 10 setup: <br> - To read out the sensor value via bus: E2 Busmode = "ON" <br> - For enabling via bus: D1 Function = 1D, D1 Busmode = "ON" <br> - For switch over setpoint $1 / 2$ via Bus: D2 Function = 5D, D2 Busmode $=$ "ON" <br> Adjustable "E2 function" for modes with one sensor <br> - $1 \mathrm{E}=$ external setpoint e.g. by external signal ( $0-10 \mathrm{~V}$ ) instead of setting "Setpoint 1 ". $0-10 \vee \triangleq 0-100 \%$ sensor measuring range. <br> - 2E = External manual operation via external signal (0-10 V). Switch over between settings on the device and external manual operation via digital input ( IO Setup: function 7D). <br> - 3E = Sensor average to E1 <br> - 4E = Sensor comparison to E1 <br> - 5E = Sensor difference to E1 <br> - 7E = Measurement value = Measurement value e.g. for limit indication, display in Info menu "E2 Actual". <br> - 8E ... 13E = sensor input for control circuit 2 base setup / operation with second control circuit. |

### 9.4.2 Setting for operation modes 4.01... 4.03

4.01 Pressure control, Setting Setpoint in Pa
4.02 Pressure control setpoint depending on outdoor temperature
4.03 Pressure control with outdoor temperature-dependent setpoint adaptation and activation by MODBUS

Settings for controller output with function 2A (by analogue signal IO Setup, by MODBUS members menu).

| Main menu | Setting |
| :---: | :---: |
| Start <br> Setting <br> Protocol <br> Base setup <br> Controller Setup |  |
| Setting 100 Pa Setpoint1 | Setpoint1 <br> Setting range: in measuring range of sensor Factory setting: 100 Pa |
| Setting <br> Setpoint2 | Setpoint2 <br> Setting "Setpoint 2" e.g. reduced value for night operation. <br> Switch over Setpoint $1 / 2$ by external contact (display as long as no allocation is carried out: $\square$ IO Setup). |


| Setting | Pband |
| :---: | :--- |
| $\mathbf{1 0 0 ~ P a}$ |  |
| Pband |  |$\quad$| Narrow control range = Short control times |
| :--- |
| Wide control range = Longer control times and more stable control |
| Setting range: in measuring range of sensor |
| Factory setting: 100 Pa |

## Additional menu item for mode 4.02 and $\$ .03$ with outside-temperature dependent targetsetpoint.

Outside-temperature dependent target-setpoint


S1 Setpoint1
S2 Setpoint2
P-min. Min. Setpoint
T-min Min. temperature
T-Start Setpoint reducing will start below this outside temperature T-band Temperature range
AT Outdoor temperature

| Setting | T-Band SA |
| :---: | :--- |
| 30 K <br> T-Band SA | Temperature range in which the setpoint change continiously with outside temperature <br> Setting range: $0.0 . .100 .0 \mathrm{~K}$ |
|  | Factory setting: 30.0 K |


| Setting | T-Start SA |  |  |  |
| :--- | :--- | :---: | :---: | :---: |
| $15^{\circ} \mathrm{C}$ |  |  | Setpoint reducing will start below this outside temperature <br> Setting range: $-10.0 \ldots . .40 .0^{\circ} \mathrm{C}$ <br> T-Start SA | Factory setting: $15.0^{\circ} \mathrm{C}$ |

### 9.5 Volume control 5.01 and 5.02

### 9.5.1 Basic setting $\mathbf{5 . 0 1}$ and 5.02

| Main menu | Base setup |
| :---: | :---: |
| Start <br> Setting <br> Protocol <br> Base setup <br> Controller Setup |  |
|  | Mode <br> Mode selection e.g. $\mathbf{5 . 0 1}$ |
| Base setup <br> DSG200 <br> E1 Analog In | E1 Analog In <br> The sensor input is factory set for modes of group $\mathbf{5}$ to sensor type "DSG200". <br> Measuring range: $0 . . .200 \mathrm{~Pa}$ <br> Output signal: 0-10 V <br> Connection terminals: "E1", "GND", "24V" <br> Other settable sensors / measuring ranges: <br> - "DSG 50", "DSG100", "DSG200", "DSG300", "DSG500", "DSG1000", "DSG2000", "DSG4000", "DSG6000", INT300, INT500 (numerical data $\xlongequal{=}$ measuring range $[\mathrm{Pa}]$, output signal $0-10 \mathrm{~V}$ ). Type designation DSG... $\xlongequal{\wedge}$ pressure sensor with new type designation MPG.. <br> - 0-10 V, 0-20 mA, 4-20 mA (for sensors with free measuring range and linear characteristic) <br> The sensor measuring range must be entered for sensors with free measuring range in order to display the actual value correctly. <br> Example with a $0-10 \mathrm{~V}$ sensor and $0-400 \mathrm{~Pa}$ measurement range: <br> E1 Analog In = 0-10 V, E1 Min. $=0,0 \mathrm{~Pa}, \mathrm{E} 1 \mathrm{Max} .=400 \mathrm{~Pa}$ |
| Base setup <br> 75 <br> E1 K-Factor | K Factor Input of the "K factor" dependent on the fan (inlet duct). setting range: 0... 5000 <br> Factory setting: 75 |
|  | E1 Offset <br> Sensor calibration with calibrated comparison device. |


| Base setup | E2 Function |
| :---: | :---: |
| OFF <br> E2 Function | The second signal input is not activated at the factory for modes with one sensor. The function is automatically jointly programmed in operating modes using two sensors. The second analog input is thus allocated and additional function allocations are not possible. |
|  | Modes with two sensors <br> - For 4.02 E2 Function at 6E preprogrammed = sensor for setpoint lowering. Preprogrammed sensor type "TF.. " <br> Adjustable "E2 function" for modes with one sensor <br> - 1E = external setpoint e.g. by external signal (0-10 V) instead of setting "Setpoint 1". $0-10 \mathrm{~V} \triangleq 0-100 \%$ setting range. <br> - $2 \mathrm{E}=$ External manual operation via external signal (0-10 V). Switch over between settings on the device and external manual operation via digital input ( IO Setup: function 7D). <br> - $3 E$ = Sensor average to E1 <br> - 4E = Sensor comparison to E1 <br> - 5E = Sensor difference to E1 <br> - 7E = Measurement value $=$ Measurement value e.g. for limit indication, display in Info menu "E2 Actual". <br> - 8E... 13E = sensor input for control circuit 2 base setup / operation with second control circuit. |

### 9.5.2 Setting for operation modes 5.01...5.02

5.01 Volume control, Setpoint in $\mathrm{m}^{3} / \mathrm{h}$
5.02 Volume control for ventilation systems setpoint depending on outdoor temperature

Settings for controller output with function 2 AA (by analogue signal 10 Setup, by MODBUS members menu).


| Setting | Maximal Speed <br> Setting range: 100 \%... "Min. Speed" Factory setting: $100 \%$ |
| :---: | :---: |
| $\begin{gathered} 100 \text { \% } \\ \text { Max. Speed } \end{gathered}$ |  |
| Setting | Manual mode <br> "OFF" = automatic control as function of the set parameters (Factory setting) <br> "ON" = automatic control without function, speed setting in menu "Speed manual" |
| OFF <br> Manual mode |  |
| Setting | Speed manual <br> Manual speed setting without influence by the external signal. <br> Activation by menu "Manual mode" or external contact at digital input ( IO Setup). <br> Setting range: $0 . . .100 \%$ 气 "Min. Speed"... "Max. Speed" <br> Factory setting: 100 \% |
| $100 \text { \% }$ <br> Speed manual |  |
|  |  |
|  | For information about deactivated regulation the adjusted value for manual speed is indicated alternating with the actual value. |

Additional menu item for mode 5.02 with outside-temperature dependent target-setpoint

Outside-temperature dependent target-setpoint


S1 Setpoint1
S2 Setpoint2
$P$-Min SA Minimum air volume
T-min Minimum temperature
T-Start Setpoint reducing will start below this outside temperature AT Outdoor temperature

An outside temperature compensation can be activated (sensor connection "E2" to "Analog In $2^{\prime \prime}$ ) when being operated as a air volume regulation device.
An optimal building climate, e.g., can be achieved through this. Through this function, the set and active Setpoint $1 / 2$ is automatically changed proportional to the measured outside temperature (Info: "Setpoint control").

| Setting | T-Band SA <br> Temperature range in which the setpoint change continiously with outside temperature <br> Setting range: $0.0 . .100 .0 \mathrm{~K}$ <br> Factory setting: 30.0 K |
| :---: | :---: |
| $\begin{gathered} 30.0 \mathrm{~K} \\ \text { T-Band SA } \end{gathered}$ |  |
| Setting | T-Start SA <br> Setpoint reducing will start below this outside temperature <br> Setting range: - $10.0 \ldots 40.0^{\circ} \mathrm{C}$ <br> Factory setting: $15.0^{\circ} \mathrm{C}$ |
| $\begin{gathered} 15.0^{\circ} \mathrm{C} \\ \text { T-Start SA } \end{gathered}$ |  |
| Setting | Min. Setpoint <br> Minimum pressure for very low outside temperature <br> Setting range: depending on measuring range of sensor and " $K$ factor" Factory setting: $700 \mathrm{~m}^{3} / \mathrm{h}$ |
| $700 \mathrm{~m}^{3} \mathrm{~h}$ <br> Min. Setpoint |  |

### 9.6 Air velocity control 6.01

### 9.6.1 Base setup 6.01

| Main menu | Base setup |
| :---: | :---: |
| Start <br> Setting <br> Protocol <br> Base setup <br> Controller Setup |  |
| Base setup <br>  <br> $\mathbf{6 . 0 1}$ <br> Mode | Mode <br> Mode selection 6.01 |
| Base setup <br> MAL1 <br> E1 Analog In | E1 Analog In <br> The sensor input is factory set for mode 6.01 to sensor type "MAL1". <br> Measuring range: $0 \ldots 1 \mathrm{~m} / \mathrm{s}$ <br> Output signal: 0-10 V <br> Connection terminals: "E1", "GND", " 24 V " <br> Other settable sensors / measuring ranges: <br> - MAL10 ( $0 \ldots . .10 \mathrm{~m} / \mathrm{s}$, output signal $0-10 \mathrm{~V}$ ) <br> - MAL15 * $(0 \ldots 15 \mathrm{~m} / \mathrm{s}$, output signal $0-10 \mathrm{~V})$ <br> - MAL20 * ( 0 ... $20 \mathrm{~m} / \mathrm{s}$, output signal $0-10 \mathrm{~V}$ ) <br> - 0-10 V, 0-20 mA, 4-20 mA (for sensors with free measuring range and linear characteristic) <br> The sensor measuring range must be entered for sensors with free measuring range in order to display the actual value correctly. <br> Example 0-10 V sensor and measuring range 0-5 M/s: <br> E1 Analog $\mathrm{In}=0-10 \mathrm{~V}, \mathrm{E} 1$ Unit $=\mathrm{m} / \mathrm{s}, \mathrm{E} 1$ Decimals $=1, \mathrm{E} 1 \mathrm{Min} .=0,0 \mathrm{~m} / \mathrm{s}, \mathrm{E} 1 \mathrm{Max} .=$ $5 \mathrm{~m} / \mathrm{s}$ <br> * Alternative measuring ranges which can be selected by jumpers for sensor type MAL10. |
| Base setup <br>  <br> $0.00 \mathrm{~m} / \mathrm{s}$ <br> E1 Offset | E1 Offset <br> Sensor calibration with calibrated comparison device. <br> The current "E1 Actual" is displayed including the offset set here. |
| Base setup <br> OFF <br> E2 Function | Adjustable "E2 Function" <br> - $1 \mathrm{E}=$ external setpoint e.g. by external signal $(0-10 \mathrm{~V})$ instead of setting "Setpoint $1 " .0-10 \vee 气 0-100 \%$ sensor measuring range. <br> - 2E = External manual operation via external signal (0-10 V). Switch over between settings on the device and external manual operation via digital input ( IO Setup: function 7D). <br> - 3E = Sensor average to E1 <br> - 4E = Sensor comparison to E1 <br> - 5E = Sensor difference to E1 <br> - 6E = sensor for outdoor temperature-dependent setpoint adaptation, preprogrammed sensor type "TF..". <br> - Menu group "Setting" additional parameter: T-Band, T-Start SA, Min. Setpoint. <br> - Menu group "Info" additional parameter: Setpoint control <br> - Example Setting for operation 4.01... 4.03 / additional menu items. <br> - 7E = Measurement value $=$ Measurement value e.g. for limit indication, display in Info menu "E2 Actual". <br> - 8 E ... 13 E = sensor input for control circuit 2 base setup / operation with second control circuit. |

### 9.6.2 Settings for operation modes 6.01

6.01 Air velocity control, Setpoint in m/s

Settings for controller output with function 2A (by analogue signal IO Setup, by MODBUS members menu).

| Main menu | Setting |
| :---: | :---: |
| Start <br> Setting <br> Protocol <br> Base setup <br> Controller Setup |  |
| Base setup <br> $0.50 \mathrm{~m} / \mathrm{s}$ Setpoint1 | Setpoint1 <br> Setting range: in measuring range of sensor Factory setting: $0.50 \mathrm{~m} / \mathrm{s}$ |
| Base setup ${ }^{\text {a }}$ (---- ${ }^{\text {Setpoint2 }}$ | Setpoint2 <br> Setting "Setpoint 2" e.g. reduced value for night operation. <br> Switch over Setpoint $1 / 2$ by external contact (display as long as no allocation is carried out: $\square$ IO Setup). |
|  | Pband <br> Narrow control range $=$ Short control times <br> Wide control range = Longer control times and more stable control <br> Setting range: in measuring range of sensor <br> Factory setting: $0.50 \mathrm{~m} / \mathrm{s}$ |
| Base setup $0 \text { \% }$ <br> Min. Speed | Min. Speed <br> Setting range: 0... "Max. Speed" Factory setting: 0 \% |
| Base setup $100 \%$ <br> Max. Speed | Max. Speed <br> Setting range: 100 \%... "Min. Speed" Factory setting: 100 \% |
| Base setup <br> OFF <br> Manual mode | Manual mode <br> "OFF" = automatic control as function of the set parameters (Factory setting) <br> "ON" = automatic control without function, speed setting in menu "Speed manual" |
| Base setup | Speed manual <br> Manual speed setting without influence by the external signal. <br> Activation by menu "Manual mode" or external contact at digital input ( IO Setup). <br> Setting range: $0 . . .100 \% \triangleq$ "Min. Speed"... "Max. Speed" <br> Factory setting: 100 \% <br> For information about deactivated regulation the adjusted value for manual speed is indicated alternating with the actual value. |
| 100 \% Speed manual |  |
|  |  |

### 9.7 Menu group Start

| Main menu | Start |
| :---: | :---: |
| Start <br> Settings <br> Protocol <br> Base setup <br> Controller Setup |  |
| Start | PIN input <br> The service menu for the installation can be protected against unintentional changes by a pin code. With further pin codes putting back to pre-setting is possible. |
| PIN input |  |
|  | PIN 0010 |
|  | Opening service menu, if PIN-protection activated. |
|  | PIN 1234 |
|  | Opening "setting". <br> if "set protection" = "ON" ( Controller Setup) |
|  | PIN 9090 |
|  | Restore user setting. |
|  | PIN 9091 |
|  | Save user setting (corresponds function "Save user setup" = "ON" Controller Setup) |
|  | PIN 9095 |
|  | Restore factory setting = delivery status |
|  | Exception: |
|  | The stored events in the "Protocol" menu are retained after resetting to factory setting! |
| Start | Language |
| GB <br> Language | Menu language by the factory set to English. In this menu different national languages can be selected ( $\mathrm{GB}=$ English, $\mathrm{D}=$ German ...). |
|  |  |
| OFF <br> US Einheiten | US Einheiten <br> The display can be switched between SI units and imperial (US) units =>US units ON. SI units (factory setting): ${ }^{\circ} \mathrm{C}$, bar, $\mathrm{Pa}, \mathrm{m}^{3} / \mathrm{h}, \mathrm{K}$-Factor, $\mathrm{m} / \mathrm{s}$ |
|  |  |
|  | Imperial (US) units: ${ }^{\circ} \mathrm{F}$, psi, in.wg, cfm, K-Faktor US, ft/s |
|  | Settings for temperature differences (with SI units in K ) are also made for Imperial units (US) in ${ }^{\circ} \mathrm{F}\left(\Delta 1.8^{\circ} \mathrm{F} \hat{=} \Delta 1 \mathrm{~K}\right)$. |
|  | Conversion factors: |
|  | - Temperature: $\mathrm{t} /{ }^{\circ} \mathrm{F}=1,8 \times \mathrm{t}^{\circ} \mathrm{C}+32$. |
|  | - Pressure: $1,0 \mathrm{psi}=0,069 \mathrm{bar}, 1,0 \mathrm{in} . \mathrm{wg}=254 \mathrm{~Pa}$ <br> - Air flow: $1,0 \mathrm{cfm}=0.5885 \mathrm{~m}^{3} / \mathrm{h}$, inlet ring: K-Factor US $=9,3 \times \mathrm{K}$-Factor SI |
|  | - Speed: $1.0 \mathrm{ft} / \mathrm{s}=0.3048 \mathrm{~m} / \mathrm{s}$ |
|  | In order to refresh the display, the desired mode must be confirmed again after switching over the units ( $\leftarrow$ Base setup)! |
| Start | Reset |
| OFF <br> Reset | Complete re-start of the device |
|  |  |
| Start | Mode <br> Query of the operating mode (e.g. 1.01 for speed controller) |
| 1.01 |  |
| Mode |  |
|  |  |


| Start | Device name |
| :--- | :--- |
| 9.15 <br> xxx |  |
| Display of device name and software version |  |
| Start |  |
| SN: $\mathbf{1 5 4 0 3 6 3 1 1 0 3 9}$ |  |
|  |  |

### 9.8 Menu group Info

The first menu item in the Info menu group is displayed (display dependent on selected mode) after switching on the line voltage or after exiting the setting menu with the Esc key combination.
Settings cannot be made in this menu group!


| Info | Display of the active target value at which the device operates. "Setpoint1" Menu "Setting" |
| :---: | :---: |
| $0^{\circ} \mathrm{C}$ <br> Setpoint1 |  |
|  | "Setpoint2" Menu "Setting" |
|  | "Ext. Setpoint" = setting by external signal 0-10 V. With activated manual mode the display constantly changes between actual value and value for manual mode. |
|  | Display for operation with two control circuits: |
|  | "1.Setpoint 1" or "1.Setpoint 2" for control circuit 1 |
|  | "2.Setpoint 1" or "2.Setpoint 2" for control circuit 2 |
| Info | Only for mode 4.02, 4.03, 5.02 with setpoint depending on outdoor temperature (E2 function $=6 \mathrm{E}]$. |
| 100.0 Pa Setpoint control |  |
| Info | Level modulation control output. In addition to the bar chart, the level of the output voltage is indicated. |
| $0 \%$ <br> Modulation |  |
|  | The modulation for each control circuit is displayed in operation with two control circuits: <br> "1. Modulation" for control circuit 1 <br> "2. Modulation" for control circuit 2 |
| Info | Momentarily status for minimum speed cut off |
| OFF <br> Min. speed cut off | "ON" = switch off, if Setpoint (+/- "Min. speed cut off") is reached. |
|  | "OFF" = no switch off that means operation with minimum rate of air. |
|  | Display for operation with two control circuits: |
|  | "1. Min. speed cut off" for control circuit 1 |
|  | "2. Min. speed cut off" for control circuit 2 |

### 9.9 Controller Setup

### 9.9.1 PIN protection activate, PIN 0010

| Controller Setup | The adjustments for the installation in the service level can be protected against <br> unintentional modifications. To do this, activate the "PIN protection" = "ON". <br> OFF <br> PIN Protection |
| :---: | :--- |
| In order to simplify the initial start-up operation, the service level in the factory setting is <br> free = "OFF" i.e. accessible without PIN 0010. |  |

## Available menu groups with activated PIN-protection

| Main menu |  |
| :--- | :--- |
| Start |  |
| Setting |  |
| Protocol |  |
|  |  |

If PIN-protection is switched on, it automatically becomes active after about 15 minutes without keys being pressed.

## Possibilities for early activation of PIN protection:

- Execute the "Reset" function in the "Start" menu group.
- By switching the mains voltage off and then on again.


## Information

After installation of the device has been carried out, "PIN-Protection" should be activated = "ON"

### 9.9.2 PIN protection activate, PIN 1234

| Controller Setup | The "Settings" menu for the user's basic settings (Setpoint, default value, min, max ..) |
| :---: | :--- |
| OFF | are freely accessible when using the factory settings (i.e. without "PIN"). <br> If necessary, these can also be protected against unauthorized modifications by using <br> a "PIN 1234". For this, the settings protection must be programmed to "ON". The <br> Set protection <br> settings menu is then no longer visible without inputting a PIN! |
|  | Function only in combination with activated PIN-Protection! |

Available menu groups with activated PIN-protection + setting protection

| Menu |  |
| :--- | :--- |
| Start |  |
| Protocol |  |
|  |  |

### 9.9.3 Save user settings restore with PIN 9090

| Controller Setup | The individually made device configurations (User Setting) can be saved here (corre- <br> Sponds to PIN 9091). <br> Save User Setup <br> By entering PIN 9090 the individually made device configurations can be reestablished <br> (C) Start - PIN Input). |
| :---: | :--- |
|  | A file (userconf.csv) is generated and saved on the main drive (root directory) when <br> saving the user setting. <br> The data can be accessed via the ZAset program. |

## Information

By entering the "PIN 9095" in the "PIN" menu of the "Start" menu group the device is reset to the asdelivered state (except for the saved events in the "Protocol"menu).
Any changes that have been made to the settings are thus lost.

### 9.9.4 Sensor Alarm ON / OFF

The inputs "E1 Analogue In" and if Sensor 2 is activated "E2 Analogue In" are monitored. In case of an interruption or short-circuit in the sensor conductor, or in case of measured values that lie outside of the device's measurement range, a time-delayed fault indication takes place.
Function only in controller mode (from 2.01)!

| Controller Setup | With "Alarm Sensors" = "ON" (factory setting). Indicated sensor disturbances are displayed as "Alarm" alternating to the actual value and stored in the menu of "Protocol". <br> A programmed alarm relay (factory setting relay K2) indicates the sensor failure. |  |
| :---: | :---: | :---: |
| ON <br> Alarm sensors |  |  |
| Controller Setup | With "AlarmSensors" = "OFF" areindicated sensor disturbances as "Message" alternating to the actual value and stored in the menu of "Protocol". |  |
| OFF <br> Alarm sensors |  |  |

### 9.9.5 Limit

| Controller Setup | After allocation of a digital input (GO IO Setup) an adjustable limitation of the modulation <br> can be activated via a digital input ("D1", "D2",..). <br> Display as long as no allocation has been carried out in "IO Setup": ---- |
| :---: | :--- |
| $-\ldots-$ | The limitation influences both outputs in operation with two control circuits. |
| Limit |  |

"Limit value" = max. possible modulation (e.g. speed reduction during night operation by time switch).
Setting range: "Limit" = "Min. Speed" to "Max. Speed".
Factory setting: $100 \%$ 气 max. modulation, i. e. no limit.

Setting depending on device tye in: \% or rpm.


Limit (idealized principle diagram)
MODBUS Out: speed setting over MODBUS
Analog Out: speed setting over analog output 0-10 V
L Limit
$S$ Setpoint
$R$ Pband
D Speed controller: setting signal
P P-controller: control deviation

### 9.9.6 Minimum speed cut off

| Controller Setup | This function is primarily significant for installation of the device as a pure P Controller <br> in refrigeration and air-conditioning technology. <br> OFF <br> Min. speed cut off |
| :--- | :--- |
|  | For operation mode speed controller $\mathbf{1 . 0 1}$ without function! |
|  | "isplay for operation with two control circuits: <br> "1. Min. speed cut off" for control circuit 1 <br> "2. Min. speed cut off" for control circuit 2 |

Msco = OFF (factory setting)
If no "Min. speed" is adjusted, the fan stops with reaching the desired value.
If "Min. speed" is adjusted (e.g. 20\%), then no disconnection of the fan takes place. I.e., always a minimum ventilation is ensured (fan does not go under setting "Min. speed").

## Msco. e.g. -2.0 K

It takes place a disconnection from setting "Min. speed"to " 0 ", if the given difference is reached related to the desired value.
At a plus value (+) before reaching the desired value At a minus value (-) after falling below the desired value.


Minimum speed cut off (idealized principle diagram)
MODBUS Out: speed setting over MODBUS
Analog Out: speed setting over analog output 0-10 V
S Setpoint
$R$ Pband
$R$
$l$
$I$ Actual value

### 9.9.7 Reverse action of the control function

| Controller Setup | For the effect of the regulation there are two functions: <br> - ON for "Val>Set=n+" $\triangleq$ increasing Fanlevel for increasing actual value over Setpoint. <br> - OFF for "Val>Set=n+" $\xlongequal{\wedge}$ increasing Fanlevel for decreasing actual value below Setpoint. <br> Display for operation with two control circuits: <br> "1. Actual>Set=n" for control circuit 1 <br> "2. Actual>Set=n" for control circuit 2 <br> For special applications an external switch over of the control function is possible (a) IO Setup). |
| :---: | :---: |
| $\underset{\text { Val>Set=n+ }}{\text { ON }}$ |  |
|  |  |
|  |  |


| Factory setting depending on selected mode |  | Example for temperature control (Idealized principle diagram) |
| :---: | :---: | :---: |
| Mode | Controller function |  |
| 1.01 | non | $\frac{0}{2} \stackrel{\circ}{2}_{4}^{4}$ |
| 2.01... | ON | $\square$ |
| 3.01... | ON |  |
| 4.01 | OFF | 全 |
| 5.01... | OFF | $\begin{aligned} & 50-\infty \\ & 50 \\ & 50 \end{aligned}$ |
| 6.01... | OFF |  <br> MODBUS Out: speed setting over MODBUS <br> Analog Out: speed setting over analog output 0-10 V <br> $R$ Pband <br> $S$ Setpoint <br> 1 Actual value <br> OFF for Val>Set=n+ = heating function <br> ON for Val>Set=n+ = cooling function |

### 9.9.8 Controller configuration

The "controller configuration" is automatically carried out during selection of the application related mode of operation (Base setup). The factory presets in accordance with the mode of operation are based on many years of experience, which is suitable for many applications. Under special circumstances, these can be individually adapted ( $\square_{\circ}^{\circ}$ Menu group "setting").

| Controller Setup | The type of control determines the method with which the controlled value behaves in case of a difference between the target and current values. For this, the control |
| :---: | :---: |
|  | technology has standard algorithms, which consist of a combination of three methods: |
| Type of control | Selection P, PID: |
|  | - P control (Proportional component, proportion of the absolute deviation) |
|  | - D control (Differential component, proportion of the last difference) |
|  | Display for operation with two control circuits: |
|  | "1.Controller type" for control circuit 1 |
|  | "2.Controller type" for control circuit 2 |
| With pure P controllers (controller type $\mathbf{P}$ ), the following described settings do not have any function. If needed, the most suitable combination for the respective control system can be determined from these proportions. |  |
| The control configur Fine adjustment is p | (KP, KI, KD, TI) is identical for both control circuits in operation with two control circuits ble for each control circuit by the separate "Pband" setting. |


| Controller Setup | P-component = reaction time <br>  <br> $\mathbf{5 0} \%$ <br> KP |
| :---: | :--- |
| Setting range: 0-200 \% |  |
| smaller = more slowly |  |
| bigger = faster |  |

### 9.9.9 Group control

Fan groups can be activated by the analogue outputs "A1" and "A2", the relay outputs "K1" and "K2" or by the RS-485 interface for MODBUS RTU.

| Controller Setup | Setting range $0 / 1$ |
| :---: | :--- |
|  | Following group versions are available: |
| $\mathbf{0}$ | - $\mathbf{0}$ : One controlled group and up to three switched groups (factory setting) |
| Group version | - 1: Two controlled groups |

## Group control via analogue outputs and relays

- The groups must be connected at the appropriate programmed output when activating by the analogue outputs and relays.
- The assignment of the analogue outputs and the relays for the group control takes place in the IO Setup.
- The number of possible groups depends on the available hardware outputs in the MODBUS Master (maximum of 4 groups possible).


## Group control im MODBUS Master Operation

- If controlling via MODBUS, an individual function can be programmed for each group device.
- The virtual outputs are assigned after the menu group "MODBUS Master" for the respective component "fan 1 ".."fan $x$ ".
- The number of possible groups does not depend on the available hardware outputs in the MODBUS Master (maximum of 4 groups possible).

Group functions (IO Setup)

| Analog output A1, A2 MODBUS A1, A2 | $\begin{aligned} & \frac{2 \mathrm{~A}}{2 \mathrm{~A}}=\text { Group } 1 \\ & =\text { Group } 2 \end{aligned}$ |
| :---: | :---: |
|  | 11A |
|  | 12A $=$ Group 4 |
| Relay output K1, K2 | $\begin{aligned} & 8 \mathrm{~K}=\text { Group } 2 \\ & 12 \mathrm{~K}=\text { Group } 3 \end{aligned}$ |
|  | 13K $=$ Group 4 |

## Information

- Group activation by analogue output, relay and MODBUS can also be combined.
- Ensure an ascending and complete sequence when assigning the groups. This means that if, for example, the function for a fourth group was assigned for an output, there must already be an assignment for groups 2 and 3 (O Setup).
- The group control only becomes active once a group function is allocated to an output (analogue, relay, MODBUS).
9.9.9.1 Variant " 0 ": One controlled group and up to three switched groups

The programming described below applies equally for group control by analogue outputs, relay outputs and MODBUS.
For group control by the analogue outputs "A1" / "A2" and the relay outputs "K1" and "K2", the available outputs must be observed in the selection of the version (combinations are possible).

## Example: Required assignment for a controlled and a switched group

- For activation by analogue output (IO Setup) or MODBUS (MODBUS Master)
- Function Afor group 1 (0-100 \% controlled)
- Function 5A for group 2 (0 / $100 \%$ switched)
- For activation of Group 2 by relay ( IO Setup)
- Function Afor group 1 (0-100 \% controlled)
- Function 8K for group 2 (ON / OFF switched)

The function 11 A must be allocated additionally to Group 3 for one controlled and two switched groups.
The function 12 A must be allocated additionally to Group 4 for one controlled and three switched groups.

| Controller Setup | Group 2 ON value |
| :---: | :---: |
| $50 \%$ Group 2 ON value | Switch-on value for Group2 <br> Setting range: 0-100 \% <br> Factory setting: 50 \% * |
| Controller Setup | OFF Value Group2 |
| $45 \%$ OFF Value Group2 | Switch-off value for group2 Setting range: 0-100\% Factory setting: $45 \%$ * |
| Controller Setup | $n \mathrm{~min}$ at Group2 |
| $\begin{gathered} 20 \text { \% } \\ \text { nmin at Group2 } \end{gathered}$ | Minimum Value for Group2 <br> Setting range: 0-100\% <br> Factory setting: 20 \% * |
| Controller Setup | Group 3 ON value |
| $\begin{gathered} 70 \% \\ \text { Group } 3 \text { ON value } \end{gathered}$ | Switch-on value for Group3 Setting range: 0-100\% Factory setting: $70 \%$ * |
| Controller Setup | OFF Value Group3 |
| $65 \%$ OFF Value Group3 | Switch-off value for group3 <br> Setting range: 0-100\% <br> Factory setting: 65 * |
| Controller Setup | nmin at Group3 |
| $\begin{gathered} 30 \% \\ \text { nmin at Group3 } \end{gathered}$ | Minimum Value for Group3 Setting range: 0-100\% Factory setting: 30 \% * |
| Controller Setup | Group 4 ON value |
| $\begin{gathered} 85 \% \\ \text { Group } 4 \text { ON value } \end{gathered}$ | Switch-on value for Group4 Setting range: 0-100\% Factory setting: $85 \%$ * |


| Controller Setup | OFF Value Group4 Switch-off value for group4 Setting range: 0-100 \% Factory setting: 80 \% * |
| :---: | :---: |
| 80 \% |  |
| OFF Value Group4 |  |
| Controller Setup | nmin at Group4 |
| 40 \% | Setting range: 0-100\% |
| nmin at Group4 | Factory setting: 40 \% * |

* Display as long as no group assignment via analogue output, relay, MODBUS: $\square$
Higher settings must be selected for following groups and the switch-off value of the group must be below the switch-on value.


## Example version "0" via MODBUS



On controlled group and three switched groups


MODBUS Out: speed setting over MODBUS
S: Modulation level of the controller in \%
G1: Group 1
G2: Group 2
G3: Group 3
G4: Group 4
G2, G3, G4 ON: ON Value Group2, 3, 4
G2, G3, G4, OFF: OFF Value Group2, 3, 4
nmin@G 2, 3, 4: nmin at Group2, 3, 4
MODBUS Out Standard: Diagram wihout group control

## Function

Group 1 is continuously controlled ( $0-100 \%$ ), the other groups are switched on and off depending on the degree of modulation ( $0 / 100 \%$ ).
If the modulation level exceeds the switch-on point "ON Value Group2", the MODBUS Master switches on the second group and the speed of the first group is reduced to an adjustable minimal value "nmin at Group2".
Then the speed of the first group increases to maximum within the remaining range.
If a third group is programmed up to switch-on point "ON Value Group3" etc.
Switch-off point "OFF Value Group2" at diminishing speed requirement.

| Controller Setup | Group 2 ON value |
| :---: | :---: |
| $50 \%$ Group 2 ON value | Setting range: 0-100\% Factory setting: 50 \% * |
| Controller Setup | OFF Value Group2 |
| $45 \text { \% }$ <br> OFF Value Group2 | Setting range: 0-100\% <br> Factory setting: 45 \% * |
| Controller Setup | nmin at Group2 |
| $\begin{gathered} 20 \% \\ \text { nmin at Group2 } \end{gathered}$ | Minimum Value for Group2 <br> Setting range: 0-100 \% <br> Factory setting: 20 \% * |

* Display as long as no group assignment via analogue output, relay, MODBUS: - ---

Example version "1": Two controlled groups

9.9.10 Display text for external message

| Controller Setup | Alternatively to the "External Error" display when an external message occurs (Ls IO |
| :--- | :--- |
|  | Setup / Digital Inputs "D1" / "D2" the following error texts can be programmed: |
| External error | - EC Motors |
| External message | - Filter |
|  | - Frost protection |
|  | - Adiabatik |
|  | - Firealarm |
|  | - Pressure switch |
|  | - Gas alarm |
|  | - Water alarm |
|  | - RCD |
|  |  |

### 9.9.11 Offset control signal

| Controller Setup | Offset control sig. $\mathbf{1}$ |
| :--- | :--- |
| If required, the characteristic of the control signal for control circuit 1 can be adjusted. <br> Offset control sig. $\mathbf{1}$ | To activate this function, re-program the output with function 2A to function 14A. <br> IO Setup. |
|  | Setting range: $0-50 \%$ |
|  | Factory setting: $0 \%$ (characteristic curve unchanged) |


9.9.12 Selection amplifier (comparator) control circuit 1 or 2 at output A1

| Controller Setup | If using two control circuits, the control circuit with the higher modulation can be <br> selected to affect the power component of the device. <br> OFF <br> Selection amplifier |
| :--- | :--- |
| This function can be used for refrigeration systems with combined refrigerant circuit |  |
| and floating brine pressure control circuits, for example. |  |
|  | Example: <br> - |
|  | Control circuit 1 is used for the refrigerant circuit. A pressure sensor is connected to <br> determine the actual value. The setpoint and control range are set in bar. <br> - Control circuit 2 is used for the brine pressurised circuit. A temperature sensor is <br> connected to determine the actual value. The setpoint and control range are set in <br> Co / K. <br> -Depending on which control circuit produces the higher modulation (depending on <br> the measured and set values), the pressure control or temperature control is used as <br> a specification for the power component. <br>  <br>  <br>  <br> Selection amplifier = OFF (factory setting) <br> No comparison of the two control circuits. <br> Selection amplifier = ON <br> Comparison of the modulation of control circuit 1 and control circuit 2 with automatic <br> control active at the highest value. |



### 9.9.13 Data on the total control deviation

The total control deviation is comprised of the sum of the control deviations for performance quantities and work quantities combined and refers to the specified areas.
In direct reference to the acquired input and controlled variables, the maximum deviation to the target value is $< \pm 5 \%$. By activating the menu-assisted adjustment, the total control deviation can be reduced to a value of $< \pm 1 \%$.
For indirect reference of the acquired input value to the controlled variable, i.e., two physical variables still need to be converted, the deviation can be reduced to < $\pm 5 \%$ through adjustment.
In the case of an internal default value through the integrated or external terminal, the control deviation remains at $< \pm 0.5 \%$.

### 9.10 IO Setup

### 9.10.1 Analog outputs "A1"/ "A2"

| IO Setup | The analog outputs 0-10 V (A1 and A2) can be allocated with various functions. |
| :---: | :---: |
| 1. Control signal (2A) <br> A1 Function |  |
| IO Setup | With the settings "A1 min." / "A2 min." and "A1 max." / "A2 max." the characteristic of the output voltage can be adapted. |
| $\begin{gathered} 0.0 \mathrm{~V} \\ \Delta 1 \mathrm{~min} \end{gathered}$ | Setting range: <br> "A1 min." / "A2 min." = 0-10 V <br> "A1 max." / "A2 max." = 0-10 V |
|  |  |
| IO Setup |  |
|  | Factory setting: <br> "A1 min." / "A2 min." = 0 V <br> "A1 max." / "A2 max." = 10 V |
| 10.0 V |  |
| A1 max. |  |
|  | The setting for "A1 min." / "A2 min." must be below "A1 max." / "A2 max.". |


| IO Setup | Inverting of the output voltage is possible with the settings "A1 Inverting" / "A2 <br> OFF <br> A1 Inverting |
| :---: | :--- |
| Inverting". |  |
| Factory setting: Inverting = "OFF" |  |


| Function | Description |
| :---: | :---: |
| OFF | no function |
| Constant voltage 10 V | Constant voltage +10 V |
| (1A) | Factory setting for "A2" at operation with one control circuit. |
| 1st control signal (2A) | Controlled 0-10 V output for control circuit 1 (factory setting for "A1") |
| $\begin{gathered} \text { E1 } \\ (3 A) \end{gathered}$ | proportional input "E1" |
| $\begin{gathered} \text { E2 } \\ \text { (4A) } \end{gathered}$ | proportional input "E2" |
| Group2 <br> (5A) | Group control (\% Controller Setup - group 2) |
| 2.Cooling (6A) | Only for mode 2.03 temperature controller with additional functions. Controller output 2 with rising activation at Actual>Nominal $=$ Cool. |
| 2.Heating (7A) | Only for mode $\mathbf{2 . 0 3}$ temperature controller with additional functions. Controller output 2 with rising activation at Actual<Nominal = Heat. |
| 2. control signal (8A) | Controlled 0-10 V output for control circuit 2 (factory setting for "A2" at operation with second control circuit). |
|  | Control circuit 2 can be activated by programming the E2 function if required (Base setup / operation with second control circuit). |
| Speed <br> (9A) | proportionally 1.Control signal |
| Group3 (11A) | Group control ( Controller Setup - group 3) |
| Group4 (12A) | Group control ( Controller Setup - group 4) |
| Offset control sig. 1 (14A) | Offset control signal 1 <br> Setting offset Controller Setup |

"A1 min." / "A2 min." and "A1 max." / "A2 max."


Function 3 A$] / 4 \mathrm{~A}$


### 9.10.2 Digital inputs "D1" / "D2"

### 9.10.2.1 Menu overview

| IO Setup | Possible functions for D1 following table. |
| :---: | :---: |
| OFF <br> D1 Function |  |
| IO Setup | To invert the function, switch to "ON" (display $\square$ as long as no function is allocated for D1). |
| OFF <br> D1 Inverting |  |
| IO Setup | With networking the digital inputs can be replaced by control over bus (Slave interface 2A/2B). <br> With mode of operation 4.03 pre-setting of "D1" is ON. <br> If bus mode is at ON , the digital input can be set by coil register c 0 for D 1 . |
| ON <br> D1 Busmode |  |
| IO Setup | Possible functions for D2 following table. |
| OFF <br> D2 Function |  |
| IO Setup | To invert the function, switch to "ON" (display $\square$ as long as no function is allocated for D2). |
| OFF <br> D2 Inverting |  |
| IO Setup | With networking the digital inputs can be replaced by control over bus (Slave interface 2A/2B). <br> With mode of operation 4.03 pre-setting of " D 2 " is ON . <br> If bus mode is at ON , the digital input can be set by coil register c 1 for D 2 . |
| ON <br> D2 Busmode |  |
| IO Setup | If the digital inputs have the same function allocation (also applies for timer function) you can choose between an AND and OR operation. |
| D-D Relation | OR operation (factory setting). The function becomes active when one of the digital inputs or the timer is activated. |
|  | AND operation. The function becomes active when all digital inputs or also the timer are activated. |


| Function | Description |
| :---: | :--- |
| OFF | No function (factory setting) |
| Enable <br> (1D) | Enable (remote control) "ON" / "OFF" |
| External error <br> (2D) | External fault alarm |
| Limit <br> (3D) | "Limit" ON / OFF |
| E1 / E2 <br> (4D) | Switch over input "E1" / "E2" (for operation with one control circuit) |
| Reset <br> (10D) | Complete re-start of the device |


| Max. Speed (11D) | Setting Max. Speed "ON" / "OFF" <br> Influences the respectively set value "1. Max. Speed" and "2. Max. Speed" in operation with two control circuits. |
| :---: | :---: |
| Override Time (21D) | Overwrite timer function (in operation with timer) <br> The timer output is overwritten for a settable time with a selectable status (ON / OFF). |
| For Mode Speed controller 1.01 |  |
| Setpoint1/2 (5D) | Switch over "Set Intern1" / "Set Intern2" <br> "Setting External 1" must be at "OFF". |
| Setpoint int./ext. <br> (6D) | Switch over "Intern" / "Extern" |
| For modes as controller (from2.01.) |  |
| Setpoint1/2 <br> (5D) | Switch over "Setpoint 1" / "Setpoint 2"for control circuit1 |
| Setpoint int./ext. <br> (6D) | Switch over "Intern" / "Extern" <br> Possible only for operation with one control circuit! |
| Control/Manual (7D) | Switch over "automatic control" / "Speed manual" Possible only for operation with one control circuit! |
| Heating/Cooling (8D) | Switch over control function (e.g. "heating" / "cooling") |
| 1.Setp+Pband1/2 <br> (15D) | for control circuit 1: Switch over Setpoint 1/2 and Pband 1/1 When programming this function, "Setting" additionally lists the parameter: "1.Pband2 for control circuit 1." |
| Only active in operation with a second control circuit! |  |
| $\begin{gathered} \text { E1 / E2 } \\ \text { (4D) } \end{gathered}$ | The output for control circuit 2 is set additionally to "A2" to "A1" (regardless of the programmed function for " A 1 "). Control circuit 1 has no output for the duration of the switching. <br> The switch over input "E1" / "E2" as in operation with one control circuit is no longer possible. |
| 2. Setpoint 1/2 (9D) | for control circuit 2: Switch over "2. Setpoint 1" / "2. Setpoint 2" |
| 2.Setp+Pband1/2 (16D) | for control circuit 2: Switch over Setpoint $1 / 2$ and Pband 1/2 <br> When programming this function, "Setting" additionally lists the parameter: " 2 Pband2 for control circuit 2." |

### 9.10.2.2 Enable ON/OFF function 1D

Remote ON/OFF by potential-free contact.
Activation of the members (speed setting) by analogue output and MODBUS interface is switched off, the other signal inputs and outputs stay active.
The device can still be operated in the switched-off state after pressing the "Esc" key combination.

- A programmed operating indicator relay (factory set "K1 function" = 1 K ) reports the switch-off.
- A programmed alarm relay (factory set "K2 function" $=2 \mathrm{~K}$ ) does not report the switch-off.


[^2]
### 9.10.2.3 External message, Function 2D

Connecting an external alarm indication (via floating contact). The device continues to work unchanged during an external indication to the digital input; the alarm symbol appears in the display. This indication can be issued via the relay contacts (K1 K2) (IO Setup function K1, K2).

| Info - Indication during closed contact (factory setting): "D1 Inverting" = "OFF " |  |
| :---: | :---: |
| $5$ | Alternative display texts for error message Controller Setup / display text for external message. |
| External error |  |
| Display alternating with actual value display |  |

9.10.2.4 Limit ON / OFF, Function 3D

The value for "Limit" adjusted in the Controller Setup, is activated over a digital input.
Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1"or "D1" "24 V").
For "D1 Inverting" = "OFF", limitation active at closed contact.
The limitation influences both outputs in operation with two control circuits.


1 Setting "Limit" (depending on device type in: \%, Hz, rpm)

### 9.10.2.5 Switch over input "E1" / "E2", function 4D

## (operation with one control cicuit)

Switch over between Input signal 1 (Analog In 1 terminal "E1") and input signal 2 (Analog In 2 terminal "E2").
Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1"or "D1" "24 V").


Si 1 Signal 1
Si 2 Signal 2
For mode speed controller (1.01) Base setup for "E2 Analog In": 1E necessary.
For modes controller (from 2.01 ..) Base setup for "E2 Analog In": 7E necessary (as far as otherwise does not occupy).
9.10.2.6 Output control circuit 2 additional to "A2" on "A1", function 4D

The output for control circuit 2 is set additionally to "A2" to "A1" (regardless of the programmed function for A1). Control circuit 1 has no output for the duration of the switching.
Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1"or "D1" "24 V").
At "D1" Inverting "OFF" the output of control circuit 2 also influences output "A1" when the contact is closed.

9.10.2.7 Set $1 / 2$ or Setpoint 1/2, Function 5 D ]

For Mode Speed controller 1.01: Switch over "Set Intern1" / "Set Intern2"
Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1"or "D1" " 24 V").


1 Setting "Set Intern1", (depending on device type in: \%, Hz, rpm)
2 Setting "Set Intern2" (depending on device type in: \%,Hz, rpm)

- "D1 Inverting" = "OFF": "Set Intern1" at opened contact / "Set Intern2" at closed contact.
- "D1 Inverting" = "ON": "Set Intern1" at closed contact / "Set Intern2" at opened contact.

| Info | Operation with "Set Intern2" is signalized by the moon symbol for reduced operation. "Set extern1" under "settings" must be programmed to "OFF". |
| :---: | :---: |
| $50 \%$ <br> Modulation |  |

For operation as controller (starting from 2.01): switch over "Setpoint 1" | "Setpoint 2" For operation with second control circuit: switch over "1.Setpoint 1" / "1.Setpoint 2"

Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1"or "D1" "24 V").


- "D1 Inverting" ="OFF": "Setpoint1" = $18^{\circ} \mathrm{C}$ at opened contact / "Setpoint2" $=25^{\circ} \mathrm{C}$ at closed contact.
- "D1 Inverting" = "ON": "Setpoint1" = $18^{\circ} \mathrm{C}$ at closed contact / "Setpoint2" $=25^{\circ} \mathrm{C}$ at opened contact.


### 9.10.2.8 Intern / Extern Function 6D

For Mode Speed controller 1.01: Switch over "Set Intern" / "Set external "
"Set extern1" under settings must be programmed to "OFF".
Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1"or "D1" " 24 V").


- "D1 Inverting" = "OFF": "Set Intern1" at opened contact / "Setting Extern" at closed contact.
- "D1 Inverting" = "ON": "Set Intern1" at closed contact / "Set Extern" at opened contact.

For operation as controller (starting from 2.01): switch over "Setpoint 1" / "external Setpoint " Possible only for operation with one control circuit!
Under Base setup "E2 function" programmed to function 1E for "external setpoint" .
Contact at digital input e.g. "Digital In 1" = "D1" - "D1"


1 Setting "Setpoint1"
ES External Setpoint e.g. $5 \mathrm{~V} \triangleq 23.8^{\circ} \mathrm{C}$
Se Sensor

- "D1 Inverting" = "ON": Setting at the unit at opened contact / Signal Extern at closed contact
- "D1 Inverting" = "OFF": Setting at the unit at closed contact / Signal Extern at opened contact


### 9.10.2.9 Automatic control / speed manual Function 7D (mode 2.01)

Possible only for operation with one control circuit!
Switch over between automatic control to set target value (depending on the activation: "Setpoint1", "Setpoint2") and the default for "manual operation" set at the device.
If for Analog In 2 "E2 function" is programmed to 2E switch over between "Setpoint1" or "Setpoint2" and external manual operation. With activated manual mode the display constantly changes between "actual value" and value for "manual mode".
Contact at digital input e.g. "Digital In 1"


1 Setting "Setpoint1"
2 Setting "Setpoint2"
3 Setting "Speed manual" (depending on device type in: \%, Hz, rpm)
EH Signal for Manual mode extern, E2 Function $=2 E$
Se Sensor

- "D1 Inverting" = "OFF" Automatic control at opened contact / manual operation at closed contact.
- "D1 Inverting" = "ON": Automatic control at closed contact / manual operation at opened contact.
9.10.2.10 Reverse action of control function (2.01), Function 8D

Switchover between: Increasing modulation during increasing actual-value and increasing modulation during sinking actual-value.
The factory presets for the "Control function" are dependent on the selected mode of operation ( Controller Setup - reverse operation of the control function).
When switching over via a digital input, the device works with the opposite function as set there.
The inversion of the control function influences both circuits in operation with two control circuits.

| Controller Setup | Settings in Controller Setup <br> ON <br> Val>Set=n+ |
| :---: | :--- | | Display for operation with two control circuits: |
| :--- |
| "1. Actual>Set=n" for control circuit 1 |
| "2. Actual>Set=n" for control circuit 2 |

9.10.2.11 Switch over Setpoint $1 / 2$ for control circuit 2 9D

Switch over between "2.Setpoint 1" and "2.Setpoint 2" (for operation with two control circuits)
Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1"or "D1" " 24 V ").


- "D1 Inverting" = "OFF": "2. Setpoint 1" = $18^{\circ} \mathrm{C}$ at opened contact / " 2 . Setpoint 2 " $=$ $25^{\circ} \mathrm{C}$ at closed contact.
- "D1 Inverting" = "ON": "2. Setpoint 1" = $18^{\circ} \mathrm{C}$ at closed contact / "2. Setpoint 2 " $=$ $25^{\circ} \mathrm{C}$ at opened contact.

| Info | Operation with " 2 . Setpoint2" is signalized by the moon symbol for reduced operation. |
| :---: | :---: |
|  | input with function 5D, the moon symbol is already switched on. |
| $28.7^{\circ} \mathrm{C}$ <br> E2 Actual |  |

9.10.2.12 Setting Max. Speed ON / OFF function 11D

The value for "Max Speed" adjusted in menu "Settings", is activated over a digital input. I.e. the unit works independently of the controller function firm with this value.
Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1"or "D1" "24 V").
This function influences both circuits in operation with two control circuits.


Display depending on device type in: \%, Hz, rpm
1 Setting "Max. Speed" or "1.Max. Speed" and "2.Max. Speed" for operation with two control circuits

- "D1 Inverting" = "OFF": "Max. Speed" active at closed contact
- "D1 Inverting" ="ON": "Max. Speed" active at opened contact
9.10.2.13 Switch over Setpoint $1 / 2$ and Pband 1/2 for control circuit 1 15D

Switching between "1st setpoint 1" / "1st setpoint 2" and "1st Pband 1" / "1st Pband 2" (from 2.01, not for 2.03).
Function basically the same as 5D, it is additionally switched over to Pband 2.
When programming this function, "Setting" additionally lists the parameter: "1.Pband 2 for control circuit 2."
Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1"or "D1" "24 V").
Example for "D1 Inverting" = "OFF":

- With open contact: "1.Setpoint $1^{"}=20^{\circ} \mathrm{C}+$ "1.Pband 1 " $=5 \mathrm{~K}$
- With closed contact: "1.Setpoint 2" $=17^{\circ} \mathrm{C}+$ "1.Pband $2 "=3 \mathrm{~K}$

1.Setpoint1 Setting "1.Setpoint 1" = Setpoint 1 of control circuit 1
1.Pband1 Setting "1.Pband 1" = Pband 1 von control circuit 1
1.Setpoint2 Setting "1.Setpoint 2" = Setpoint 2 of control circuit 1
1.Pband2 Setting "1.Pband 2" = Pband 1 von control circuit 1

| Info | Operation with "1.Setpoint2" and "1.Pband2" is signalized by the moon symbol for reduced operation. |
| :---: | :---: |
| $\begin{gathered} 28.7^{\circ} \mathrm{C} \\ \text { E1 Actual } \end{gathered}$ | If Setpoint 2 was activated additionally for control circuit 1 or control circuit 2 by a digital input with function 5D / 9D the moon symbol is already switched on. |
|  | If Setpoint 2 and Pband 2 were activated additionally for control circuit 2 by a digital input with function 16D, the moon symbol is already switched on. |

9.10.2.14 Switch over Setpoint $1 / 2$ and Pband $1 / 2$ for control circuit 2 16D

Switch over between "2.Setpoint 1" / "2.Setpoint 2" and "2.Pband 1" / "2.Pband 2" (only for operation with second control circuit possible).
Function basically the same as 5D and 9D, it is additionally switched over to Pband 2.
When programming this function, "Setting" additionally lists the parameter: "2Pband2 for control circuit 2."

Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1"or "D1" "24 V").
Example for "D1 Inverting" = "OFF":

- With open contact: "2.Setpoint $1^{\prime \prime}=20^{\circ} \mathrm{C}+$ "2.Pband $1 "=5 \mathrm{~K}$
- With closed contact: "2.Setpoint 2 " $=17^{\circ} \mathrm{C}+$ "2.Pband 2 " $=3 \mathrm{~K}$

2.Setpoint1 Setting "2.Setpoint 1" $=$ Setpoint 1 of control circuit 2
2.Pband1 Setting "2.Pband 2" $=$ Pband 1 von control circuit 2
2.Setpoint2 Setting "2.Setpoint 2" = Setpoint 2 of control circuit 2
2.Pband2 Setting "2.Pband 2" $=$ Pband 2 von control circuit 2

| Info | Operation with " 2 .Setpoint2" and " 2 .Pband2" is signalized by the moon symbol for reduced operation. |
| :---: | :---: |
| $28.7^{\circ} \mathrm{C}$ | If Setpoint 2 was activated additionally for control circuit 1 or control circuit 2 by a digital input with function 5D / 9D the moon symbol is already switched on. |
| 2 Actua | If Setpoint 2 and Pband 2 was activated additionally for control circuit 1 by a digital input with function 15D, the moon symbol is already switched on. |

### 9.10.2.15 Timer function overwrite 21D

The timer output can be overwritten for a settable time with a selectable status if required ( To overwrite the timer function by pressing keys until the next timing change => "Override Time" = 0 min.
The override time is activated by pressing a key at a digital input (example for D1 not inverted). The bypass time can be ended prematurely by pressing another key.
If the contact remains closed, the override time also run out, then a short interruption is required to reactivate.


Contact depending on device type at terminals "D1" - "D1" or "D1" - "24 V"
Example: speed limitation over Timer (Function 3D)
The timer limits the maximum speed for a certain period of time (e.g. timer ON from 6:00-10:00 am). With the "Override Timer" contact the limitation (from 6:00-10:00 am) activated by the timer can be cancelled for an adjustable period "Override Time" (timer / timer function overwritten: Override Status = OFF)
To activate the limitation outside the programmed time (10:01-5:59 am ) => "Override Status" = ON

### 9.10.3 Configuration of analog inputs "E1"and "E2"

### 9.10.3.1 Signal adaption E1 and E2

If required, an adaptation of the specification signal / speed characteristic curve is possible

## Information

Setting options depending on the version of the software available!
These settings are mostly practical for the operating mode with rotational speed specification over an external signal. In operating modes (as of 2.01) this setting is not suited for influencing the regulation process.

| IO Setup |  |
| :---: | :---: |
| $\begin{gathered} 0 \\ \text { E1 Modus } \end{gathered}$ | E1 Modus <br> 0 = E1 min. / E1 max. without function (factory setting) <br> 1) = Offset / turn <br> 2 = signal range <br> 3 = Hysteresis setting On / Off (function depending on the version of the software available) |
| IO Setup |  |
| $\begin{gathered} 0 \text { \% } \\ \text { E1 Min. } \end{gathered}$ | E1 Min. <br> Setting range: 0-100 \% <br> Factory setting: 0 \% |
| IO Setup |  |
| $\begin{gathered} 0 \% \\ \text { E1 max } \end{gathered}$ | E1 max Setting range: 0-100 \% Factory setting: $100 \%$ |
| IO Setup |  |
| $\begin{gathered} 0 \\ \text { E2 Mode } \end{gathered}$ | E2 Mode <br> 0 = E2 min. / E2 max. without function (factory setting) <br> 1 = Offset / turn <br> 2 = signal range |
| IO Setup |  |
| $\begin{gathered} 0 \% \\ \text { E2 min. } \end{gathered}$ | E2 min. <br> Setting range: 0-100 \% <br> Factory setting: 0 \% |
| IO Setup |  |
| $\begin{gathered} 0 \% \\ \text { E2 max. } \end{gathered}$ | E2 max. <br> Setting range: 0-100 \% <br> Factory setting: 100 \% |

Example for Mode " 1.01 " with speed setting signal 0-10 V


## Modus 1

Example: "E1 min." = 20 \%
The controller begins only at approx. 20\% higher signal with minimal modulation.

Example: "E1 max." = 80 \%
The modulation rises linear to $100 \%$ modulation with $80 \%$ setting signal.

## Modus 2

Example: "E1 min." = 30 \%
Only with approx. 30 \% setting signal the controller begins with approx. $30 \%$ modulation.

Example: "E1 max." = 80 \%
Over $80 \%$ setting signal the modulation is switched to $100 \%$ modulation.

## Modus 3

Example: "E1 min." = 30 \%, "E1 max." = 80 \% Over approx. $80 \%$ setting signal the modulation is switched on.
Below approx. 30 \% setting signal the modulation is switched off.

For a correct function: E1 min. higher 0 \% and E1 max. below 100 \%.
example 2 and 3 only for information.

Idealized principle diagrams for setting:
"Min. Speed" $=0 \%$ and "Max. Speed" $=100 \%$

### 9.10.3.2 Inverting analog inputs "E1" / "E2"

After programming the signal or sensor type, an inversion of the inputs can be carried out.

| IO Setup | Factory setting for Inverting inputs = "OFF" (if input activated) (signal: 0-10 V, 0$20 \mathrm{~mA}, 4-20 \mathrm{~mA}$ ). <br> For activation using inverted default signals or sensors with inverted output signals proportional to the measurement range, switch inverting to "ON" (Signal: 10-0 V, 20 $0 \mathrm{~mA}, 20-4 \mathrm{~mA}$ ). |
| :---: | :---: |
| OFF <br> E1 Inverting |  |
| IO Setup |  |
| OFF <br> E2 Inverting |  |

Example: mode 1.01 speed controller, setting by external signal


MODBUS Out: speed setting over MODBUS
Analog Out: speed setting over analog output 0-10 V
Si Signal
OFF Inverting = OFF
ON Inverting $=O N$

### 9.10.3.3 "E1" / "E2" Bus mode

After programming the signal or sensor type, the raw value (0-32767) of an analog sensor input can be written in a Holding Register (h9000 for E1 and h9001 for E2) with the bus mode activated.
The connection is made at the MODBUS RTU Slave interface. Connecting terminals: 2A (2D+), 2B (2D-).

| IO Setup | The bus mode of the inputs is set to "OFF" at the factory. <br> With activated bus mode, the raw values can be written accordingly into the Holding Registers, addresses h9000 and h9001 for "E1" and "E2". |
| :---: | :---: |
| OFF <br> E1 Busmode |  |
| IO Setup |  |
| OFF <br> E2 Busmode |  |

### 9.10.4 Function and inverting for relay outputs "K1" and "K2"

| IO Setup | Various functions can be allocated to the relay outputs "K1" and "K2". In case of the same function allocation for "K1" and "K2", these work parallel. <br> The inversion of the relays "K1" and "K2" is set at the factory to "OFF" (when a function is programmed). <br> For switching inversion to "ON" (switching behaviour dependent on assigned function). The relays can only pull up basically when the voltage supply of the electronics is working. Three-phase current devices must have at least 2 line phases! |  |  |
| :---: | :---: | :---: | :---: |
| Operating indication (1K) <br> K1 Function |  |  |  |
| IO Setup |  |  |  |
| OFF <br> K1 Inverting |  |  |  |
| IO Setup |  |  |  |
| Fault indication (2K) K2 Function |  |  |  |
| IO Setup |  |  |  |
| OFF <br> K2 Inverting |  |  |  |


| Function | Description |
| :---: | :---: |
| OFF | No function Relays remain always de-energized. |
| Operating indication (1K) | Operating indication (factory setting for "K1", non inverting). Operation without fault, reports enable "OFF" |
| Fault indication (2K) | Fault indication (factory setting for "K2", non inverting). <br> Pulled up in operation without fault, with release "OFF" not dropped out. <br> Drops out in case of line and device fault and external fault at the digital input. Depending on programming in event of sensor failure. <br> When networked via the MODBUS Master interface, fault indication in case of faulty MODBUS connection and fault on a member. |
| External error (3K) | External fault separate with message at digital input (factory setting if terminals bridged). |
| Limit modulation (4K) | Limit modulation Over or falling below limits for modulation. |
| Limit E1 <br> (5K) | Limit "E1" <br> Whenover or falling below limits for input signal "E1". |
| Limit E2 <br> (6K) | Limit "E2" <br> Whenover or falling below limits for input signal "E2". |
|  | For modes as controller (from 2.01.) |
| Setpoint Offset (7K) | Limit: Setpoint offset (only for active Setpoint control circuit 1). Deviation between actual value and setpoint to high. |
| Group2 <br> (8K) | Group control (Group 2) <br> Switching on fans depending on modulation |
| Group3 (12K) | Group control (Group 3) <br> Switching on fans depending on modulation |
| Group4 (14K) | Group control (Group 4) <br> Switching on fans depending on modulation |
|  | For modes as temperature controller with additional functions 2.03 |
| 2.Heating (9K) | Heating function <br> Switch ON point: temperature = Setpoint +/- Offset <br> Switch OFF point: Temperature around hysteresis over switch ON point |
| 2.Cooling (10K) | Cooling function <br> Switch ON point: temperature $=$ Setpoint $+/-$ Offset <br> Switch OFF point: Temperature around hysteresis below switch ON point |



| Function | Controller status | K1/ K2 <br> energized <br> de-energized |  |
| :---: | :--- | :---: | :---: |
|  |  | Inverting |  |
|  |  | OFF | ON |
| 1K | Operation without fault, line supply okay | $\mathbf{1}$ | 0 |
| 2K | Fault with indication by relay | $\mathbf{0}$ | 1 |
| 3K | External Fault at digital input for external fault | $\mathbf{1}$ | $\mathbf{0}$ |
| 4K | Over or falling below modulation | $\mathbf{1}$ | $\mathbf{0}$ |
| 5K | over or falling below limits for input signal "E1" | $\mathbf{1}$ | $\mathbf{0}$ |
| 6K | over or falling below limits for input signal "E2" | $\mathbf{1}$ | $\mathbf{0}$ |
| 7K | setpoint deviation to high | $\mathbf{1}$ | $\mathbf{0}$ |

### 9.10.5 COM2 Function

| IO Setup | Possible settings: <br> MODBUS Slave <br> - MODBUS Slave (factory setting): In the main menu the "Diagnostic" menu group is <br> COM2 Function <br> followed by the "MODBUS Slave" menu group. The communication parameters <br> can be set in this. |
| :--- | :--- |
|  | OFF: The "MODBUS Slave" or "MODEM SMS" menu group is not displayed in <br> the main menu. |
|  | MODEM SMS: In the main menu the "IO Setup" menu group is followed by the <br> "MODEM SMS" menu group. Input SIM PIN for MODEM SMS interface (no <br> function at present). |

### 9.11 Limits

### 9.11.1 Limit indication depending on modulation

only for Modulation control circuit 1!
Display for operation with two control circuits: 1.Modul. function, 1.Modulation min., 1.Modulation max., 1.Modul. Delay


[^3]
## Example indication by relay "K1":

## not inverted

IO Setup: K1 Function $=4 \mathrm{~K}$
IO Setup: K1 Inverting = OFF



A Modulation

## Inverting

IO Setup: K1 Function $=4 \mathrm{~K}$
IO Setup: K1 Inverting = OFF


$\stackrel{11.05 .2007}{\text { v_grenzwert_ausst_k1_i.vsd }}$
A Modulation
If "Level min." is higher than "Level max.", the "Level max." switching point is without hysteresi

### 9.11.2 Limit indication depending on setting or sensor signal

## Same procedure for analogue inputs "E1" and "E2".



| Limits | E1 Delay |
| :---: | :---: |
| Lmt E1Del. | Setting range: 0-120 sec. <br> Factory setting: 2 sec. |

## Information

Always adjust the value for the maximum input signal higher than the value for the minimum input signal!
E1 Max. > E1 Min.

Example for a limit indication of default signal or sensor signal to "Analog In 1"


Terminal "E1" and "GND" alarm via relay "K1" (non-inverted) IO Setup $\rightarrow$ K1 function: $5 \mathrm{~K}=$ limit indicators

### 9.11.3 Limit indication depending on (offset) to Setpoint

In operating modes as a controller (starting from 2.01), two limit indicators can be carried out based on the set target value (Setpoint) and measured actual value (on E1).
Only for active Setpoint of control circuit 1!
Display for operation with two control circuits: 1.Offset function, 1.Offset 1, 1.Offset 2, 1.Offset hyst., 1.Offset Delay


Example for temperature regulation; for other modes of operation settings in corresponding sensor unit.

Offset 1 for alarm during exceeding


Example: Setpoint $15.0^{\circ} \mathrm{C}$, Offset +5.0 K , Hysteresis 2.0 K

Offset 2 for alarm during undercutting


Example: Setpoint $15.0^{\circ} \mathrm{C}$, Offset -5.0 K , Hysteresis 2.0 K

### 9.12 Timer

### 9.12.1 Timerfunction

The device has a real time clock. The clock is backed up (Gold Cap) and has a reserve of 2 or 3 days after sufficient operation on a voltage supply.
The time and date must be set during start-up operation and when using the real-time clock. The device calculates the weekday based on the date.
In principle, the timer function acts like a digital switch input (timer "On" $=$ closed contact at inverting OFF). The same functions can be assigned to the timer switch as the digital inputs("D1 ..D2)".

| Function | Description * | $\begin{gathered} \text { Timer ON = } \\ (@ \text { Timer Invert. = OFF }) \end{gathered}$ |
| :---: | :---: | :---: |
| OFF | No function (factory setting) |  |
| Enable <br> (1D) | Enable (remote control) "ON" / "OFF" | Device ON |
| External error (2D) | External fault alarm | Failure |
| Limit (3D) | "Limit" ON / OFF <br> Influences control circuit 1 and control circuit 2 in operation with two control circuits | Limit ON |
| E1 / E2 <br> (4D) | Switch over input "E1" / "E2" (for operation with one control circuit) | Signal at E2 |
| Reset (10D) | Complete re-start of the device | Reset |
| Max. Speed (11D) | Setting Max. Speed "ON" / "OFF" <br> Influences the respectively set value "1. Max. Speed" and "2. <br> Max. Speed" in operation with two control circuits. | Max. Speed ON |
| Override Time (21D) | Do not use function for timer (only for digital input). |  |
|  |  |  |
| For mode speed controller 1.01 |  |  |
| Setpoint1/2 (5D) | Switch over "Set Intern1" / "Set Intern2" "Setting External 1" must be at "OFF". | Set Intern2 |
| Setpoint int./ext. (6D) | Switch over "Intern" / "Extern" | Set extern |
| For modes as controller (from 2.01.) |  |  |
| Setpoint1/2 <br> (5D) | Switch over "Setpoint 1" / "Setpoint 2"for control circuit1 | Setpoint2 |


| Function | Description * | Timer ON = <br> (@ Timer Invert. = OFF) |
| :---: | :---: | :---: |
| Setpoint int./ext. (6D) | Switch over "Intern" / "Extern" <br> Possible only for operation with one control circuit! | Setpoint External |
| Control/Manual (7D) | Switch over "automatic control" / "Speed manual" Possible only for operation with one control circuit! | Manual mode |
| Heating/Cooling (8D) | Switch over control function (e.g. "heating" / "cooling") | Reversal standard |
| $\begin{aligned} & \text { 1.Setp+Pband1/2 } \\ & \text { (15D) } \end{aligned}$ | for control circuit 1: Switch over Setpoint 1/2 and Pband 1/1 When programming this function, "Setting" additionally lists the parameter: "1.Pband2 for control circuit 1." | First control circuit Setpoint $2+$ Pband 2 |
|  |  |  |
|  | Only active in operation with a second control circuit! |  |
| $\begin{gathered} \text { E1 / E2 } \\ \text { (4D) } \end{gathered}$ | The output for control circuit 2 is additionally set to " A 2 " to "A1" (regardless of the programmed function for "A1"). The first control circuit has no output for the duration of the switch over. <br> The switch over input "E1" / "E2" as in operation with one control circuit is no longer possible. | Second control circuit to $\mathrm{A} 1+\mathrm{A} 2$ |
| 2. Setpoint 1/2 (9D) | for control circuit 2: Switch over "2. Setpoint 1" / "2. Setpoint 2 " | Second control circuit Setpoint 2 |
| 2.Setp+Pband1/2 <br> (16D) | for control circuit 2: Switch over Setpoint 1/2 and Pband 1/2 When programming this function, "Setting" additionally lists the parameter: " 2 Pb band2 for control circuit 2." | Second control circuit Setpoint $2+$ Pband 2 |

* Detailed description IO Setup / Digital Inputs "D1"/ "D2"


## Example: Programming limitation for output voltage (Limit ON / OFF)

Sequence


P

2

4
$3 \times 4$

6

[P]
7
[ESC]

| Controller Setup <br> IO Setup <br> Limits <br> Timer <br> Autoadressing |  |
| :---: | :---: |
| Timer | Press the P-key and set the hours with the UP / DOWN keys, press the P-key to save. Now the minutes flash and can be set with the UP / DOWN keys, press the P-key to save. |
| $\begin{aligned} & \text { 13:05 } \\ & \text { Time } \end{aligned}$ |  |
| Timer | To set the date follow the same method as for "Time". The date setting consists of day, month and year <br> Example for: 9. April 2013 |
| $\begin{gathered} \text { 09.04.13 } \\ \text { Date } \end{gathered}$ |  |

### 9.12.3 Automatic summer time

The summertime automatic is factory set to "OFF", i.e. switched off. When the summertime automatic is activated the device automatically switches between daylight saving time and wintertime.
"North" = for countries in the Northern Hemisphere.
"South" = for countries in the Southern Hemisphere.

|  |  | for Northern Hemisphere | for Southern Hemisphere |
| :---: | :---: | :---: | :---: |
| Timer |  | Timer | Timer |
| OFF <br> Summertime Auto. | $\rightarrow$ | North <br> Summertime Auto. | South <br> Summertime Auto. |

## Information

If the summer time automatic is used, the switch over date and the switch over time are identical and unchangeable for both settings.
The time is put forward from 2:00 am to 3:00 am respectively on the last Sunday in March (South put back from 3:00 am to 2:00 am) and put back from 3:00 am to 2:00 am (South put forward from 2:00 am to 3:00 am on the last Sunday in October.
If other dates for the switch over between summer time and winter time are required, the clock must be changed by hand (manually) on the respective date.

### 9.12.4 Enter switching times

Two switching times can be entered for the same function (e.g. 3D = Limit) for each weekday. The menu items are repeated for each weekday with two on- and off-times each. Switching times are not preprogrammed at the factory.
In order to make configuration easier, the same switching times can be made for several days in a block. To prevent unwanted switching times from arising, all should be deleted before programming. To do this, select the block Mo-Su and deactivate all 4 switching times.

Be sure to delete all switching times before carrying out complete new settings.


* If switching times are already programmed for all weekdays "Mon-Sun", press the $P$ key and increase the hours with the $\mathbf{\Delta}$ key until the deactivation appears after "23", display: --- . Then press the $P$ key twice to confirm and delete the switching times.

All programmed switching times are deleted after loading the factory setting or resetting the mode.

Factory setting without preprogrammed switching times

| Mon-Sun |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Mon-Fri |  |  |  |  |  |  |  |  |  | Sat-Sun |  |  |  |
| Mon |  | Tue |  | Wed |  | Thr |  | Fri |  | Sat |  | Sun |  |
| ON1 | - -:- - | ON1 | - -:- - | ON1 | --:- - | ON1 | --:- - | ON1 | --:- - | ON1 | - -:- - | ON1 | - -:- |
| OFF1 | --:- - | OFF1 | - -:- - | OFF1 | - -:- - | OFF1 | --:- - | OFF1 | --:- - | OFF1 | --:- - | OFF1 | - -:- - |
| ON2 | --:- - | ON2 | --:- - | ON2 | --:- - | ON2 | - -:- - | ON2 | --:- | ON2 | --:- - | ON2 | --:- - |
| OFF2 | --:- - | OFF2 | - -:- - | OFF2 | - -:- - | OFF2 | --:- - | OFF2 | --:- - | OFF2 | - -:- - | OFF2 | - -:- - |

## Example 1: Every day at 8 am ON and at 6 pm OFF

| Mon-Sun |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ON1 | 08:00 | ON1 | 08:00 | ON1 | 08:00 | ON1 | 08:00 | ON1 | 08:00 | ON1 | 08:00 | ON1 | 08:00 |
| OFF1 | 18:00 | OFF1 | 18:00 | OFF1 | 18:00 | OFF1 | 18:00 | OFF1 | 18:00 | OFF1 | 18:00 | OFF1 | 18:00 |
| ON2 | --:- - | ON2 | - -:- - | ON2 | --:- - | ON2 | - -:- - | ON2 | --:- - | ON2 | - -:- - | ON2 | - -:- - |
| OFF2 | --:- - | OFF2 | --:- | OFF2 | - -:- - | OFF2 | --:- - | OFF2 | --:- | OFF2 | --:- | OFF2 | --:- - |

## Example 2: Monday to Friday at 6 am ON at 8 am OFF and at 5 pm ON at 10 pm OFF

| Mon-Fri |  |  |  |  |  |  |  |  |  | Sat-Sun |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ON1 | 06:00 | ON1 | 06:00 | ON1 | 06:00 | ON1 | 06:00 | ON1 | 06:00 | ON1 | - -:- - | ON1 | --:- |
| OFF1 | 08:00 | OFF1 | 08:00 | OFF1 | 08:00 | OFF1 | 08:00 | OFF1 | 08:00 | OFF1 | --:- | OFF1 | - -:- - |
| ON2 | 17:00 | ON2 | 17:00 | ON2 | 17:00 | ON2 | 17:00 | ON2 | 17:00 | ON2 | - -:- - | ON2 | - -:- - |
| OFF2 | 22:00 | OFF2 | 22:00 | OFF2 | 22:00 | OFF2 | 22:00 | OFF2 | 22:00 | OFF2 | -- | OFF2 | --:- |

## Example 3: Wednesday 6 pm ON and Thursday at 8 am OFF

| Mon |  | Tue |  | Wed |  | Thr |  | Fri |  | Sat |  | Sun |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ON1 | --:- - | ON1 | - -:- - | ON1 | 18:00 | ON1 | --:- - | ON1 | --:- - | ON1 | - -:- - | ON1 | --:- - |
| OFF1 | - -:- - | OFF1 | - -:- - | OFF1 | - -:- - | OFF1 | 08:00 | OFF1 | --:- | OFF1 | --:- | OFF1 | --:- |
| ON2 | --:- - | ON2 | --:- - | ON2 | --:- - | ON2 | --:- - | ON2 | --:- | ON2 | - -:- - | ON2 | --:- |
| OFF2 | --:- | OFF2 | - -:- - | OFF2 | --:- - | OFF2 | --:- - | OFF2 | --:- | OFF2 | - -:- - | OFF2 | --:- |


| Free tables for entering individual timer settings |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| M | Tu | We |  |  |  | Sun |  |
|  |  |  |  |  |  |  |  |
| ON1 | ON1 | ON1 | ON1 | ON1 | ON1 | ON1 |  |
| OFF1 | OFF1 | OFF1 | OFF1 | OFF1 | OFF1 | OFF1 |  |
| ON2 | ON2 | ON2 | ON2 | ON2 | ON2 | ON2 |  |
| OFF2 | OFF2 | OFF2 | OFF2 | OFF2 | OFF2 | OFF2 |  |

### 9.12.5 Inverting timer function

Inverting of the timer function is possible if required.

| Timer | Timer Inverting |
| :---: | :--- |
| OFF | In the "OFF" setting (factory setting), the programmed function is activated at the <br> switch-on time (clock icon in the display) and deactivated again at the switch-off time <br> (cs timer function). |
| Timer Inverting |  |
| In the "ON" setting, the programmed function is deactivated at the switch-on time and |  |
| activated again at the switch-off time (clock icon in the display). |  |

### 9.12.6 Overwrite timer function

The timer output can be overwritten for a settable time with a selectable status if required. Activation is by a digital input (IO Setup function 21D)
Application: Exceptions from the normal timing operation, e.g. for manual or automatic presence switch, party mode, etc.

| Timer | Override Time <br> 120 min <br> Override Time <br> Settable time for overwriting the timer function <br> Setting range: $0 \ldots 65535 \mathrm{~min}$. <br> Factory setting: 120 min |
| :--- | :--- |
| In the "0 min." setting, the timer function is overwritten with the selected status until the |  |
| next timing change. |  |

### 9.12.7 Adjustment of the real time clock

| Timer | Fine adjustment of the real time clock is possible if required. |  |  |
| :--- | :--- | :---: | :---: |
| The greater the value, the slower the clock runs. If the value is increased by one point, <br> this corresponds to a slowing of the clock by approx. 2 to 3 s per month. |  |  |  |
| RTC Adjust | Setting range: $0-127$ |  |  |
|  | Factory setting: 60 |  |  |

### 9.13 MODBUS Slave

Addressing and configuration of the MODBUS Slave interface.
Via this interface the device can be networked with a master building control system, the device then operates as a pure Slave and uses the MODBUS-RTU protocol.
The connection is made to the terminals "2A (2D+)", "2B (2D-)" of the MODBUS Slave interface ( installation / RS-485 interfaces for MODBUS RTU).

## Information

- In the IO Setup the "COM function must be set" to "MODBUS Slave" so that this menu group is displayed (factory setting).
- MODBUS settings (baud rate, parity) are saved after a reset ( menu group "Start" -> "Reset" or interrupt voltage supply).

| MODBUS Slave | Bus Address <br> The device address is factory set to the highest available MODBUS address: 247. Setting range MODBUS Address: 1-247. |
| :---: | :---: |
| $247$ <br> Bus Address |  |
| MODBUS Slave | Addressing <br> Switch addressing to "ON" before setting "address". |
| OFF <br> Addressing |  |
| MODBUS Slave | UART Baudrate <br> Setting transfer rate Valid values: 4800, 9600, 19200, 38400, 115200 Factory setting: 19200 |
| $19200$ <br> UART Baudrate |  |
| MODBUS Slave | UART Mode <br> Setting transfer format Valid values: $8 \mathrm{O} 1,8 \mathrm{~N} 1,8 \mathrm{E} 1$ Factory setting: 8E1 |
| 8E1 <br> UART Mode |  |

### 9.14 MODBUS Master

Addressing of the members that are activated via the MODBUS Master interface.
Addressing can be done automatically by a patented method. It is then no longer necessary to address every single member manually in the network.
Alternatively, manual addressing is possible, for which separate components are required for setting the individual member address.

## Information

- A maximum of 32 devices can be connected. The communication settings are pre-set to 19.2 kbd , 8E1 and cannot be changed.
- To ensure activation, the function of the digital input "D1" of the members is automatically set to "OFF" by the MODBUS Master. I.e. any programmed enable function for switching off the member (by a potential-free contact) is no longer active.

| Main menu | MODBUS Master |
| :---: | :---: |
| MODBUS Master | After addressing (manual or automatic), the devices are subsequently listed to the |
| Fan 1 (2A) | "MODBUS Master" menu group (\%"members MODBUS Master"). |
| Fan 2 (2A) |  |
| Fan 3 (2A) |  |
| [P] Enter [ESC] Info |  |

### 9.14.1 Automatic addressing

- The first member (MODBUS address 1) must be connected to the terminals 1A(1D+) and 1B (1D-), additionally the "ID" connections must be connected ( installation / communication / addressing members MODBUS Master interface).
- The members are automatically addressed consecutively according to the installation.
- In order to do the automatic addressing successfully, all the bus members to be addressed must be connected with each other, applied to voltage and switched on.

The automatic addressing can only be done with compatible devices!


### 9.14.2 Manual addressing

The addressing is done manually by a separate hand held terminal or PC software, the corresponding member count must be entered on the MODBUS Master.

- The members are connected to the device by the terminals 1A(1D+) and 1B (1D-) ( installation / communication).
- All bus members must be addressed uniquely, consecutively and starting at address 1 . Otherwise communication could be disturbed or no communication can be set up.
- In order to complete the manual addressing successfully, all the bus members to be addressed must be connected with each other, applied to voltage and switched on.

| Main menu |  | MODBUS Master |
| :---: | :---: | :---: |
| Limits <br> Timer <br> Diagnostic <br> MODBUS Master |  |  |
| [P] Enter | [ESC] Info |  |
| MODBUS |  | Press the P-key to open the "MODBUS Master". |
| Autoaddressing |  |  |
| [P] Enter | [ESC] Menu |  |
| MODBUS Master |  | Press the $\boldsymbol{\nabla}$-key to select the "Bus Slavecount" menu. |
|  | ecount |  |
| [P] Edit | [ESC] Menu |  |
| MODBUS |  | Press the P-key to open the menu. |
| [P] Edit | [ESC] Menu |  |


| Info | Error message when entering too high a member count, alternately with the actual |
| :--- | :--- |

### 9.15 Member MOBUS Master

After addressing, (manual or automatic) the members are then listed to the "MODBUS Master" menu group.

| Main menu | The function for activation by MODBUS is displayed after the address of the |
| :--- | :--- |
| MODBUS Master | member. |
| Fan $1(2 A)$ | The same function is programmed initially for all members after addressing. 1. |
| Fan $2(2 A)$ | Control Signal $(2 A)$. |
| Fan $3(2 A)$ | l.e. every member is activated by the output of control circuit 1. |
| $[P]$ Enter $[$ [ESC] Info |  |

After selection with the $\boldsymbol{\nabla} \boldsymbol{\Delta}$ keys, press the $\mathbf{P}$-key to open the State menu of the member (menu content depends on the type of member).

## State menu member

Example: ECblue fan

| Fan $1(2 A)$ |  |
| :--- | :--- |
| ECblue V13.05 | $\leftarrow$ Device type and firmware version |
| Fan OK! | $\leftarrow$ Operating state of the member |
| Speed [rpm 570] | $\leftarrow$ Speed Actual value $(1 /$ min $)$ |
| Motorcurrent [A] 2.60 | $\leftarrow$ Current consumption |
| P=0W $\quad$ Level $=0 \%$ | $\leftarrow$ Power consumption and modulation of the device |
| [P] Edit $\quad$ [ESC] Menu |  |

To set the MODBUS function for the member, press the $\mathbf{P}$-key.


Exit the menu with the Esc key combination $\boldsymbol{\nabla}+\boldsymbol{\Delta}$.

## 10 Menu tables

### 10.1 Menues of operating modes

| Mode | $\begin{aligned} & 1.01 \\ & 1.02 \end{aligned}$ | $\begin{aligned} & 2.01 \\ & 2.03 \\ & 2.04 \end{aligned}$ | 2.02 | 2.05 | $\begin{aligned} & 3.01 \\ & 3.02 \end{aligned}$ | $\begin{aligned} & 3.03 \\ & 3.04 \end{aligned}$ | 4.01 4.02 4.03 | $\begin{aligned} & 5.01 \\ & 5.02 \end{aligned}$ | 6.01 | User Setting |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Parameter | Factory setting |  |  |  |  |  |  |  |  |  |
| Info |  |  |  |  |  |  |  |  |  |  |
| Setting direct | $\begin{aligned} & 1.02= \\ & 80 \% \end{aligned}$ |  |  |  |  |  |  |  |  |  |
| Setting step ${ }^{1}$ | $1.02=0$ |  |  |  |  |  |  |  |  |  |
| E1-E2 actual |  |  |  | $-2.4{ }^{\circ} \mathrm{C}$ |  |  |  |  |  |  |
| Control value |  | $\begin{gathered} 2.04= \\ 300^{\circ} \mathrm{C} \end{gathered}$ |  |  |  | $\begin{aligned} & 12.0 \mathrm{bar} \\ & 26^{\circ} \mathrm{C} \end{aligned}$ |  |  |  |  |
| E1 Actual |  | $30.0{ }^{\circ} \mathrm{C}$ | $30.0{ }^{\circ} \mathrm{C}$ | $30.0{ }^{\circ} \mathrm{C}$ | $\begin{aligned} & 10.0 \mathrm{bar} \\ & -88.7^{\circ} \mathrm{C} \end{aligned}$ | $\begin{aligned} & 10.0 \mathrm{bar} \\ & -88.7^{\circ} \mathrm{C} \end{aligned}$ | 88.7 Pa | $712 \mathrm{~m}^{3} \mathrm{~h}$ | $0.45 \mathrm{~m} / \mathrm{s}$ |  |
| E2 Actual |  | $\begin{gathered} 2.04= \\ 30.0^{\circ} \mathrm{C} \end{gathered}$ | ----- | $30.0{ }^{\circ} \mathrm{C}$ | - | $\begin{aligned} & 10.0 \text { bar } \\ & -88.7^{\circ} \mathrm{C} \end{aligned}$ | $\begin{gathered} 4.02 \\ 4.03= \\ 21.0^{\circ} \mathrm{C} \end{gathered}$ | $\begin{gathered} 5.02= \\ 21.0^{\circ} \mathrm{C} \end{gathered}$ | ----- |  |
| Setpoint1 <br> 1. Setpoint $1^{2}$ |  | $20.0{ }^{\circ} \mathrm{C}$ | $5.0{ }^{\circ} \mathrm{C}$ | $0.0{ }^{\circ} \mathrm{C}$ | $\begin{aligned} & 12.0 \mathrm{bar} \\ & 35.0^{\circ} \mathrm{C} \end{aligned}$ | $\begin{aligned} & 12.0 \mathrm{bar} \\ & 35.0^{\circ} \mathrm{C} \\ & \hline \end{aligned}$ | 100 Pa | $530 \mathrm{~m}^{3} \mathrm{~h}$ | $0.50 \mathrm{~m} / \mathrm{s}$ |  |
| 2.Setpoint $1^{3}$ |  |  |  |  |  |  |  |  |  |  |
| Setpoint control |  |  |  |  |  |  | $\begin{aligned} & 4.02, \\ & 4.03= \\ & 100 \mathrm{~Pa} \end{aligned}$ | $\begin{gathered} 5.02= \\ 530 \mathrm{~m}^{3} \mathrm{~h} \end{gathered}$ |  |  |
| Modulation 1. Control ${ }^{2}$ | $\begin{gathered} 1.01= \\ 0 \% \end{gathered}$ | 0 \% | 0 \% | 0 \% | 0 \% | 0 \% | 0 \% | 0 \% | 0 \% |  |
| 1. Control ${ }^{3}$ |  | 0 \% | 0 \% |  | 0 \% | 0 \% | 0 \% | 0 \% | 0 \% |  |
| Set external1 | $\begin{gathered} 1.01= \\ 0 \% \end{gathered}$ |  |  |  |  |  |  |  |  |  |
| Min. speed cut off 1. Min. speed cut off ${ }^{2}$ |  | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| 2. Min. speed cut off ${ }^{3}$ |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |
| Start |  |  |  |  |  |  |  |  |  |  |
| PIN input | ---- | --- | --- | -- | --- | --- | --- | --- | --- |  |
| Language | GB | GB | GB | GB | GB | GB | GB | GB | GB |  |
| US units | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| Reset | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| Mode | $\begin{aligned} & 1.01 \\ & 1.02 \end{aligned}$ | $\begin{aligned} & 2.01 \\ & 2.03 \\ & 2.04 \end{aligned}$ | 2.02 | 2.05 | $\begin{aligned} & 3.01 \\ & 3.02 \end{aligned}$ | $\begin{aligned} & 3.03 \\ & 3.04 \end{aligned}$ | $\begin{aligned} & 4.01 \\ & 4.02 \\ & 4.03 \end{aligned}$ | $\begin{aligned} & 5.01 \\ & 5.02 \end{aligned}$ | 6.01 |  |
| xxx | 9.31 | 9.31 | 9.31 | 9.31 | 9.31 | 9.31 | 9.31 | 9.31 | 9.31 |  |
| SN: | $\begin{aligned} & \text { 000005- } \\ & \text { E45536 } \end{aligned}$ | $\begin{aligned} & \text { 000005- } \\ & \text { E45536 } \\ & \hline \end{aligned}$ | $\begin{array}{\|l\|l\|} \hline 000005- \\ \text { E45536 } \\ \hline \end{array}$ | $\begin{array}{\|l\|} \hline 000005- \\ \text { E45536 } \\ \hline \end{array}$ | $\begin{aligned} & \text { 000005- } \\ & \text { E45536 } \\ & \hline \end{aligned}$ | $\begin{array}{\|l\|l\|} \hline 000005- \\ \text { E45536 } \\ \hline \end{array}$ | $\begin{array}{\|l\|} \hline 000005- \\ \text { E45536 } \\ \hline \end{array}$ | $\begin{aligned} & \text { 000005- } \\ & \text { E45536 } \\ & \hline \end{aligned}$ | 000005- <br> E45536 |  |
|  |  |  |  |  |  |  |  |  |  |  |
| Setting |  |  |  |  |  |  |  |  |  |  |
| Set Intern1 | $\begin{gathered} 1.01= \\ 80 \% \end{gathered}$ |  |  |  |  |  |  |  |  |  |
| Set Intern2 | $\begin{gathered} 1.01=-- \\ -- \end{gathered}$ |  |  |  |  |  |  |  |  |  |
| Setting direct | $\begin{gathered} 1.02= \\ 80 \% \end{gathered}$ |  |  |  |  |  |  |  |  |  |


| Mode | $\begin{aligned} & 1.01 \\ & 1.02 \end{aligned}$ | $\begin{aligned} & 2.01 \\ & 2.03 \\ & 2.04 \end{aligned}$ | 2.02 | 2.05 | $\begin{aligned} & 3.01 \\ & \hline 3.02 \end{aligned}$ | $\begin{aligned} & 3.03 \\ & \hline 3.04 \end{aligned}$ | 4.01 4.02 4.03 | $\begin{aligned} & 5.01 \\ & 5.02 \end{aligned}$ | 6.01 | User Setting |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Parameter | Factory setting |  |  |  |  |  |  |  |  |  |
| Setting step ${ }^{1}$ | $1.02=0$ |  |  |  |  |  |  |  |  |  |
| Setpoint1 1. Setpoint $1^{2}$ |  | $20.0{ }^{\circ} \mathrm{C}$ | $5.0{ }^{\circ} \mathrm{C}$ | $0.0{ }^{\circ} \mathrm{C}$ | $\begin{aligned} & 12.0 \mathrm{bar} \\ & 35.0^{\circ} \mathrm{C} \\ & \hline \end{aligned}$ | $\begin{aligned} & 12.0 \mathrm{bar} \\ & 35.0^{\circ} \mathrm{C} \\ & \hline \end{aligned}$ | 100 Pa | $530 \mathrm{~m}^{3} \mathrm{~h}$ | $0.50 \mathrm{~m} / \mathrm{s}$ |  |
| Setpoint2 <br> 1. Setpoint $2^{2}$ |  | -- | ----- | --- | ---- | ----- | $4.03=$ $100 \mathrm{~Pa}$ | ---- | ---- |  |
| Pband 1 <br> 1. Pband $1^{2}$ |  | 5.0 K | 20.0 K | 5.0 K | 5.0 bar 7.0 K | 5.0 bar 7.0 K | 100 Pa | $530 \mathrm{~m}^{3} \mathrm{~h}$ | $0.50 \mathrm{~m} / \mathrm{s}$ |  |
| 1. Pband $2^{4}$ |  | 5.0 K | 20.0 K | 5.0 K | 5.0 bar 7.0 K | 5.0 bar 7.0 K | 100 Pa | $530 \mathrm{~m}^{3} \mathrm{~h}$ | $0.50 \mathrm{~m} / \mathrm{s}$ |  |
| Min. Speed 1.Min. Speed ${ }^{2}$ | 0\% | 0\% | 0\% | 0\% | 0\% | 0\% | 0\% | 0\% | 0\% |  |
| Max. Speed <br> 1. Max. Speed ${ }^{2}$ | 100 \% | 100 \% | 100 \% | 100 \% | 100 \% | 100 \% | 100 \% | 100 \% | 100 \% |  |
| 2. Setpoint $1^{3}$ |  |  |  |  |  |  |  |  |  |  |
| 2.Setpoint $2^{3}$ |  |  |  |  |  |  |  |  |  |  |
| 2. Pband $1^{3}$ |  |  |  |  |  |  |  |  |  |  |
| 2. Pband $2^{5}$ |  |  |  |  |  |  |  |  |  |  |
| 2. Min. Speed ${ }^{3}$ | 0\% | 0\% | 0\% |  | 0\% |  | 0\% | 0\% | 0\% |  |
| 2. Max. Speed ${ }^{3}$ | 100 \% | 0\% | 100 \% |  | 100 \% |  | $100 \%$ | $100 \%$ | $100 \%$ |  |
| Set external1 | $\begin{gathered} 1.01= \\ \text { ON } \end{gathered}$ |  |  |  |  |  |  |  |  |  |
| Manual mode <br> 1. Manual mode ${ }^{2}$ |  | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| Speed manual <br> 1. Speed man. ${ }^{2}$ |  | 100 \% | 100 \% | 100 \% | 100 \% | 100 \% | 100 \% | 100 \% | 100 \% |  |
| Offset AnalogOut |  | $\begin{gathered} 2.03= \\ 0.0 \mathrm{~K} \end{gathered}$ |  |  |  |  |  |  |  |  |
| Pband AnalogOut |  | $\begin{gathered} 2.03= \\ 2.0 \mathrm{~K} \end{gathered}$ |  |  |  |  |  |  |  |  |
| Min. AnalogOut |  | $\begin{gathered} 2.03= \\ 0 \% \end{gathered}$ |  |  |  |  |  |  |  |  |
| Max. AnalogOut |  | $\begin{aligned} & 2.03= \\ & 100 \% \end{aligned}$ |  |  |  |  |  |  |  |  |
| OffsetDigitalOut |  | $\begin{gathered} 2.03= \\ 1.0 \mathrm{~K} \end{gathered}$ |  |  |  |  |  |  |  |  |
| Hyst.DigitalOut |  | $\begin{gathered} 2.03= \\ 1.0 \mathrm{~K} \end{gathered}$ |  |  |  |  |  |  |  |  |
| Alarm Minimum |  | $\begin{aligned} & 2.03= \\ & 0.0^{\circ} \mathrm{C} \end{aligned}$ |  |  |  |  |  |  |  |  |
| Alarm Maximum |  | $\begin{gathered} 2.03= \\ 40.0^{\circ} \mathrm{C} \end{gathered}$ |  |  |  |  |  |  |  |  |
| T-Band SA |  |  |  |  |  |  | $\begin{aligned} & 4.02+ \\ & 4.03= \\ & 30.0 \mathrm{~K} \end{aligned}$ | $\begin{aligned} & 5.02= \\ & 30.0 \mathrm{~K} \end{aligned}$ |  |  |
| T-Start SA |  |  |  |  |  |  | $\begin{gathered} 4.02+ \\ 4.03= \\ 15.0^{\circ} \mathrm{C} \end{gathered}$ | $\begin{aligned} & 5.02= \\ & 15.0^{\circ} \mathrm{C} \end{aligned}$ |  |  |
| Min Setpoint |  |  |  |  |  |  | $\begin{gathered} 4.02+ \\ 4.03= \\ 70.0 \mathrm{~Pa} \end{gathered}$ | $\begin{gathered} 5.02= \\ 700 \mathrm{~m}^{3} \mathrm{~h} \end{gathered}$ |  |  |
|  |  |  |  |  |  |  |  |  |  |  |
| Protocol |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |


| Mode | $\begin{aligned} & 1.01 \\ & 1.02 \end{aligned}$ | $\begin{aligned} & \hline 2.01 \\ & 2.03 \\ & 2.04 \\ & \hline \end{aligned}$ | 2.02 | 2.05 | $\begin{gathered} 3.01 \\ \hline 3.02 \end{gathered}$ | $\begin{aligned} & 3.03 \\ & \hline 3.04 \end{aligned}$ | $\begin{aligned} & 4.01 \\ & 4.02 \\ & 4.03 \end{aligned}$ | $\begin{gathered} 5.01 \\ 5.02 \end{gathered}$ | 6.01 | User Setting |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Parameter | Factory setting |  |  |  |  |  |  |  |  |  |
| Base setup |  |  |  |  |  |  |  |  |  |  |
| Mode | $\begin{aligned} & 1.01 \\ & 1.02 \end{aligned}$ | $\begin{aligned} & 2.01 \\ & \hline 2.03 \\ & \hline 2.04 \\ & \hline \end{aligned}$ | 2.02 | 2.05 | $\begin{array}{\|l} \hline 3.01 \\ \hline 3.02 \\ \hline \end{array}$ | $\begin{array}{\|l\|} \hline 3.03 \\ \hline \mathbf{3 . 0 4} \end{array}$ | $\begin{array}{\|l\|} \hline 4.01 \\ \hline 4.02 \\ \hline 4.03 \\ \hline \end{array}$ | $\begin{array}{\|l\|} \hline 5.01 \\ \hline 5.02 \\ \hline \end{array}$ | 6.01 |  |
| E1 Analog In | $\begin{gathered} 1.01=0 \\ -10 \mathrm{~V} \end{gathered}$ | TF | TF | TF | $\begin{aligned} & 0-30 \\ & \text { MBG } \end{aligned}$ | $\begin{aligned} & \text { 0-30 } \\ & \text { MBG } \end{aligned}$ | DSG200 | $\begin{array}{\|c\|} \hline 4.01= \\ \text { DSG200 } \\ 4.02+ \\ 4.03= \\ \text { DSG50 } \end{array}$ | 0-1 MAL |  |
| Number steps | $1.02=0$ |  |  |  |  |  |  |  |  |  |
| Step 1 value | $\begin{array}{\|l\|} \hline 1.02=-- \\ -(20 \%) \\ \hline \end{array}$ |  |  |  |  |  |  |  |  |  |
| Step 2 value | $\begin{aligned} & \hline 1.02=-- \\ & --(40 \%) \\ & \hline \end{aligned}$ |  |  |  |  |  |  |  |  |  |
| Step 3 value | $\begin{aligned} & 1.02=-- \\ & --(50 \%) \end{aligned}$ |  |  |  |  |  |  |  |  |  |
| Step 4 value | $\begin{aligned} & 1.02=-- \\ & --(60 \%) \end{aligned}$ |  |  |  |  |  |  |  |  |  |
| Step 5 value | $\begin{gathered} 1.02=-- \\ -- \\ (100 \%) \end{gathered}$ |  |  |  |  |  |  |  |  |  |
| E1 Refrigerant |  |  |  |  | $\begin{aligned} & 3.02= \\ & \text { R503 } \end{aligned}$ | $\begin{aligned} & 3.04= \\ & \text { R503 } \end{aligned}$ |  |  |  |  |
| E1 K-Factor |  |  |  |  |  |  |  | 75 |  |  |
| E1 Unit |  | ----- | ----- | ----- | ----- | ----- | ----- | ----- | ----- |  |
| E1 Decimals |  | ----- | ----- | ----- | ----- | ---- | ---- | ---- - | ---- |  |
| E1 Min. |  | - | -- | ----- | --- | ---- | ---- | --- | --- |  |
| E1 max |  | ----- | ----- | ----- | ----- | ----- | ----- | ----- | ----- |  |
| E1 Offset |  | $149.9{ }^{\circ} \mathrm{C}$ | $149.9{ }^{\circ} \mathrm{C}$ | $149.9{ }^{\circ} \mathrm{C}$ | $\begin{aligned} & 0.00 \mathrm{bar} \\ & 149.9^{\circ} \mathrm{C} \end{aligned}$ | 0.00 bar <br> $149.9^{\circ} \mathrm{C}$ | 0.0 Pa | $0 \mathrm{~m}^{3} \mathrm{~h}$ | 0.0 m/s |  |
| E2 Function | $\begin{gathered} 1.01= \\ \text { OFF } \end{gathered}$ | $\begin{gathered} \text { OFF } \\ 2.04= \\ 4 \mathrm{E} \end{gathered}$ | OFF | 5E | OFF | 4E | $\begin{gathered} \text { OFF } \\ 4.02+ \\ 4.03= \\ 6 \mathrm{E} \end{gathered}$ | $\begin{gathered} \text { OFF } \\ 5.02= \\ 6 \mathrm{E} \end{gathered}$ | OFF |  |
| E2 Analog In | $1.01=--$ --- | $\begin{gathered} 2.04= \\ \text { TF } \end{gathered}$ | - | TF | -- | $\begin{aligned} & \text { 0-30 } \\ & \text { MBG } \end{aligned}$ | $\begin{gathered} 4.02= \\ \text { TF } \\ 4.03= \\ \text { Bus } \end{gathered}$ | $5.02=$ TF | ----- |  |
| E2 Refrigerant |  |  |  |  |  | $\begin{aligned} & 3.04= \\ & \text { R503 } \end{aligned}$ |  |  |  |  |
| E2 K-Factor ${ }^{2}$ |  |  |  |  |  |  |  | ----- |  |  |
| E2 Unit |  | ---- | --- | --- | ---- | ----- | $\begin{aligned} & 4.03 \\ & ={ }^{\circ} \mathrm{C} \\ & \hline \end{aligned}$ | ---- | ----- |  |
| E2 Decimals |  | -- | --- | ----- | -- - | ----- | $4.03=1$ | ---- | -- |  |
| E2 Min. |  | - - | --- | --- | ---- | ----- | $\begin{aligned} & 4.03=- \\ & 35.0^{\circ} \mathrm{C} \end{aligned}$ | ----- | ---- |  |
| E2 Max. |  | ----- | ----- | ---- | ----- | ----- | $4.03=$ $65.0^{\circ} \mathrm{C}$ | ----- | ----- |  |


| Mode | $\begin{aligned} & 1.01 \\ & 1.02 \end{aligned}$ | $\begin{aligned} & 2.01 \\ & 2.03 \\ & 2.04 \end{aligned}$ | 2.02 | 2.05 | $\begin{aligned} & 3.01 \\ & \hline 3.02 \end{aligned}$ | $\begin{gathered} 3.03 \\ \hline 3.04 \end{gathered}$ | $\begin{aligned} & 4.01 \\ & 4.02 \\ & 4.03 \end{aligned}$ | $\begin{gathered} 5.01 \\ 5.02 \end{gathered}$ | 6.01 | User Setting |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Parameter | Factory setting |  |  |  |  |  |  |  |  |  |
| E2 Offset |  | $\begin{gathered} 2.04= \\ 149.9^{\circ} \mathrm{C} \end{gathered}$ | ---- | $149.9{ }^{\circ} \mathrm{C}$ | ---- | $\begin{aligned} & 0.00 \mathrm{bar} \\ & 149.9^{\circ} \mathrm{C} \end{aligned}$ | $\begin{array}{\|c\|} \hline---- \\ 4.02+ \\ 4.03= \\ 149.9^{\circ} \mathrm{C} \\ \hline \end{array}$ | $\begin{gathered} ---- \\ 5.02= \\ 149.9^{\circ} \mathrm{C} \end{gathered}$ | ----- |  |
| Controller Setup |  |  |  |  |  |  |  |  |  |  |
| PIN Protection | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| Set protection | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| Save User Setup | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| Alarm sensors |  | ON | ON | ON | ON | ON | ON | ON | ON |  |
| Limit | ----- | ----- | ---- | ---- - | ----- | ---- - | ---- | ---- - | ----- |  |
| Min. speed cut off 1. Min. speed cut off ${ }^{2}$ |  | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| 2. Min. speed cut off ${ }^{3}$ |  |  |  |  |  |  |  |  |  |  |
| Val>Set=n+ <br> 1. $\mathrm{Val}>$ Set $=n+{ }^{2}$ |  | ON | ON | ON | ON | ON | OFF | OFF | OFF |  |
| 2. Val>Set=n+ ${ }^{3}$ |  |  |  |  |  |  |  |  |  |  |
| Type of control 1.Controller type ${ }^{2}$ |  | P | P | P | P | P | Pid | Pid | Pid |  |
| 2.Controller type ${ }^{3}$ |  |  |  |  |  |  |  |  |  |  |
| KP |  | 50 \% | $50 \%$ | 50 \% | 50 \% | 50 \% | 50 \% | 50 \% | 50 \% |  |
| KI |  | $50 \%$ | 50 \% | 50 \% | 50 \% | 50 \% | 50 \% | 50 \% | 50 \% |  |
| KD |  | 50 \% | 50 \% | 50 \% | 50 \% | 50 \% | 50 \% | 50 \% | 50 \% |  |
| TI |  | 0 \% | 0 \% | 0 \% | 0 \% | 0 \% | 0 \% | 0 \% | 0 \% |  |
| Group version | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |  |
| Group 2 ON value | ----- | ---- | ---- | --- | ----- | --- | ---- | ---- | ----- |  |
| OFF Value Group2 | ---- | ---- | ---- | --- | ----- | ----- | ----- | ----- | ----- |  |
| nmin at Group2 | ----- | ----- | ---- | ----- | ----- | ----- | ---- | ----- | ----- |  |
| Group 3 ON value | ----- | -- | -- | ----- | --- | -- | --- | --- | --- |  |
| OFF Value Group3 | ---- | -- | -- | ----- | --- | -- | ----- | --- | ----- |  |
| nmin at Group3 | ---- | ---- | ---- | ----- | ---- | ----- | ---- | ---- | --- |  |
| Group 4 ON value | ---- | ----- | ---- | --- | ----- | --- | ---- | ---- | ----- |  |
| OFF Value Group4 | ----- | ----- | ----- | ----- | ----- | ----- | --- | ----- | ---- |  |
| nmin at Group4 | --- | --- | -- | ----- | -- | -- | --- | --- | --- |  |
| External message | External error |  |  |  |  |  |  |  |  |  |
| Offset control sig. 1 | 0 \% | 0 \% | 0 \% | 0 \% | 0 \% | 0 \% | 0 \% | 0 \% | 0 \% |  |
| Selection amplifier |  | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
|  |  |  |  |  |  |  |  |  |  |  |
| 10 Setup |  |  |  |  |  |  |  |  |  |  |
| A1 Function | 2A | 2A | 2A | 2A | 2A | 2A | 2A | 2A | 2A |  |
| A1 min. | 0.0 V | 0.0 V | 0.0 V | 0.0 V | 0.0 V | 0.0 V | 0.0 V | 0.0 V | 0.0 V |  |
| A1 max. | 10.0 V | 10.0 V | 10.0 V | 10.0 V | 10.0 V | 10.0 V | 10.0 V | 10.0 V | 10.0 V |  |
| A1 Inverting | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| A2 Function | 1A | $\begin{gathered} \text { 1A (2.03 } \\ =6 \mathrm{~A}) \end{gathered}$ | 1A | 1A | 1A | 1A | 1A | 1A | 1A |  |
| A2 min. | 0.0 V | 0.0 V | 0.0 V | 0.0 V | 0.0 V | 0.0 V | 0.0 V | 0.0 V | 0.0 V |  |
| A2 max. | 10.0 V | 10.0 V | 10.0 V | 10.0 V | 10.0 V | 10.0 V | 10.0 V | 10.0 V | 10.0 V |  |


| Mode | $\begin{aligned} & 1.01 \\ & 1.02 \end{aligned}$ | 2.01 <br> 2.03 <br> 2.04 | 2.02 | 2.05 | $\begin{aligned} & 3.01 \\ & \hline 3.02 \end{aligned}$ | $\begin{gathered} 3.03 \\ \hline 3.04 \end{gathered}$ | $\begin{aligned} & 4.01 \\ & 4.02 \\ & 4.03 \\ & \hline \end{aligned}$ | $\begin{gathered} 5.01 \\ 5.02 \end{gathered}$ | 6.01 | User Setting |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Parameter | Factory setting |  |  |  |  |  |  |  |  |  |
| A2 Inverting | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| D1 Function | OFF | OFF | OFF | OFF | OFF | OFF | $\begin{gathered} \text { OFF } \\ 4.03= \\ 1 D \end{gathered}$ | OFF | OFF |  |
| D1 Inverting | ---- | ----- | ---- | ---- | ----- | ----- | $4.03=$ OFF | ----- | ----- |  |
| D1 Busmode | -- | --- | ---- | --- | ----- | ----- | $4.03=$ ON | ----- | ----- |  |
| D2 Function | OFF | OFF | OFF | OFF | OFF | OFF | $\begin{gathered} \text { OFF } \\ 4.03= \\ 5 \mathrm{D} \end{gathered}$ | OFF | OFF |  |
| D2 Inverting | --- | ----- | -- | --- | ---- | --- | $4.03=$ OFF | ----- | ----- |  |
| D2 Busmode | --- | ----- | ---- | ---- | ----- | ----- | $4.03=$ ON | ----- | ----- |  |
| D-D Relation | OG | OG | OG | OG | OG | OG | OG | OG | OG |  |
| E1 Inverting | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| E1 Busmode | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| E2 Inverting | ----- | $\begin{gathered} 2.04= \\ \text { OFF } \end{gathered}$ | ---- | OFF | ----- | OFF | $\begin{gathered} 4.02+ \\ 4.03= \\ \text { OFF } \end{gathered}$ | $\begin{gathered} 5.02= \\ \text { OFF } \end{gathered}$ | OFF |  |
| E2 Busmode | OFF | OFF | OFF | OFF | OFF | OFF | $\begin{gathered} \text { OFF } \\ 4.03= \\ \text { ON } \end{gathered}$ | OFF | OFF |  |
| K1 Function | 1K | $\begin{gathered} 1 \mathrm{~K}(2.03 \\ =2 \mathrm{~K}) \end{gathered}$ | 1K | 1K | 1K | 1K | 1K | 1K | 1K |  |
| K1 Inverting | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| K2 Function | 2K | $\begin{gathered} 2 \mathrm{~K}(2.03 \\ =9 \mathrm{~K}) \end{gathered}$ | 2K | 2K | 2K | 2K | 2K | 2K | 2K |  |
| K2 Inverting | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| COM2 Function | MODBUS Slave |  |  |  |  |  |  |  |  |  |
| Limits |  |  |  |  |  |  |  |  |  |  |
| Level Function <br> 1. Level. Function ${ }^{2}$ | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| Level min. <br> 1. Level min. ${ }^{2}$ | ----- | ----- | ---- | ---- | ---- | ---- | ----- | ---- | ---- |  |
| Level max. <br> 1. Level max. ${ }^{2}$ |  | ----- | ----- | ----- | ----- | ---- | ----- | ----- | ---- |  |
| Level Delay <br> 1. Level Delay ${ }^{2}$ | ----- | ----- | -- | -- | -- | -- | ----- | -- | ---- |  |
| Lmt E1 Function | OFF | $\begin{gathered} \text { OFF } \\ 2.03= \\ 1 \mathrm{~L} \end{gathered}$ | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| Lmt E1 min | ---- | $\begin{aligned} & 2.03= \\ & 0.0^{\circ} \mathrm{C} \end{aligned}$ | ---- | ---- | ---- | ----- | ----- | ----- | ----- |  |


| Mode | $\begin{aligned} & 1.01 \\ & 1.02 \end{aligned}$ | 2.01 <br> 2.03 <br> 2.04 | 2.02 | 2.05 | $\begin{aligned} & 3.01 \\ & \hline 3.02 \end{aligned}$ | $\begin{aligned} & 3.03 \\ & \hline 3.04 \end{aligned}$ | 4.01 4.02 4.03 | $\begin{gathered} 5.01 \\ 5.02 \end{gathered}$ | 6.01 | User Setting |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Parameter | Factory setting |  |  |  |  |  |  |  |  |  |
| Lmt E1 max. | ----- | $\begin{array}{r} 2.03= \\ 40.0^{\circ} \mathrm{C} \end{array}$ | ---- | ---- | ------ | --- | ----- | --- | -- |  |
| Lmt E1 Hyst. | ----- | $\begin{aligned} & 2.03= \\ & 1.0 \mathrm{~K} \end{aligned}$ | ----- | ---- | ----- | ---- | ----- | ---- | ----- |  |
| Lmt E1 Del. | - | $2.03=$ $2 \mathrm{sec} .$ | ----- | -- | ----- | -- | ----- | ----- | -- |  |
| Lmt E2 Function | - | $2.04=$ OFF | -- | OFF | - | OFF | $\begin{gathered} 4.02,03 \\ =O F F \end{gathered}$ | $\begin{gathered} 5.02= \\ \text { OFF } \end{gathered}$ | -- |  |
| Lmt E2 min. | ----- | ---- | ----- | ---- | ----- | ---- | ----- | ---- | -- |  |
| Lmt E2 max. | ----- | ----- | ----- | ----- | ----- | -- | ----- | ----- | ----- |  |
| Lmt E2 Hyst. | ----- | ----- | ----- | ----- | ----- | ---- - | ----- | ----- | ---- - |  |
| Lmt E2 Del. | ----- | ----- | ----- | ---- | -- | -- | ----- | -- | --- |  |
| Offset Function <br> 1. Offset Function ${ }^{2}$ |  | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| Offset 1 <br> 1.Offset $1^{2}$ |  | ----- | ----- | ----- | ----- | ----- | ----- | ----- | ----- |  |
| Offset 2 <br> 1.Offset $2^{2}$ |  | - | -- | --- | -- | ----- | -- | ----- | ----- |  |
| Offset Hyst. <br> 1. Offset Hyst. ${ }^{2}$ |  | ----- | ---- | ----- | ----- | ----- | ----- | ----- | ----- |  |
| Offset Delay <br> 1. Offset Del. ${ }^{2}$ |  | ----- | ----- | ----- | ----- | ----- | ----- | ----- | ----- |  |
|  |  |  |  |  |  |  |  |  |  |  |
| Timer |  |  |  |  |  |  |  |  |  |  |
| Time | 14:24 | 14:24 | 14:24 | 14:24 | 14:24 | 14:24 | 14:24 | 14:24 | 14:24 |  |
| Date | 19.04.13 | 19.04.13 | 19.04.13 | 19.04.13 | 19.04.13 | 19.04.13 | 19.04.13 | 19.04.13 | 19.04.13 |  |
| Summertime Auto. | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| Timer Function | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| Mon |  |  |  |  |  |  |  |  |  |  |
| Mon ON1 | --:-- | --:- | --:-- | --:- | --:- | --: | --: | --:- | --:- |  |
| Mon OFF1 | --:- | --:- | --:- - | --:- - | --:- - | --:-- | --:- | --:- | --:-- |  |
| Mon ON2 | --:- | --:- | --:- | --:- | --:- | -- | --:- | :- | --: |  |
| Mon OFF2 | --:-- | --:-- | --:-- | --:-- | --:-- | --:-- | --:-- | --:-- | --:-- |  |
| RTC Adjust | 60 | 60 | 60 | 60 | 60 | 60 | 60 | 60 | 60 |  |
| Timer Inverting | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| Override Time | 120 min | 120 min | 120 min | 120 min | 120 min | 120 min | 120 min | 120 min | 120 min |  |
| Override Status | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
|  |  |  |  |  |  |  |  |  |  |  |
| Diagnostic |  |  |  |  |  |  |  |  |  |  |
| Runtime Controller | $\begin{gathered} 000056:- \\ 46: 13 \\ \hline \end{gathered}$ | $\begin{array}{\|c\|} \hline 000056:- \\ 46: 13 \\ \hline \end{array}$ | $\begin{gathered} 000056:- \\ 46: 13 \end{gathered}$ | $\begin{array}{\|c\|} \hline 000056:- \\ 46: 13 \\ \hline \end{array}$ | $\begin{gathered} 000056:- \\ 46: 13 \end{gathered}$ | $\begin{gathered} 000056:- \\ 46: 13 \end{gathered}$ | $\begin{gathered} 000056:- \\ 46: 13 \end{gathered}$ | $\begin{gathered} 000056:- \\ 46: 13 \end{gathered}$ | $\begin{gathered} 000056:- \\ 46: 13 \end{gathered}$ |  |
| Runtime Motor | $\begin{gathered} 000056:- \\ 46: 13 \end{gathered}$ | $\begin{array}{\|c\|} \hline 000056:- \\ 46: 13 \\ \hline \end{array}$ | $\begin{gathered} \text { 000056:- } \\ 46: 13 \end{gathered}$ | $\begin{gathered} 000056:- \\ 46: 13 \end{gathered}$ | $\begin{gathered} 000056:- \\ 46: 13 \end{gathered}$ | $\begin{gathered} 000056:- \\ 46: 13 \end{gathered}$ | $\begin{gathered} 000056:- \\ 46: 13 \end{gathered}$ | $\begin{gathered} 000056:- \\ 46: 13 \end{gathered}$ | $\begin{gathered} 000056:- \\ 46: 13 \end{gathered}$ |  |
| E1-KTY | $20.0{ }^{\circ} \mathrm{C}$ | $20.0{ }^{\circ} \mathrm{C}$ | $20.0{ }^{\circ} \mathrm{C}$ | $20.0{ }^{\circ} \mathrm{C}$ | $20.0{ }^{\circ} \mathrm{C}$ | $20.0{ }^{\circ} \mathrm{C}$ | $20.0{ }^{\circ} \mathrm{C}$ | $20.0{ }^{\circ} \mathrm{C}$ | $20.0{ }^{\circ} \mathrm{C}$ |  |
| E1-Current | 0.00 mA | 0.00 mA | 0.00 mA | 0.00 mA | 0.00 mA | 0.00 mA | 0.00 mA | 0.00 mA | 0.00 mA |  |
| E1 - Voltage | 0.00 V | 0.00 V | 0.00 V | 0.00 V | 0.00 V | 0.00 V | 0.00 V | 0.00 V | 0.00 V |  |
| E2 - KTY | $20.0{ }^{\circ} \mathrm{C}$ | $20.0{ }^{\circ} \mathrm{C}$ | $20.0{ }^{\circ} \mathrm{C}$ | $20.0{ }^{\circ} \mathrm{C}$ | $20.0{ }^{\circ} \mathrm{C}$ | $20.0{ }^{\circ} \mathrm{C}$ | $20.0{ }^{\circ} \mathrm{C}$ | $20.0{ }^{\circ} \mathrm{C}$ | $20.0{ }^{\circ} \mathrm{C}$ |  |
| E2-Current | 0.00 mA | 0.00 mA | 0.00 mA | 0.00 mA | 0.00 mA | 0.00 mA | 0.00 mA | 0.00 mA | 0.00 mA |  |


| Mode | $\begin{aligned} & 1.01 \\ & 1.02 \end{aligned}$ | $\begin{aligned} & 2.01 \\ & 2.03 \\ & 2.04 \end{aligned}$ | 2.02 | 2.05 | $\begin{gathered} 3.01 \\ \hline 3.02 \end{gathered}$ | $\begin{gathered} 3.03 \\ \hline 3.04 \end{gathered}$ | $\begin{aligned} & 4.01 \\ & 4.02 \\ & 4.03 \end{aligned}$ | $\begin{gathered} 5.01 \\ 5.02 \end{gathered}$ | 6.01 | User Setting |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Parameter | Factory setting |  |  |  |  |  |  |  |  |  |
| E2 - Voltage | 0.00 V | 0.00 V | 0.00 V | 0.00 V | 0.00 V | 0.00 V | 0.00 V | 0.00 V | 0.00 V |  |
| D1 | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| D2 | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| K1 | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| K2 | ON | ON | ON | ON | ON | ON | ON | ON | ON |  |
|  |  |  |  |  |  |  |  |  |  |  |
| MODBUS Slave |  |  |  |  |  |  |  |  |  |  |
| Bus Address | 247 | 247 | 247 | 247 | 247 | 247 | 247 | 247 | 247 |  |
| Addressing | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |  |
| UART Baudrate | 19200 | 19200 | 19200 | 19200 | 19200 | 19200 | 19200 | 19200 | 19200 |  |
| UART Mode | 8E1 | 8E1 | 8E1 | 8E1 | 8E1 | 8E1 | 8E1 | 8E1 | 8E1 |  |
|  |  |  |  |  |  |  |  |  |  |  |
| MODBUS Master |  |  |  |  |  |  |  |  |  |  |
| Autoaddressing |  |  |  |  |  |  |  |  |  |  |
| Bus Slavecount | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |  |

[^4]
### 10.2 Possible allocation of the IOs, PINs

## Units for analog inputs E1 and E2

The following units can be set for programmed sensors with free measuring range ( $0-10 \mathrm{~V}, 0-20 \mathrm{~mA}, 4$ 20 mA ).

| E1 Analog $\ln *$ |  |
| :--- | :--- |
| E2 Analog $\ln$ | ${ }^{\circ} \mathrm{C}, \mathrm{m}^{3} / \mathrm{h}, \mathrm{bar}, \%, \mathrm{~Pa}, \mathrm{~m} / \mathrm{s}, \mathrm{m}^{3} / \mathrm{s}, \mathrm{Ohm}, \mathrm{mbr},{ }^{\circ} \mathrm{F}, \mathrm{ft} / \mathrm{s}, \mathrm{cfm}, \mathrm{in} . \mathrm{wg}, \mathrm{psi}, \mathrm{ppm}$ |

* for Modes 5.01 and 5.02 display in $\mathrm{m}^{3} / h$, other units are not possible


## Analog outputs A1 and A2

| Function | Description |
| :---: | :---: |
| OFF | no function |
| Constant voltage 10 V | Constant voltage +10 V |
| (1A) | Factory setting for "A2" at operation with one control circuit. |
| 1st control signal (2A) | Controlled 0-10 V output for control circuit 1 (factory setting for "A1") |
| $\begin{gathered} \text { E1 } \\ (3 A) \end{gathered}$ | proportional input "E1" |
| $\begin{gathered} \text { E2 } \\ (4 A) \end{gathered}$ | proportional input "E2" |
| Group2 <br> (5A) | Group control ( Controller Setup - group 2) |
| 2.Cooling (6A) | Only for mode $\mathbf{2 . 0 3}$ temperature controller with additional functions. Controller output 2 with rising activation at Actual>Nominal = Cool. |
| 2.Heating <br> (7A) | Only for mode $\mathbf{2 . 0 3}$ temperature controller with additional functions. Controller output 2 with rising activation at Actual<Nominal = Heat. |
| 2. control signal (8A) | Controlled 0-10 V output vor control circuit 2. |
|  | Factory setting for "A2" at operation with second control circuit. |
|  | A second control circuit can be activated if required by programming the E2 function ( ${ }^{\circ}$ Base Setup E2 functions $8 \mathrm{E}-13 \mathrm{E}$ and second control circuit) |
| Speed (9A) | proportionally 1.Control signal |
| Group3 (11A) | Group control ( Controller Setup - group 3) |
| Group4 (12A) | Group control (\% Controller Setup - group 4) |
| Offset control sig. 1 (14A) | Offset control signal 1 <br> Setting offset Controller Setup |

## Digital inputs D1 and D2

| Function | Description |
| :---: | :---: |
| OFF | No function (factory setting) |
| Enable <br> (1D) | Enable (remote control) "ON" / "OFF" |
| External error (2D) | External fault alarm |
| Limit | "Limit" ON / OFF |
| (3D) | Influences control circuit 1 and control circuit 2 |
| $\begin{gathered} \text { E1 / E2 } \\ \text { (4D) } \\ \hline \end{gathered}$ | Switch over input "E1" / "E2" (for operation with one control circuit) |
| Reset <br> (10D) | Complete re-start of the device |
| Max. Speed (11D) | Setting Max. Speed "ON" / "OFF" <br> Influences the respectively set value "1. Max. Speed" and "2. Max. Speed" in operation with two control circuits. |
| Override Time (21D) | Overwrite timer function (in operation with timer) |
|  | For Mode Speed controller 1.01 |
| Setpoint1/2 (5D) | Switch over "Set Intern1" / "Set Intern2" "Setting External 1" must be at "OFF". |
| Setpoint int./ext. <br> (6D) | Switch over "Intern" / "Extern" |
|  | For modes as controller higher 2.01 |
| Setpoint1/2 <br> (5D) | Switch over "Setpoint 1" / "Setpoint 2"for control circuit1 |
| Setpoint int./ext. <br> (6D) | Switch over "Intern" / "Extern" <br> Possible only for operation with one control circuit! |
| Control/Manual (7D) | Switch over "automatic control" / "Speed manual" <br> Possible only for operation with one control circuit! |
| Heating/Cooling (8D) | Switch over control function (e.g. "heating" / "cooling") |
| 1.Setp+Pband1/2 <br> (15D) | for control circuit 1: Switch over Setpoint 1/2 and Pband 1/1 <br> When programming this function, "Setting" additionally lists the parameter: "1.Pband2 for control circuit 1." |
| Only active in operation with a second control circuit! |  |
| $\begin{gathered} \text { E1 / E2 } \\ \text { (4D) } \end{gathered}$ | The output for control circuit 2 is set additionally to "A2" to "A1" (regardless of the programmed function for A1). The first control circuit has no output for the duration of the switch over. <br> The switch over input "E1" / "E2" as in operation with one control circuit is no longer possible. |
| 2. Setpoint $1 / 2$ (9D) | for control circuit 2: Switch over "Setpoint 1" / Setpoint 2" |
| $\begin{aligned} & \text { 2.Setp+Pband1/2 } \\ & \text { (16D) } \end{aligned}$ | for control circuit 2: Switch over Setpoint 1/2 and Pband 1/2 <br> When programming this function, "Setting" additionally lists the parameter: " 2 Pband2 for control circuit 2." |

## Analogue input E2

| Function | Description Function E2 |
| :---: | :---: |
| OFF | No function (factory setting) |
|  |  |
| For mode speed controller 1.01 |  |
| 1E | Operation with a second setting signal (switch over "E1" <-> "E2" via floating contact) |
| 4E | Operation with a second setting signal and automatic control at the higher level ("E1" <> "E2") |
|  |  |
| For modes as controller higher 2.01 |  |
| Ext. Setpoint (1E) | 1E = External Setpoint e.g. via external signal (0-10 V) instead of "Setpoint 1" |
| Ext. Manual mode <br> (2E) | External manual operation via external signal ( $0-10 \mathrm{~V}$ ). Switch over between settings on the device and external manual operation via digital input. |
| Average E1 (3E) | Sensor average with E1 (\%mode 2.04) |
| Comparison E1 (4E) | Sensor comparison with E1 (\%mode 2.04) |
| Difference E1 (5E) | Sensor difference to E1 (L®mode 2.05) |
| Setpoint derating (6E) | Sensor for setpoint outdoor temperature controlled (5)mode 4.02, 5.02). |
| Measurement (7E) | Measurement value e.g. Measurement value e.g. for limit indication, display in Info menu "E2 Actual". |
| For activation of a second control circuit <br> (only possible in certain modes (operation with second control circuit) |  |
| Temperature (8E) | Temperature control, pre-settings and sensor selection correspond to mode 2.01 |
| Cold-Pressure (9E) | Pressure control condensers, pre-settings and sensor selection correspond to mode 3.01 |
| Cold-Temperature (10E) | Pressure control condensers with input for refrigerant, pre-settings, sensor selection and input for refrigerant corresponding to mode $\mathbf{3 . 0 2}$ |
| Air Pressure (11E) | Pressure control air conditioning, pre-settings and sensor selection correspond to mode 4.01 |
| Air flow (12E) | Volume control, pre-settings, sensor selection and K-factor for inlet ring correspond to mode 5.01 |
| Air speed (13E) | Air velocity control, pre-settings correspond to mode $\mathbf{6 . 0 1}$ |

## Digital outputs K1 and K2

| Function | Description |
| :---: | :---: |
| OFF | No function <br> Relays remain always de-energized |
| Operating indication (1K) | Operating indication (factory setting for "K1", non inverting). Operation without fault, reports enable "OFF" |
| Fault indication (2K) | Fault indication (factory setting for "K2", non inverting). <br> Pulled up in operation without fault, with release "OFF" not dropped out. <br> Drops out in case of line and device fault and external fault at the digital input. Depending on programming in event of sensor failure. |
| External error (3K) | External fault separate with message at digital input (factory setting if terminals bridged) |
| Limit modulation (4K) | Limit modulation Over or falling below limits for modulation |
| Limit E1 <br> (5K) | Limit "E1" <br> When over or falling below limits for input signal "E1" |
| Limit E2 (6K) | Limit "E2" <br> When over or falling below limits for input signal "E2" |
|  | For modes as controller higher 2.01 |
| Setpoint Offset (7K) | Setpoint Offset <br> Deviation between actual value and setpoint to high |
| Group2 <br> (8K) | Group control (Group 2) <br> Switching on fans depending on modulation |
| Group3 (12K) | Group control (Group 3) <br> Switching on fans depending on modulation |
| Group4 (14K) | Group control (Group 4) <br> Switching on fans depending on modulation |
| For modes as temperature controller with additional functions $\mathbf{2 . 0 3}$ |  |
| 2.Heating (9K) | Heating function <br> Switch ON point: temperature = Setpoint $+/-$ Offset <br> Switch OFF point: Temperature around hysteresis over switch ON point |
| 2.Cooling (10K) | Cooling function <br> Switch ON point: temperature $=$ Setpoint $+/$ Offset <br> Switch OFF point: Temperature around hysteresis below switch ON point |

## Limits GW E1 and GW E2

| Function | Description function GW E1, GW E2 |
| :---: | :--- |
| OFF | no function |
| Failure <br> (1L) | Indication with the centralized fault of a programmed relay (IO allocation Function 2K). <br> Warning symbol in display, "AL" code in events memory. <br> Message <br> (2L) <br> Filter error <br> (3L) Ls merely displayed in the events menu as message "msg". |
| Filter Message <br> (4L) | Like function 2L with fault message "Filter" |

## PINs

| PIN | Function |
| :---: | :---: |
| PIN 0010 | Opening service menu, if PIN-protection activated |
| PIN 1234 | Opening "setting". <br> if "set protection" = "ON" ( Controller Setup) |
| PIN 9090 | Restore user setting |
| PIN 9091 | Save user setting (corresponds function "Save user setup" = "ON" Controller Setup) |
| PIN 9095 | Restore factory setting = delivery status |

## 11 Diagnostics menu

| Main menu | The diagnostics menu supplies information about the momentary operating condition of the device. |
| :---: | :---: |
| IO Setup Limits Timer Autoaddressing Diagnostic |  |
| Diagnostic | Operating hours on the line <br> The time counter (h:m:s) runs as soon as line voltage is applied to the device and the device is switched on (without failure). <br> If events occur (e.g. sensor failure, MODBUS communication etc.), the operating time at this time is also saved ( $\xi^{-}$Protocol). |
| 000419:27:28 <br> Runtime Controller |  |
| Diagnostic | Operating hours with modulation <br> The time counting (h:m:s) runs only when a modulation of the controller is present |
| 000146:23:54 <br> Runtime Motor |  |
| Diagnostic | Signal height at analog input E1 (Analog In 1) |
| $\begin{aligned} & 20.0^{\circ} \mathrm{C} \\ & \text { E1-KTY } \end{aligned}$ |  |
| Diagnostic |  |
| $\begin{gathered} 9.0 \mathrm{~mA} \\ \text { E1-Current } \end{gathered}$ |  |
| Diagnostic |  |
| $\begin{gathered} 4.0 \mathrm{~V} \\ \text { E1 - Voltage } \end{gathered}$ |  |
| Diagnostic | Signal height at analog input E2 (Analog In 2) |
| $\begin{aligned} & 20.0^{\circ} \mathrm{C} \\ & \text { E2 }- \text { KTY } \end{aligned}$ |  |
| Diagnostic |  |
| 9.0 mA E2-Current |  |



## 12 Protocol

### 12.1 Display and query of events and malfunctions

| Main menu | Events during operation can lead to a malfunctioning of the device. |
| :--- | :--- |
| Start | The last 100 events are saved in the "Protocol" menu group. |
| Setting | Position 1 = latest event, display: Protocol $1 / 100$ |
| Protocol | Position 100 = last saved event, display: Protocol 100/100 |
| Base setup <br> Controller Setup | The saved events are retained even after resetting to factory setting (\% menu <br>  <br>  |

The device distinguishes between several event types which are identified by different symbols.

## Example

| Protocol 1/100 $\Delta$ | Attention symbol = message |
| :---: | :---: |
| Modulation Runtime Controller 000493:04:59 | The message is only listed in the protocol. There is no message alternately with the actual value display and no message via alarm relay. <br> Exception <br> In case of sensor failure there is always a message in the display (Controller Setup / Alarm Sensors) . |
| Protocol 2/100 | Bell symbol $=$ Alarm |
| Error MODBUS Com Runtime Controller 000193:04:59 | The alarm message is listed in the protocol and appears alternately with the actual value display. <br> Message by alarm relay depending on the type of failure and programming. |
| Protocol 2/100 X | Cross symbol = previous messages |
| Line Fault Runtime Controller 000493:04:59 | Cause of the message no longer exists. |

## Example: Previous line failure on a member

| Protocol 2/100 X |  |
| :--- | :--- |
| Line Fault <br> Runtime Controller <br> $000493: 04: 59$ | Previous line failure on a member connected via the MODBUS interface. <br> When the failure was cleared (line voltage available again), the device was on <br> the line for 493 hours, 4 minutes and 59 seconds. |
| [P] Details $\quad$ [ESC]Menu |  |

Press the P-key to show further details.

| Protocol 2/100 X |  |
| :---: | :---: |
| Line Fault | Date and time when the failure was cleared (time setting timer) |
| Date Time <br> 15.04.13 $10: 24$ |  |
| [P] Details [ESC]Menu |  |

Press the P-key to show further details.

| Protocol 2/100 X |  |
| :---: | :---: |
| Line Fault Place Fan 1 | Member on which the failure occurred. |
| [P] Details [ESC]Menu |  |

Press the P-key to show further details.

| Protocol 2/100 X |  |
| :---: | :---: |
| Line Fault <br> Modulation <br> $0 \%$ | Modulation of the member at the time of the message. |
| [P] Details $\quad[$ ESC]Menu |  |

Exit the menu with the Esc key combination $\boldsymbol{\nabla}+\boldsymbol{\Delta}$.

### 12.2 Messages and trouble shooting

A momentary pending alarm or error message is indicated by a blinking display and appears alternately with the actual value display.

| Display | Relais switches * |  | Cause |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Operation | Failure |  | Adjustment |
| no display | - | - | No line voltage Jumper J1 for USB interface plugged | Line voltage available? <br> Unit switch OFF and automatically ON when the voltage has been restored <br> Check line fuse <br> Check jumper J1, pull off or only plug to one PIN |
| OFF | X | - | No enable | Switch OFF by external contact (function 1D = enable programmed for Digital In) |
|  | - | - | fault in Eprom | Works with defaults. |
|  | - | X | fault EEP damaged | Works with defauls. |
|  | X | X | EEP data incorrectly | controller runs with the read settings. |
|  | - | X | Sensor 1 <br> Interruption / short circuit in the sensor leads or sensor values measured are outside measuring range | The device works with minimal or maximum modulation depending on whether there is a short-circuit or an interruption, and on the programmed mode of operation. <br> Check sensor |
|  | - | X | Sensor2 <br> Interruption / short circuit in the sensor leads or sensor values measured are outside measuring range | The device works with minimal or maximum modulation depending on whether there is a short-circuit or an interruption, and on the programmed mode of operation. |


| Display | Relais switches * <br> Opera- <br> tion | Failure | Cause | Reaction of Controller |
| :---: | :---: | :---: | :--- | :--- |


| Display | Relais switches * |  | Cause | Reaction of Controller |
| :---: | :---: | :---: | :---: | :---: |
|  | Operation | Failure |  | Adjustment |
| Motor fault <br> Fan: 3 | - | X | Example for motor fault at member with address 3 | The control module continues running unchanged. <br> Reset required on the member (4) operating instructions of the device concerned). |
| Line Fault <br> Fan: 6 | - | X | Example for line failure at member with address 6 | The control module continues running unchanged. <br> Check line supply of member. |
|  |  |  |  |  |

[^5]
## 13 Enclosure

### 13.1 Technical data

| Type | CXE/AVC MODBUS |
| :---: | :---: |
| Part-No. | 37256 (320053-42) |
| Line voltage | $1 \sim 230 \mathrm{~V}(-15 \%$ bis +10\%), 50/60 Hz |
| Weight | $0,9 \mathrm{~kg}$ |
| Input resistance for sensor or signal set for the rotational speed (E1, E2) | for 0-10 V input: $\mathrm{R}_{\mathrm{i}}>900 \mathrm{k} \Omega$ <br> for input 4-20 mA: $R_{i}=250 \Omega($ max. load $500 \Omega)$ |
| Voltage supply e.g. for sensors | +24 V (-30... $20 \%$ ), $\mathrm{I}_{\max } 70 \mathrm{~mA}$ |
| Analog output (A1, A2 0-10 V) | Load resistance (load) $>5 \mathrm{k} \Omega$ <br> Short-circuit proof, short-circuit current $=24 \mathrm{~mA}$ |
| Digital inputs (D1, D2) | $\mathrm{R}_{\mathrm{i}}$ approx. $7.8 \mathrm{k} \Omega$ Input current typ. 2.5 mA <br> Voltage range high level: 7.1... 19 V DC <br> Voltage range low level: $0 . \ldots .2 .7 \mathrm{~V}$ DC |
| Max. heat dissipation | approx. 10 W |
| Max. line fuse | 10 A |
| Max. permissible ambient temperature | $55^{\circ} \mathrm{C}$ |
| Min. permissible ambient temperature | $0^{\circ} \mathrm{C}$ (if mains voltage is not switched off up to $-20^{\circ} \mathrm{C}$ ) |
| Permissible rel. humidity | 85 \% no condensation |
| Electromagnetic compatibility for the standard voltage 230 / 400 V according to DIN IEC 60038 | Interference emission EN 61000-6-3 (domestic household applications) |
|  | Interference immunity EN 61000-6-2 (industrial applications) |
| Housing protection | IP54 |

Connectable conductors (information for all terminals)

| Push-In <br> Terminals |  | Cross section min. | Cross section max. |
| :---: | :---: | :---: | :---: |
|  | Terminal range, rated connection | $0.13 \mathrm{~mm}^{2}$ | $1.5 \mathrm{~mm}^{2}$ |
|  | Wire connection cross section AWG | AWG 24 | AWG 16 |
|  | Solid H05(07) V-U | $0.2 \mathrm{~mm}^{2}$ | $1.5 \mathrm{~mm}^{2}$ |
|  | Flexible H05(07) V-K | $0.2 \mathrm{~mm}^{2}$ | $1.5 \mathrm{~mm}^{2}$ |
|  | With wire end ferrule DIN 46 228/1 | $0.25 \mathrm{~mm}^{2}$ | $1.5 \mathrm{~mm}^{2}$ |
| * | Wire plastic collar ferrule DIN 46 228/4, | $0.25 \mathrm{~mm}^{2}$ | $0.75 \mathrm{~mm}^{2}$ |
|  | Rigid conductors and conductors with wire end ferrules can be plugged into the terminal without tools. Use the flexible conductor for connection and the push button for release. <br> Stripping length: 8 mm |  |  |
| The data refer to the connection possibilities of the terminals. The necessary conductor cross section must be dimensioned according to the respective prevailing conditions. |  |  |  |

### 13.2 Connection diagram



1 Line
2 Digital inputs for potential-free contacts
3 Outputs (I $\max =2 \mathrm{~mA})$ : A1 pre-programmed control output e.g. for controlling a speed controller. Fans with integrated controller and input 0 10 V can be activated directly. A2 pre-programmed for constant voltage +10 V
4 Inputs E1 + E2: 0... $10 \mathrm{~V}, 0 \ldots 20 \mathrm{~mA}, 4 \ldots 20 \mathrm{~mA}, \mathrm{TF}$. ( $K T Y$, Pt1000)
5 Contact rating max. AC 250 V 2 A (ohmic load)
6 Jumper J1 for USB interface (Bootloader)

## Attention!

Plug the jumper J1 to both PINs only for a software update via USB interface. The device will not switch on if this jumper is plugged to both PINs!
Do not replug the jumper under voltage, observe the safety instructions!


### 13.3 Dimensions [mm]



### 13.4 Index

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| M |  |  |  |
| mains is connected | 10 |  |  |
| mains voltage | 10 |  |  |
| MAL | 47 |  |  |
| MBG | 37 |  |  |
| member count | 89 |  |  |
| members | 87, 90 |  |  |
| Menu tables | 91 |  |  |
| Minimum speed cut off | 53 |  |  |
| MODBUS Master | 12, 87 |  |  |
| MODBUS Slave | 12, 86 |  |  |

### 13.5 Manufacturer reference $\boldsymbol{C} \boldsymbol{\epsilon}$

Our products are manufactured in accordance with the relevant international regulations. If you have any questions concerning the use of our products or plan special uses, please contact:

> Systemair Industrievägen 3 73930 Skinnskatteberg Telefon:+46 (0) 22244000 Telefax:+46 (0) 22244099 mailbox@systemair.se www.systemair.se


[^0]:    * Operation with a second control circuit possible

[^1]:    * Detailed description IO Setup / Digital Inputs "D1"/ "D2"

[^2]:    Attention!
    No disconnection (isolation) when turned off, in accordance with VBG4 §6)!

[^3]:    * Display --- as long as function $=$ OFF

[^4]:    1 For adjustment "Setting Sep" > 0 ( Base setup)
    2 For control circuit 1 in operation with a second control circuit (Base Setup / Function E2)
    3 For control circuit 2 in operation with a second control circuit (presetting depending on programmed function)
    4 In operation with control circuit 2 and programmed function 15 D for digital input ( $\$$
    5 In operation with control circuit 2 and programmed function 16 D for digital input ( $\$$

[^5]:    * Alternative display texts for error message via external contact Controller Setup / display text for external message.
    ** Alternative display texts for limit alarms limits function 3L

